

Week #1 : Chapter 21

• Composition of Matters

Matter \Rightarrow Atoms \Rightarrow Protons (Z : atomic number)
 (Molecules) \Rightarrow Electrons (Z : typically)
 \Rightarrow Neutron ($A-Z$; A : atomic weight)

Proton (positively charged): $1e = 1.602 \times 10^{-19}$ Coulomb (C)

Electron (negative charged): $2e = -e = -1.602 \times 10^{-19}$ C

Example: $A(\text{Cu}) = 63.6 \Rightarrow 6.02 \times 10^{23}$ Cu atoms weigh 63.6 gm
 $Z(\text{Cu}) = 29$

\Downarrow $\rho(\text{Cu}) = 8.9 \text{ gm/cm}^3$

$M_e = 9.1 \times 10^{-31} \text{ Kg}$

$r_e = 2.8 \times 10^{-15} \text{ m}$

$$\# \text{ Cu atoms/cm}^3 = \frac{6.02 \times 10^{23} \text{ atoms}}{(63.6 \text{ gm} / \rho(\text{Cu}))} \sim 9 \times 10^{22} / \text{cm}^3$$

Total electron charge in 1 cm^3 Cu

$$Q_e = Z \cdot e_i (\# \text{ Cu atoms/cm}^3)$$

$$= -1.6 \times 10^{-19} (e) \times 29 \times 9 \times 10^{22}$$

$$\sim 4 \times 10^5 \text{ C}^*$$

Big ideas of E&M: Where are we heading?

1. Electric charges (moving or not) produce electric force or force field that are felt by electric charges (moving or not)
2. Moving electric charges produce magnetic force or force field that are only felt by moving electric charges
3. Time-varying magnetic force field produces electric force field that are felt by electric charges (moving or not)
4. Time-varying electric force field produces magnetic force field that are felt by moving electric charges.
5. Mutually generating E & M fields propagate as a wave *

- Electrification: charge transfer ($10^{-8} \sim 10^{-7} \text{ C}$)

$$1 \text{ nC} = 10^{-9} \text{ C} ; \quad 1 \mu\text{C} = 10^{-6} \text{ C}$$

Conductors: at least one type of charge carriers is free to move about

Insulators: neither type of charge carriers is free to move about

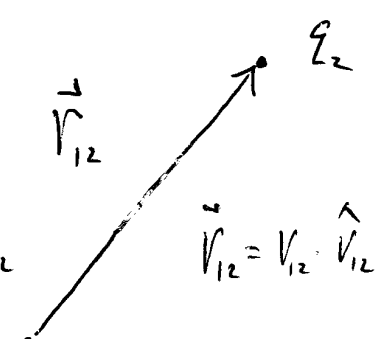
Electrification: charge transfer between insulators as a result of forced contact and "quick" separation.

Electrons are being exchanged

Like charges repel each other

Opposite charges attract each other

- Coulomb's law (between point charges):

$$\vec{F}_{1 \text{ on } 2} = k \frac{q_1 q_2}{r_{12}^2} \hat{r}_{12} = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r_{12}^2} \hat{r}_{12}$$


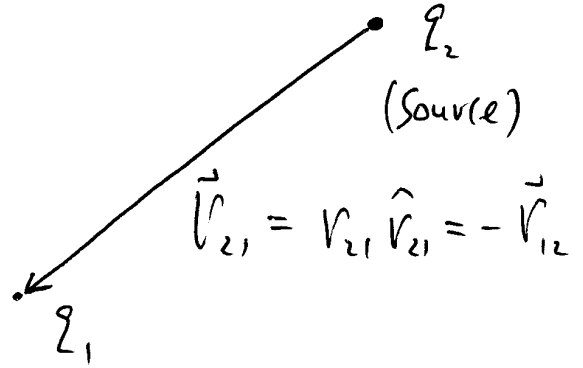
$$\epsilon_0 = 8.85 \times 10^{-12} \text{ C}^2 / \text{N} \cdot \text{m}^2, \quad k = 9.0 \times 10^9 \text{ N} \cdot \text{m}^2 / \text{C}^2 \quad q_1 \text{ (source)}$$

$$\vec{F}_{2 \text{ on } 1} = \frac{1}{4\pi\epsilon_0} \frac{q_2 \cdot q_1}{r_{21}^2} \hat{v}_{21} = -\vec{F}_{1 \text{ on } 2}$$

q_1, q_2 : algebraic product (with signs)

Like charges: $q_1, q_2 > 0$

Opposite charges: $q_1, q_2 < 0$



"Point charges": Distributions of q_1 & q_2 respectively $\ll r_{12}$

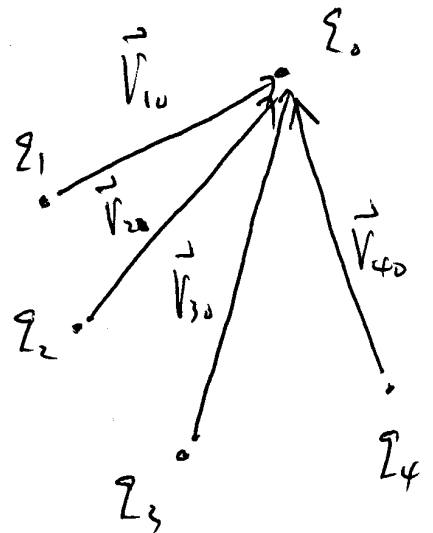
Example 22-2

$$\left(\frac{F_e}{F_g} \sim 1 \text{ if } \frac{q}{m} \approx 10^{-10} \text{ C/kg} \right)^*$$

Principle of Superposition: (vector sum)

$$\vec{F}_{\text{on } q_0} = \vec{F}_{1 \text{ on } 0} + \vec{F}_{2 \text{ on } 0} + \dots$$

$$= \frac{q_0}{4\pi\epsilon_0} \left\{ \frac{q_1}{r_{10}^2} \hat{v}_{10} + \frac{q_2}{r_{20}^2} \hat{v}_{20} + \dots \right\}$$



Example 22-4

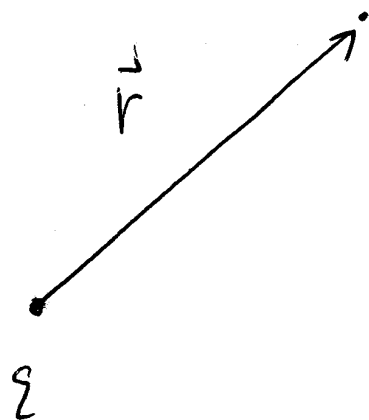
- Electric field (force field like gravitational field)

Like the mass of the Earth sets up a gravitational force field such that any massive object can feel the pull of this force field, an electric charge q sets up an electric field such that another point charge Q can feel the force exerted by q .

$$F_{q \text{ on } Q} = \left(\frac{1}{4\pi\epsilon_0} \right) \frac{q}{r^2} \cdot \hat{r} \cdot Q \equiv \vec{E}_q \cdot Q$$

$$\vec{E}_q(\vec{r}) \equiv \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r} \quad (\text{SI: N/C})$$

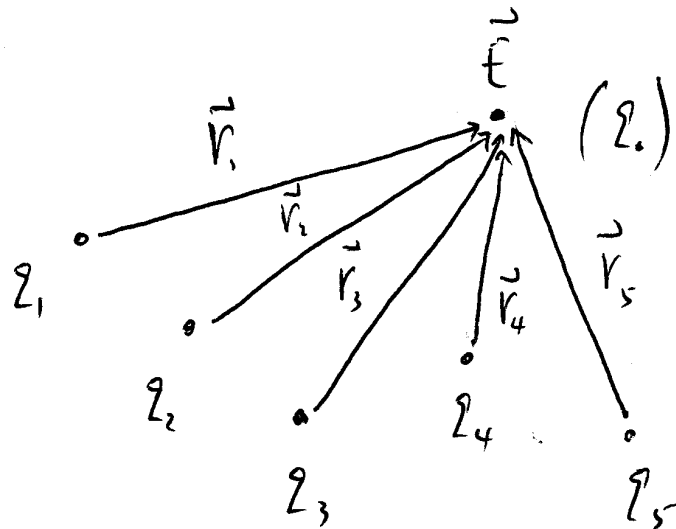
$\vec{E}_q(\vec{r})$: electric field produced by a point charge q at a field position \vec{r} from q .



Force by q on a point charge Q placed at \vec{r}

$$\vec{F} = Q \vec{E}_q(\vec{r}) = Q \vec{E} \quad (\text{for simplicity})$$

Electric field produced by a collection of point charges (principle of superposition)



$$\vec{E} = \frac{\vec{F}_{\text{on } q_0}}{q_0} = \vec{E}_{q_1}(\vec{r}_1) + \vec{E}_{q_2}(\vec{r}_2) + \dots \quad (\text{Vector sum})$$

$$\vec{F}_{\text{on } q_0} = q_0 \vec{E} \quad (\text{as long as } \vec{E} \text{ is known})$$

Determination of $\vec{F}_{\text{on } q_0}$ is a matter of determination of \vec{E} *

Example 22-9

• Electric fields from continuous charge distribution

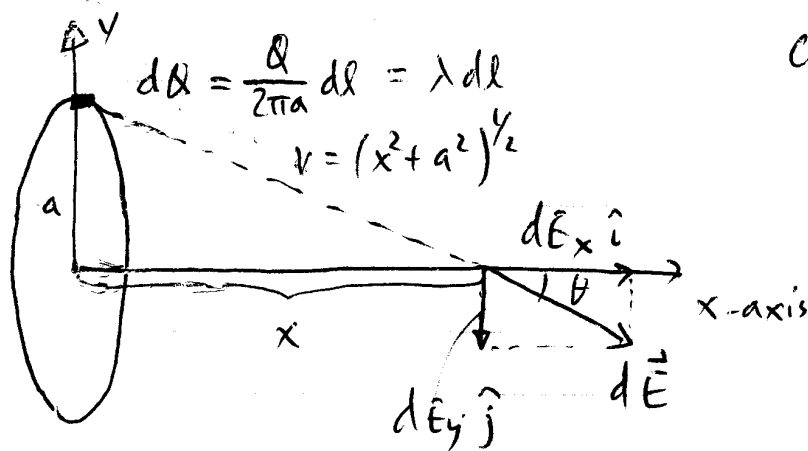
line charge density (C/m): $\lambda = \frac{\Delta Q}{\Delta L}$ *

Surface charge density (C/m²): $\sigma = \frac{\Delta Q}{\Delta A}$ *

Volume charge density (C/m³): $\rho = \frac{\Delta Q}{\Delta V}$ *

* $\Delta L, \Delta A, \Delta V$ small compared to source-field distance

Example 22-10



$$\cos \theta = \frac{x}{r} = \frac{x}{(x^2 + a^2)^{1/2}}$$

dE_y cancels the contribution from dl on the opposite side

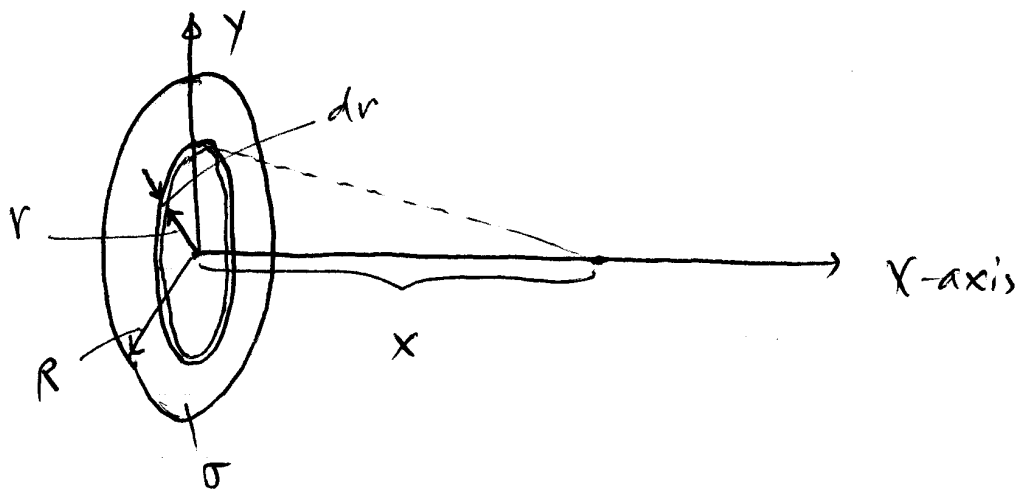
dE_x adds up: $E_x = \int dE_x = \frac{1}{4\pi\epsilon_0} \int_0^{2\pi a} \frac{(\lambda/2\pi a) dl}{x^2 + a^2} \cdot \frac{x}{(x^2 + a^2)^{1/2}}$

$x \gg a$: "point charge"
 $E_x = \frac{1}{4\pi\epsilon_0} \cdot \frac{Q}{x^2}$

$$= \frac{1}{4\pi\epsilon_0} \frac{Q \cdot x}{(x^2 + a^2)^{3/2}} \Rightarrow \vec{E} = \frac{1}{4\pi\epsilon_0} \frac{Qx}{(x^2 + a^2)^{3/2}} \hat{i}$$

Example 22-11 : read yourself

Example 22-12 :



From the thin ring of radius r and width dr

$$d\vec{E}_x = \frac{1}{4\pi\epsilon_0} \frac{x}{(x^2 + r^2)^{3/2}} \cdot (2\pi r dr \sigma)$$

$$\vec{E}_x = \int_0^R d\vec{E}_x = \frac{x\sigma}{4\pi\epsilon_0} \int_0^R \frac{2\pi r dr}{(x^2 + r^2)^{3/2}}$$

$$= \frac{\sigma}{2\epsilon_0} \left[1 - \frac{x}{\sqrt{x^2 + R^2}} \right]$$

$$\vec{E} = E_x \hat{i} = \frac{\sigma}{2\epsilon_0} \left[1 - \frac{x}{\sqrt{x^2 + R^2}} \right] \hat{i}$$

Limiting cases:

Point charge ($R \ll x$): $\vec{E} \approx \frac{\sigma}{2\epsilon_0} \cdot \frac{R^2}{2x^2} \hat{i} = \frac{1}{4\pi\epsilon_0} \frac{\pi R^2 \sigma}{x^2} \hat{i}$

Infinitely large plane of charge ($R \gg x$): $\vec{E} = \frac{\sigma}{2\epsilon_0} \hat{i}$

How large a plane does one need? $\vec{E} = (0.9) \frac{\sigma}{2\epsilon_0} \hat{i}$ for $\frac{x}{R} = 0.1$

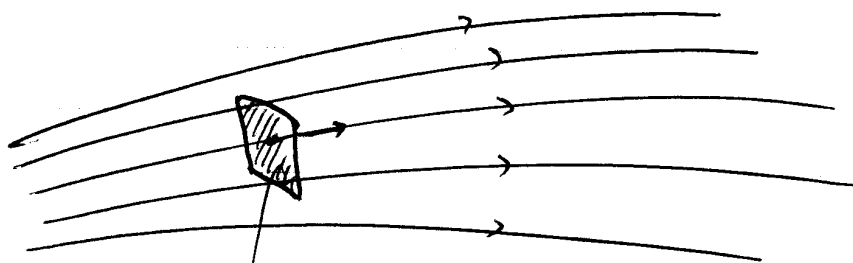
*

• Electric field lines:

A set of directed lines representing (depicting) electric field

Direction: along \hat{E} locally

Number density: equal to magnitude of $|\vec{E}|$.



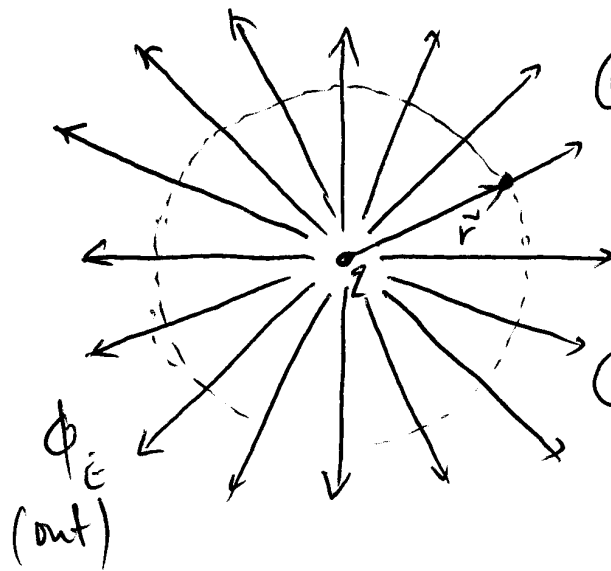
ΔA perpendicular to \vec{E}

$\Phi_E = N \cdot m^2/c$
Electric flux

$$|\vec{E}| = \frac{\text{Number of field lines passing through } \Delta A}{\Delta A} = \frac{\Delta \Phi_E}{\Delta A}$$

Electric field lines from a point charge

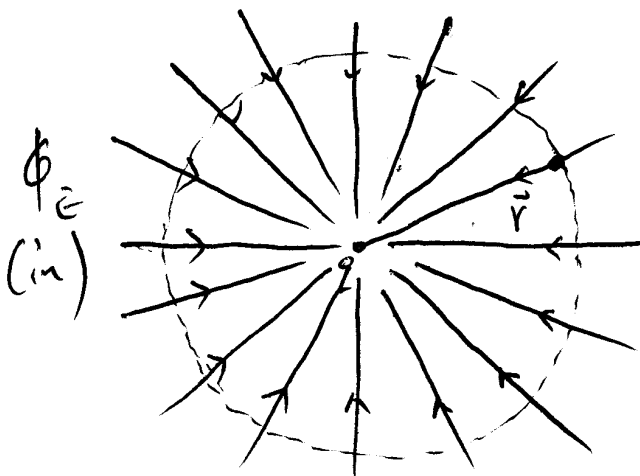
Draw $\Phi_E = |Q|/\epsilon_0$ lines symmetrically outward for a positive charge Q .



① Direction of the lines is along radial direction \hat{r} ;

② Density of the field lines $= \frac{\Phi_E}{4\pi r^2} = \frac{1}{4\pi\epsilon_0} \frac{Q}{r^2} = |\vec{E}|$

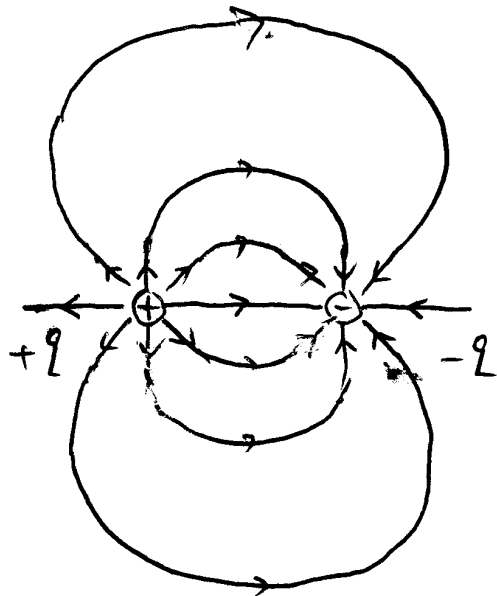
Draw $\Phi_E = |Q|/\epsilon_0$ lines symmetrically inward for a negative charge $Q < 0$.



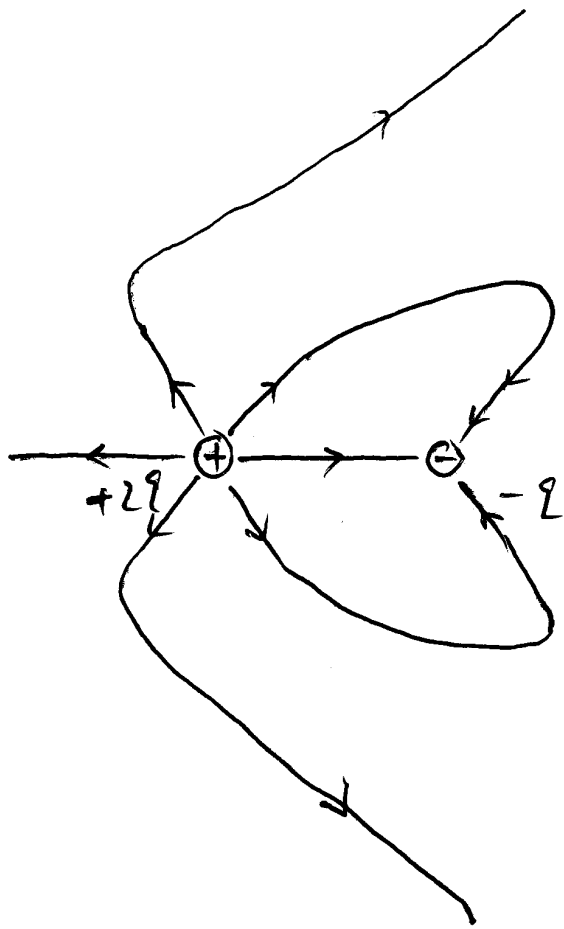
① Direction of the lines along the opposite of the radial direction: $-\hat{r}$

② Number density $\frac{\Phi_E}{4\pi\epsilon_0} = \frac{\Phi_E}{4\pi r^2} = \frac{1}{4\pi\epsilon_0} \frac{|Q|}{r^2} = |\vec{E}|$

Electric field lines from two point charges



To a far field point, there appears as a net "point" charge in this region. \Rightarrow Electric field lines must thin out to zero



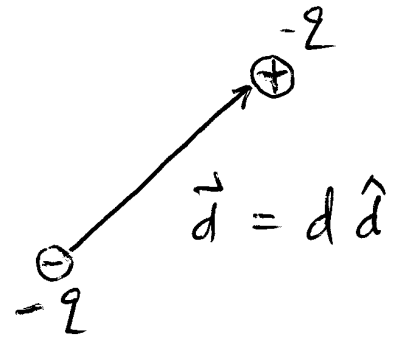
To a faraway field point, there appears a net positive point charge q in this region, and thus "three" net field lines "escape" eventually symmetrically "radiate" outward.

- Motion and behaviors of electric charges in electric fields

Example 22-7, read it yourself, similar to a point mass near the surface of Earth

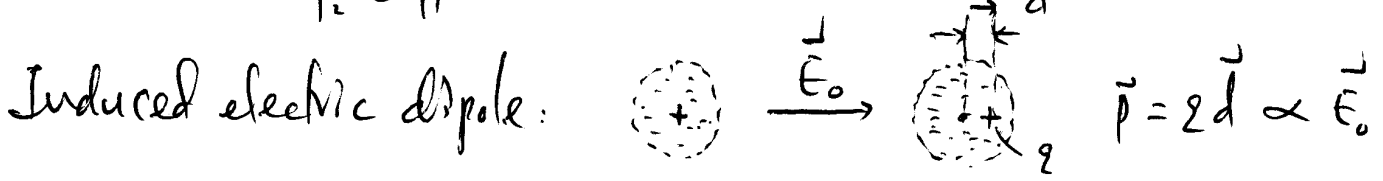
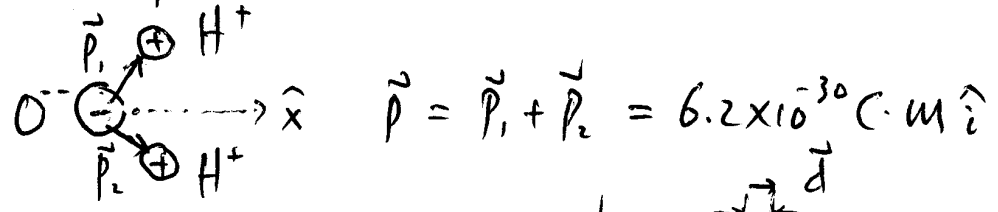
- Electric dipole in electric fields

An electric dipole is a pair of charges of equal magnitude but with opposite sign, with the positive charge separated from the negative charge by a position vector \vec{d}

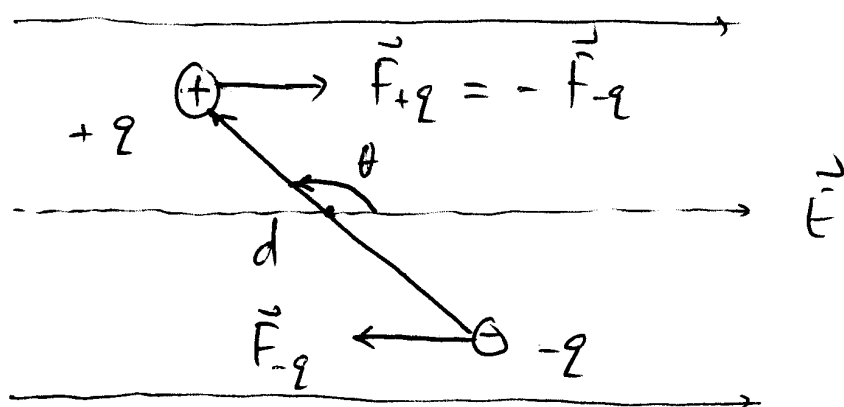


Dipole moment $\vec{p} \equiv q \vec{d} = q d \hat{d}$

Permanent dipole: water molecules



Electric dipole (permanent or induced) in a uniform \vec{E}



* Field line demonstration
 \vec{p} prefers to align along \vec{E}

① Net force on the dipole is zero. $\vec{F}_{+q} = -\vec{F}_{-q} = q\vec{E}$

② But \vec{F}_{+q} and \vec{F}_{-q} are along the two lines that are apart by $d \sin \theta$, thus exerting a torque

$$|\vec{\tau}| = qEd \sin \theta = (qd \sin \theta) \cdot E = |\vec{p} \times \vec{E}|$$

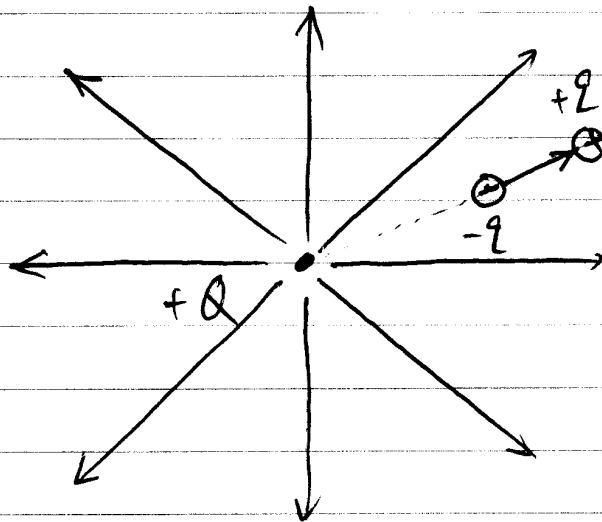
$$\vec{\tau} = \vec{p} \times \vec{E} \quad (\text{causing clockwise rotation in this case})$$

③ Potential energy $U(\theta)$ of \vec{p} in \vec{E} :
 Potential energy U is gained by rotating \vec{p} counter clockwise against electric torque $\vec{\tau}$:

$$U(\theta) - U(0) = \int_0^\theta qE \sin \theta \cdot d\theta = -qE \cos \theta + qE$$

$$\therefore U(\theta) = -qE \cos \theta = -\vec{p} \cdot \vec{E}$$

- Electric dipole \vec{p} in a non-uniform
(Attraction of water by charged rod/plastic)

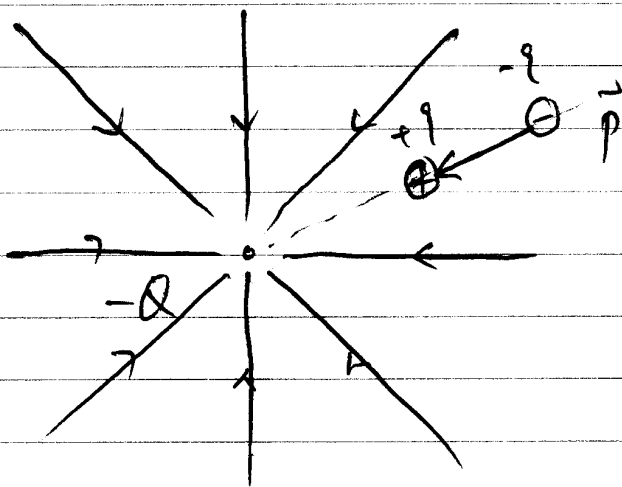


\vec{p} first aligns along the direction of the mean electric field
 $\langle \vec{E} \rangle = \frac{1}{2} (\vec{E}_{-q} + \vec{E}_{+q})$

Since $-q$ is closer to $+Q$ than $+q$, $|\vec{E}_{-q}| > |\vec{E}_{+q}|$.

Thus, \vec{p} is attracted to Q (positive)

This is true for permanent/induced dipole moment.



Since $+q$ is closer to $-Q$ than $-q$,

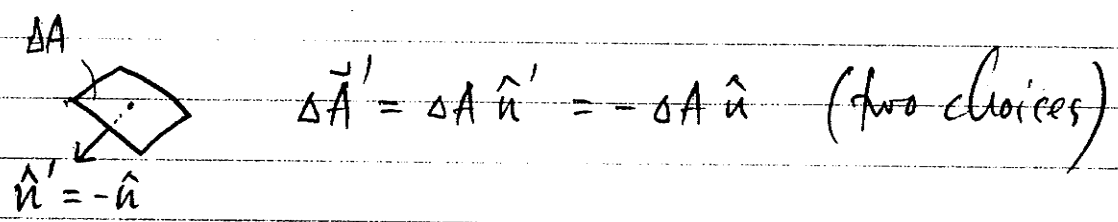
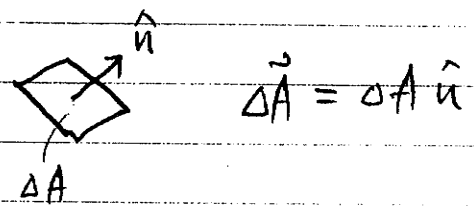
$$|\vec{E}_{+q}| > |\vec{E}_{-q}|$$

Thus \vec{p} is attracted to $-Q$, source of the non-uniform \vec{E} field.

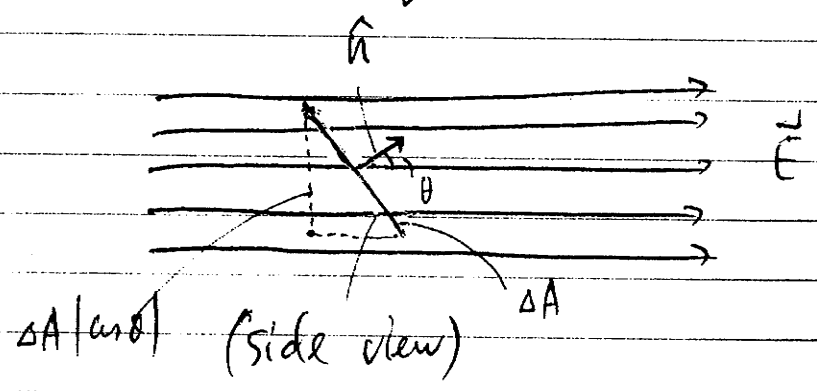
Week #2, Chapter 22 (Gauss' law)

- Electric flux: electric field lines through a directed area

Directed area $\Delta \vec{A}$: area of a flat surface ΔA multiplied (Vector area) by a chosen unit vector \hat{u} along its normal



Electric flux through a directed area $\Delta \vec{A}$:



$$|\Delta \phi_E| = |\vec{E}| \cdot \Delta A \cdot |\cos \theta|$$

Define:

$$\Delta \phi_E = \vec{E} \cdot \Delta \vec{A}$$

$\Delta\phi_E > 0$: $\vec{E} \cdot \hat{n} > 0$, electric field lines leaving the directed area $\Delta\vec{A}$

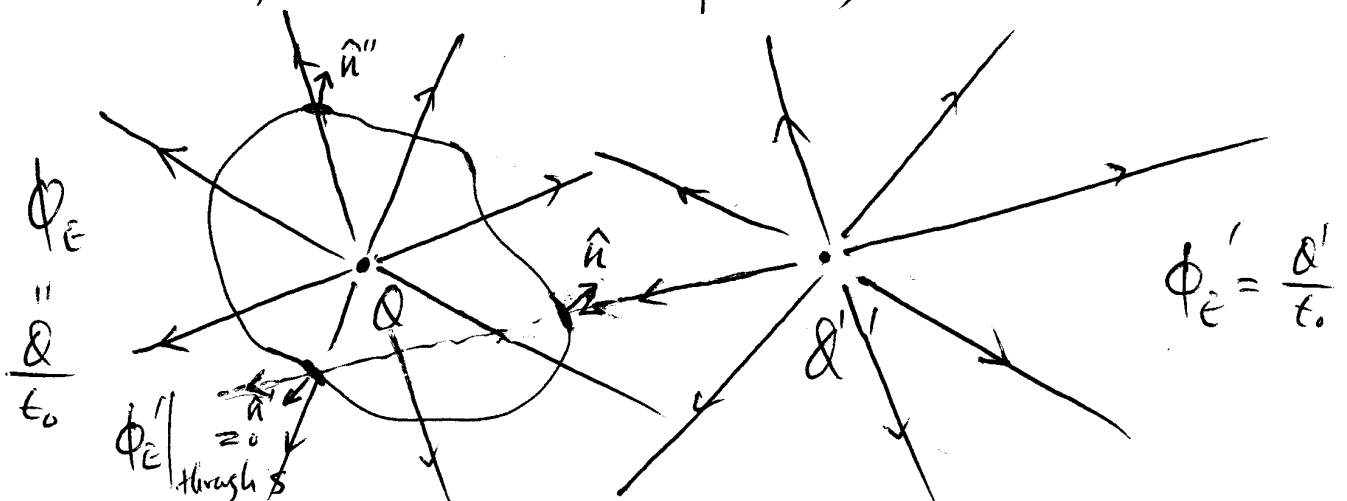
$\Delta\phi_E < 0$: $\vec{E} \cdot \hat{n} < 0$, electric field lines entering the directed area $\Delta\vec{A}$

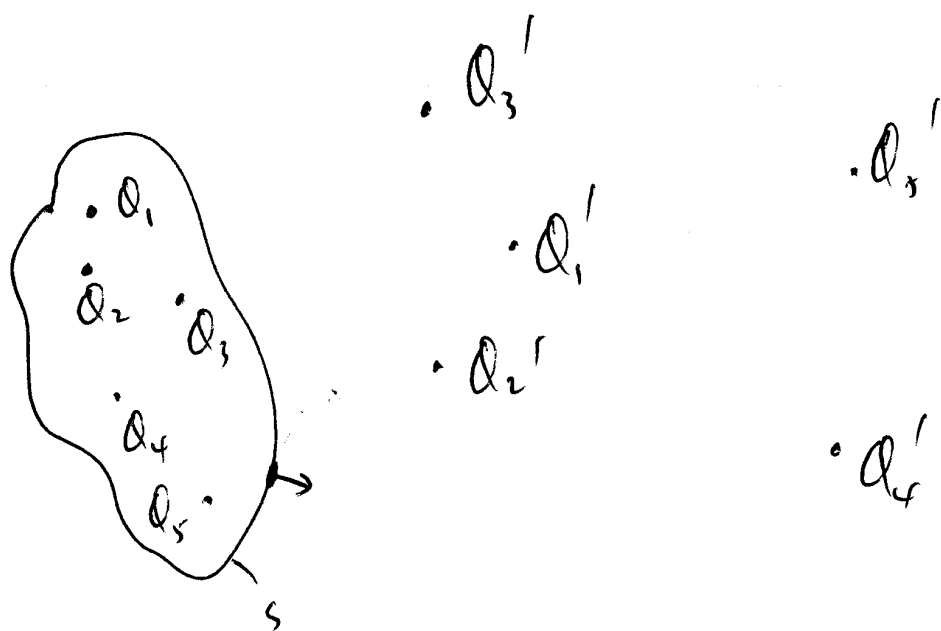
• Gauss' law:

Electric field lines leaving a closed surface S equal the total charge inside S divided by ϵ_0

$$\oiint_S \vec{E} \cdot d\vec{A} = \frac{Q_{\text{inside}}}{\epsilon_0}$$

The unit vector of each directed area element $d\vec{A}$ is always chosen to be pointing outward.





$$\oint_S \vec{E} \cdot d\vec{A} = \oint_S (\vec{E}_{Q_1} + \vec{E}_{Q_2} + \dots + \vec{E}_{Q_5} + \vec{E}_{Q_1'} + \vec{E}_{Q_2'} + \dots + \vec{E}_{Q_5'}) \cdot d\vec{A}$$

$$= \oint_S \vec{E}_{Q_1} \cdot d\vec{A} + \oint_S \vec{E}_{Q_2} \cdot d\vec{A} + \dots + \oint_S \vec{E}_{Q_5} \cdot d\vec{A}$$

$$+ \oint_S \vec{E}_{Q_1'} \cdot d\vec{A} + \oint_S \vec{E}_{Q_2'} \cdot d\vec{A} + \dots + \oint_S \vec{E}_{Q_5'} \cdot d\vec{A}$$

$$= \frac{Q_1}{\epsilon_0} + \frac{Q_2}{\epsilon_0} + \dots + \frac{Q_5}{\epsilon_0}$$

$$= \frac{(Q_1 + Q_2 + \dots + Q_5)}{\epsilon_0}$$

$$= \frac{Q_{\text{inside}}}{\epsilon_0}$$

$$\oint_S \vec{E} \cdot d\vec{A} = \frac{Q_{\text{inside}}}{\epsilon_0} \quad (\text{Gauss' law})$$

It doesn't mean at all that \vec{E} is only produced by Q_{inside} !!

- Application of Gauss' law (What's the use of it??)
 - Finding \vec{E} under symmetric or limiting situations

Example 23-5

Example 23-6, read yourself, and compare with example 22-11 in the limit that the line is long.

Example 23-7, may read yourself, compare with Example 22¹²

- Charges on conductor surfaces and electric fields at conductor surfaces

Under static conditions (nothing moves no more), the electric field inside a conductor is always zero (otherwise freely movable electric charge carriers would move under the electric field until the latter is perfectly cancelled out): $\vec{E}_{\text{inside}} = 0$

No net (unbalanced) electric charges can remain inside a conductor.

(By enclosing any volume inside a conductor, since

$$\oint_S \vec{E} \cdot d\vec{A} = \oint_S \vec{E}_{\text{inside}} \cdot d\vec{A} = 0 = \frac{Q_{\text{inside } S}}{\epsilon_0}$$

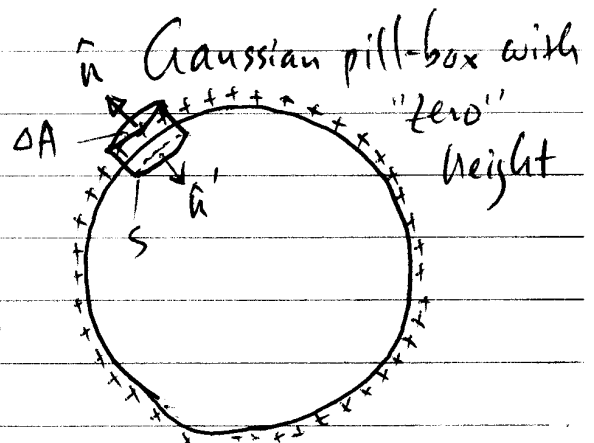
net charges inside any volume in a conductor is zero.)

Net or unbalanced electric charges can only reside on the surface of a conductor.

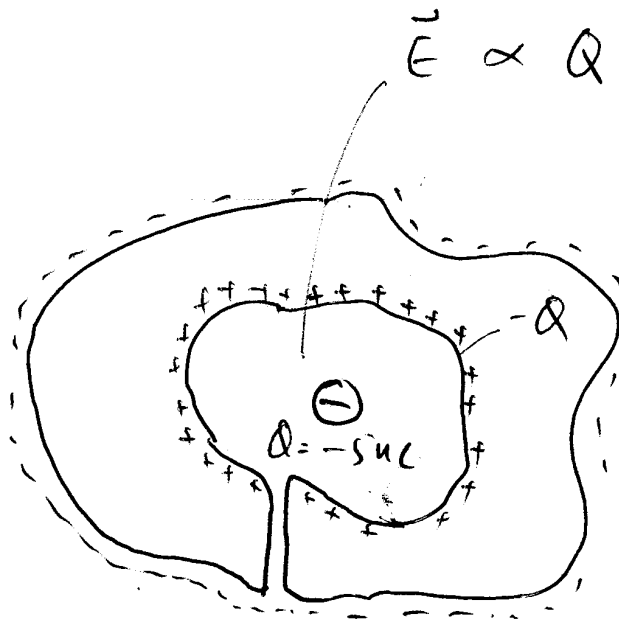
Electric field outside a conductor surface:

$$\oint_S \vec{E} \cdot d\vec{A} = \vec{E}_{\text{outside}} \cdot \hat{n} \cdot \Delta A = \sigma \cdot \Delta A / \epsilon_0$$

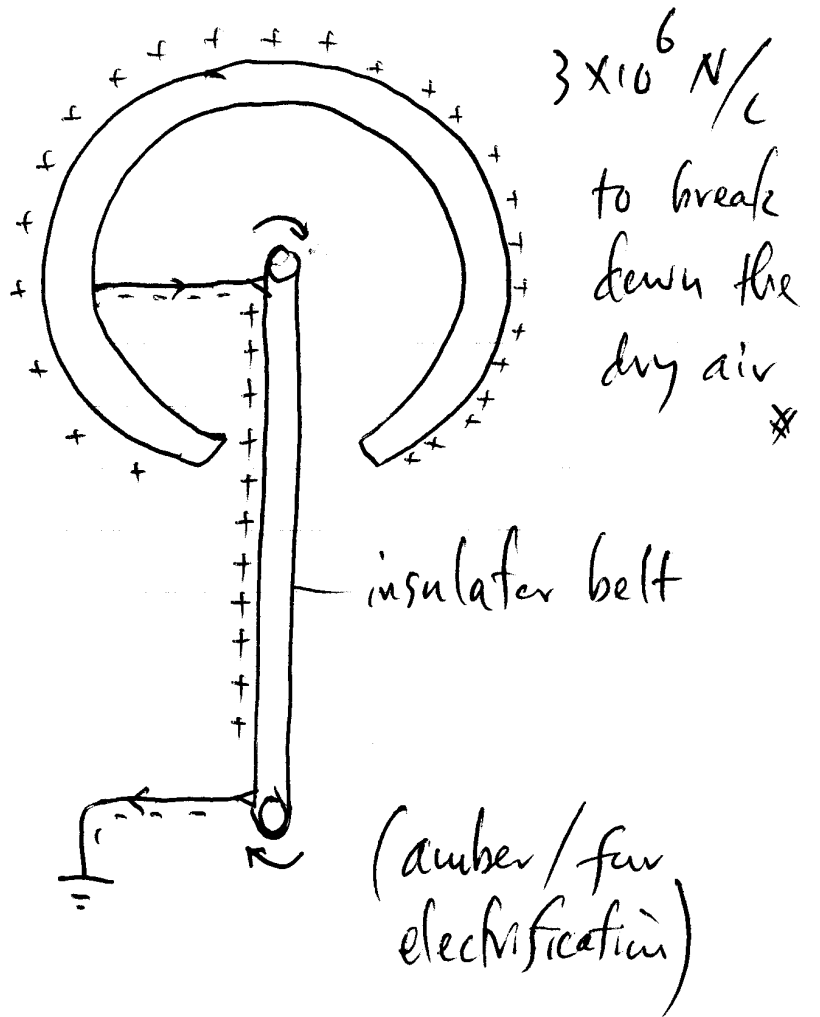
$$\vec{E}_{\text{outside}} \cdot \hat{n} = \sigma / \epsilon_0 \quad *$$



Example 23-10



Van der Graaf



Week #3 : Chapter 23

- Electric potential energy U of charges in an electric field: "potential energy originated from electrostatic forces"

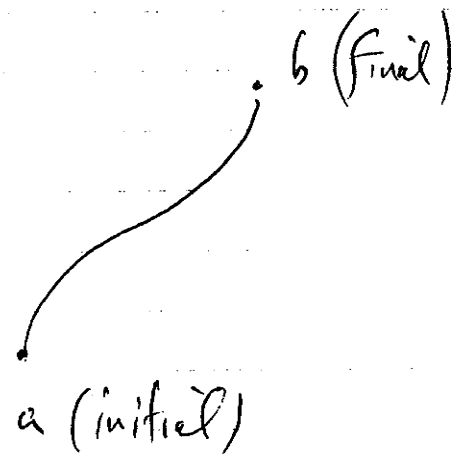
Like a massive object in a gravitational field (a coke can at the surface of the earth), a charged object in an electric field experiences a force

$$\vec{F}_E = q\vec{E} \quad (\text{electro-static})$$

Alone, \vec{F}_E accelerates the charged (q) object and does work when q is moved from a to b , gaining kinetic energy K

Work done by \vec{F}_E on q
= Gain of kinetic energy
of a q -charged object,
 $K_b - K_a$

$W(\vec{F}_E \text{ on } q) = K_b - K_a$



(SI unit: Joules)

\vec{F}_E alone

\vec{F}_E is "conservative" (like gravitational forces).

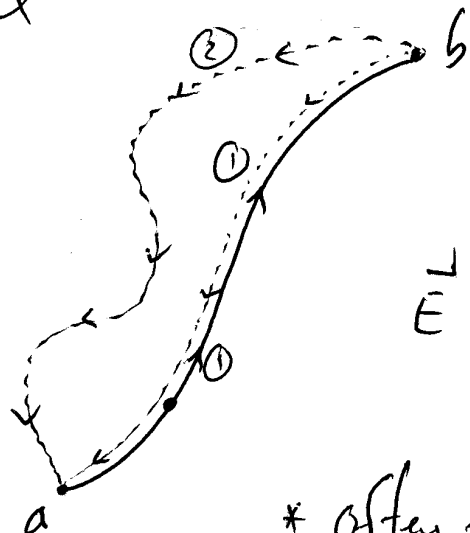
- 1) Work done against \vec{F}_E as a charged object is moved from b to a , by an external force or at the expense of the kinetic energy of the object (K_b) is not "wasted"
- 2) The equal amount of work is returned as \vec{F}_E works to move the object from a back to b in form of the kinetic energy of the object or the work done to an external system (e.g., heating up a light bulb, moving a mechanical motor).
- 3) The work done by \vec{F}_E , or against \vec{F}_E , is independent of the route that the charged object takes to get from an initial position (e.g., a) to a final position (e.g., b).

A charged object q in \vec{E} has a potential energy U_q^*

$$U_q(a) - U_q(b) = \text{Work done}$$

$$\text{by } \vec{F}_E = q\vec{E}$$

$$= \int_a^b \vec{F}_E \cdot d\vec{l} = q \int_a^b \vec{E} \cdot d\vec{l}$$



* often that is all we really care !!!

Equivalently, the electric potential energy change is equal to the work done against \vec{F}_E when q is moved from an initial position a to a final position b :

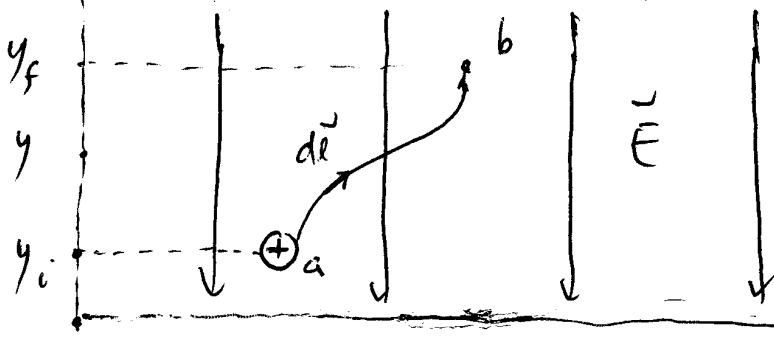
$$U_q(b) - U_q(a) = \int_a^b \vec{F}_{\text{ext}} \cdot d\vec{\ell} = \int_a^b (-\vec{F}_E) \cdot d\vec{\ell}$$

$$= -q \int_a^b \vec{E} \cdot d\vec{\ell}$$

$$\therefore U_q(b) - U_q(a) = -q \int_a^b \vec{E} \cdot d\vec{\ell} = q \cdot \left(- \int_a^b \vec{E} \cdot d\vec{\ell} \right)$$

Example: Potential energy a charged particle in a uniform electric field \vec{E}

y-axis



$$d\vec{\ell} = dx\hat{i} + dy\hat{j}$$

$$\vec{E} = -E\hat{j}$$

$$U_q(b) - U_q(a) = q \int_a^b (-\vec{E}) \cdot d\vec{\ell}$$

$$= qE(y_f - y_i)$$

$$U_q(y) = qE \cdot y$$

Unlike massive objects ($m > 0$), in a gravitational field, in a same electric field \vec{E} , whether $U_2(b)$ is higher or lower than $U_2(a)$ also depends on whether $q > 0$ or $q < 0$.

- ① $q > 0$: U_2 increases in the direction opposite to \vec{E}
- ② $q < 0$: U_2 decreases in the direction opposite to \vec{E}
(unlike gravity !!)

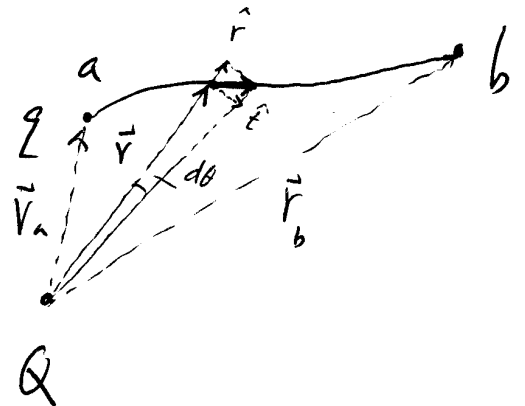
Example: Electric potential energy of a point charge q in the electric field produced by another point charge Q

$$U_2(b) - U_2(a) = q \int_a^b (-\vec{E}) \cdot d\vec{\ell}$$

$$= -q \cdot \int_a^b \frac{k \cdot Q}{r^2} \hat{r} \cdot (\hat{r} dr + r d\theta \hat{e}_\theta)$$

$$= -kqQ \cdot \int_a^b \frac{dr}{r^2} = kqQ \int_{r_a}^{r_b} d\left(\frac{1}{r}\right)$$

$$= \frac{kqQ}{r_b} - \frac{kqQ}{r_a} \quad (\text{independent of how } q \text{ reaches } b \text{ from } a)$$



$$d\vec{\ell} = dr \hat{r} + (r d\theta) \cdot \hat{e}_\theta$$

$$U_q(r) = \frac{kq \cdot Q}{r} + \text{constant}$$

Taking $U_q(\infty) = 0$, constant is set to zero

$$U_q(r) - U_q(\infty) = \frac{kqQ}{r}$$

Principle of superposition:

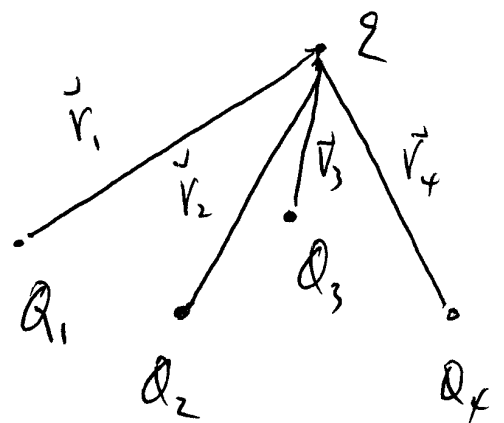
Electric potential energy of a point charge q in the electric field produced by a set of point charges (Q_1, Q_2, \dots)

$$U_q(r) - U_q(\infty) = \sum_{n=1} \frac{kqQ_n}{r_n}$$

For continuous charge distributions,

$$U_q - U_q(\infty) = \int \frac{kq dQ}{r}$$

(Volume, Surface, Line)



- Electric potential energy of a collection of point charges in a given configuration (arrangement)

Potential energy of these charges in a given configuration is the work done AGAINST the electrostatic forces between these charges, when they are brought from being infinitely apart to the configuration.

Two charges (q_1, q_2 , separated by r_{12})

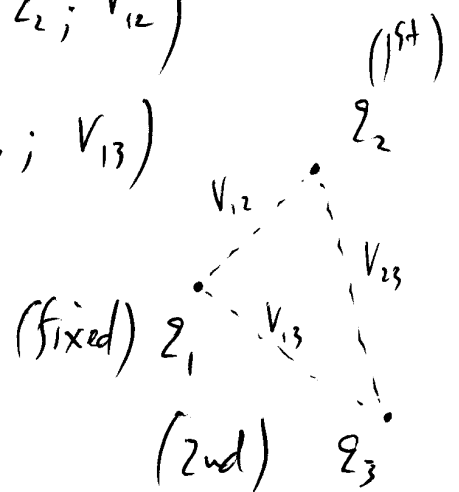
$$U(q_1, q_2; r_{12}) = \frac{kq_1 \cdot q_2}{r_{12}}$$

Three charges (q_1, q_2, q_3 ; r_{12}, r_{23}, r_{32})

$$U(q_1, q_2, q_3; r_{12}, r_{21}, r_{23}) = U(q_1, q_2; r_{12})$$

$$+ U(q_2, q_3; r_{23}) + U(q_1, q_3; r_{13})$$

$$= \frac{kq_1 q_2}{r_{12}} + \frac{kq_2 q_3}{r_{23}} + \frac{kq_1 q_3}{r_{13}}$$



- Electric potential V in an electric field \vec{E}

Electric potential V is a scalar function of spatial coordinate. The difference of the electric potential between two points in space, a and b , equals to the work done on a unit positive charge against the electrostatic force produced by \vec{E} on the charge as it is moved from a to b :

$$V_b - V_a = - \int_a^b \vec{E} \cdot d\vec{l}$$

(SI units: volt or V)

$$1V = 1J/C = 1N \cdot m/C$$

- Potential energy difference for a charge q in the electric field is

$$U_q(b) - U_q(a) = q(V_b - V_a) \Rightarrow V_b - V_a = \frac{U_q(b) - U_q(a)}{q}$$

- Electric field \vec{E} and the gradient of $V(\vec{r})$: $\vec{E} = -\nabla V$

$$V(\vec{r} + d\vec{r}) - V(\vec{r}) = \underbrace{\left(\frac{\partial V}{\partial x} \right)_{\vec{r}} dx + \left(\frac{\partial V}{\partial y} \right)_{\vec{r}} dy + \left(\frac{\partial V}{\partial z} \right)_{\vec{r}} dz}_{(\nabla V)_{\vec{r}} \cdot d\vec{r}} = -\vec{E} \cdot d\vec{r}$$

- Electric potential V in the electric field of a point charge Q

$$V(\vec{r}) - V(\infty) = \frac{1}{4\pi\epsilon_0} \cdot \frac{Q}{r}$$

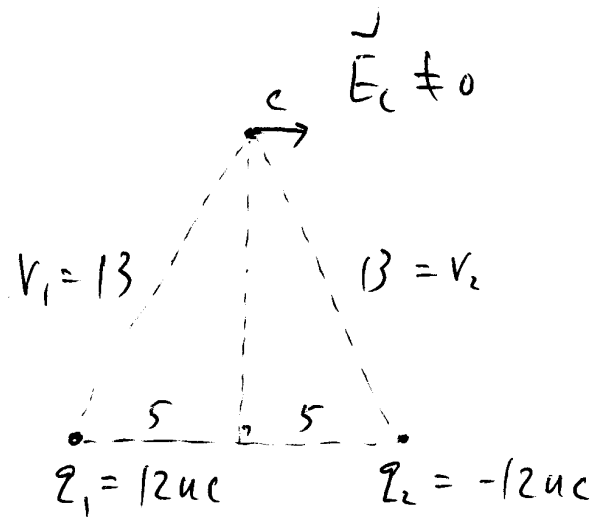
Assuming $V(\infty) = 0$ (reference)

$$V(\vec{r}) = \frac{kQ}{r}$$



Example 24-4:

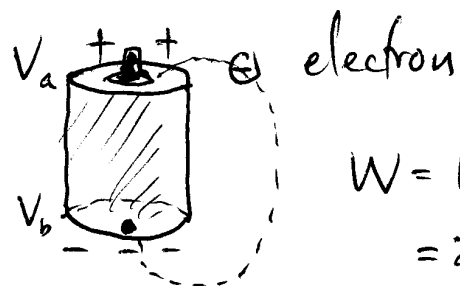
$$\begin{aligned} V_c &= \frac{kq_1}{r_1} + \frac{kq_2}{r_2} \\ &= \frac{k}{r_1} (q_1 + q_2) = 0 \end{aligned}$$



Example: Moving an electron

$$\begin{aligned} \text{Work done} &= q_e (V_b - V_a) \\ &= (-e) (-1.5 \text{ V}) \end{aligned}$$

1.5 V
battery

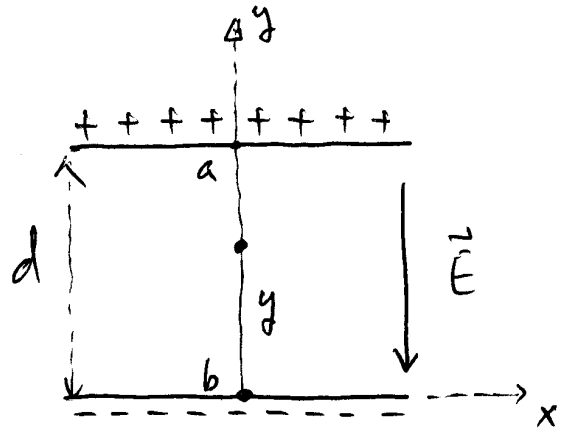


$$\begin{aligned} W &= 1.5 \text{ eV} \\ &= 2.4 \times 10^{-19} \text{ J} \end{aligned}$$

*

Example 24-9

Against \vec{E} , one does positive work when moving a positive charge along positive y -axis:



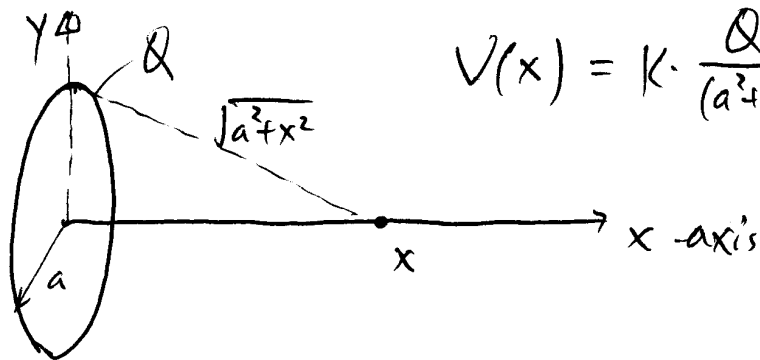
$$V(y) - V(0) = V(y) - V_b = Ey$$

Potential difference between the two plates

$$V_a - V_b = E \cdot d \quad E = \frac{V_a - V_b}{d} \quad (\text{V/m})$$

Electric potential increases in directions against \vec{E} *

Example 24-11



$$V(x) = k \cdot \frac{Q}{(a^2 + x^2)^{1/2}}$$

$$E_x = -\frac{\partial V}{\partial x} = k \frac{Qx}{(a^2 + x^2)^{3/2}}$$

- Line integration of an electric field along a close loop is zero.

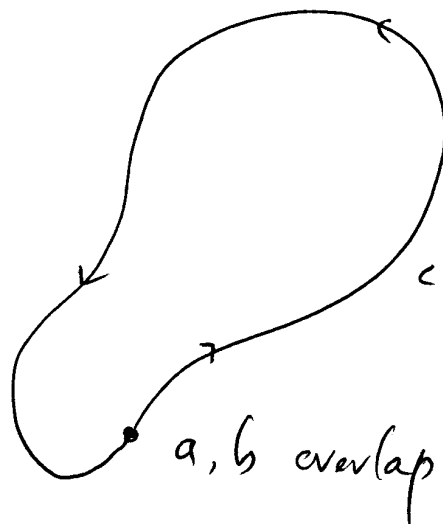
$$\oint_C \vec{E} \cdot d\vec{l} = 0 \quad (\text{Second Maxwell's equation})$$

Since the net work done on a charge q over a close loop by the electro-static force $\vec{F}_e = q\vec{E}$ is zero.

$$(V_b - V_a) \Big|_{a,b \text{ overlap}}$$

$$= - \oint_C \vec{E} \cdot d\vec{l}$$

$$= 0 \quad (\text{We haven't gone anywhere!})$$



- Equi-potential surfaces:

All points in space such that $V(\vec{r}) = \text{constant}$.

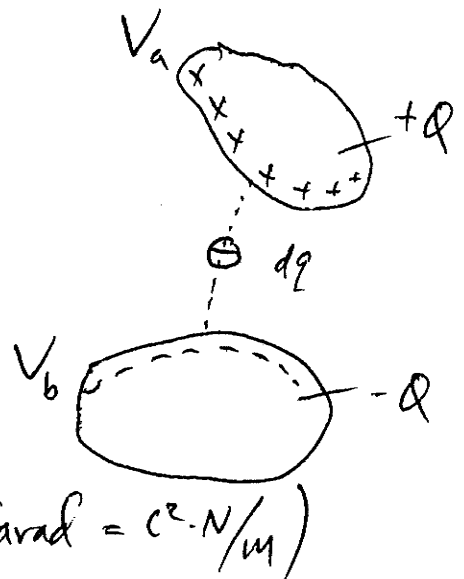
Week #4, Chapter 24

- Moving electric charges against electric forces allows storage of energy (electric potential energy)
- To retrieve stored electric potential energy with ease requires the movable electric charges to be mobile, and thus the "stored" charges must be on conductors.
- Capacitor and capacitance C of a capacitor

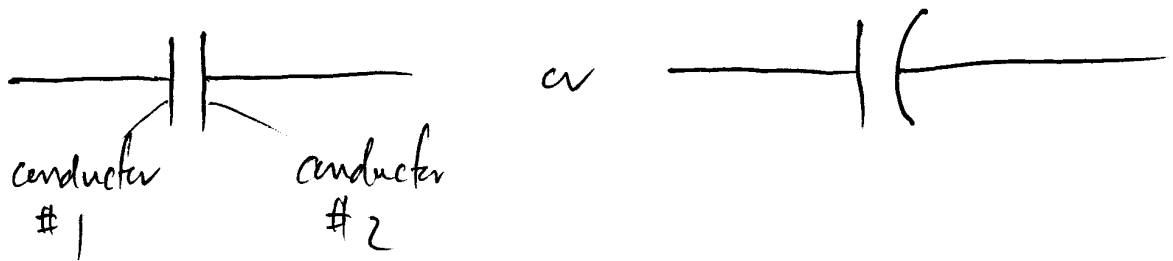
A pair of (initially neutral) conductors forms a capacitor that can store electric potential energy.

By moving a net charge Q from one conductor to another, a potential difference is established between the two conductors, $V_a - V_b$, and it is proportional to Q with the proportionality constant C only depending upon the geometry of the two conductors

$$Q = C(V_a - V_b) \quad (\text{SI unit: Farad} = \text{C}^2 \cdot \text{N} / \text{m})$$



C : capacitance of a capacitor (unit: Farad = C^2/Nm)



- stored electric potential energy in a capacitor equals the work done by moving $+Q$ from b to a

$$W = \Delta U = \int_0^Q (V_a - V_b)_i \cdot dQ = \frac{1}{C} \int_0^Q Q dQ = \frac{Q^2}{2C}$$

$$\therefore \Delta U = \frac{Q^2}{2C} = \frac{C}{2} (V_a - V_b)_Q^2$$

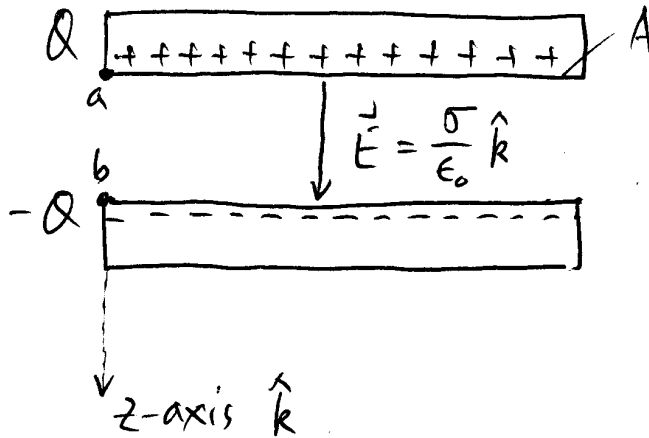
Equivalently, if $-Q$ is being moved (electrons), $dQ > 0$

$$\begin{aligned} W = \Delta U &= \int (V_b - V_a)_i (-dQ) = \int (V_a - V_b)_i \cdot dQ \\ &= \frac{1}{C} \int_0^Q Q dQ = \frac{Q^2}{2C} \end{aligned}$$

*

• Capacitance of a parallel-plate capacitor

Two conducting plates separated by d , and having an overlapping area A .



When $d \ll \sqrt{A}$, by symmetry Q and $-Q$ are uniformly distributed. The electric field E inside is uniform and contributed by two sheets of charges

$$\vec{E} = \frac{\sigma}{2\epsilon_0} \hat{k} + \frac{(-\sigma)}{2\epsilon_0} (-\hat{k}) = \frac{\sigma}{\epsilon_0} \hat{k} = E \hat{k}$$

Potential difference $V_a - V_b = Ed = \frac{\sigma}{\epsilon_0} d = \frac{Q}{\epsilon_0 A/d}$

$$\therefore C = \frac{Q}{V_a - V_b} = \frac{\epsilon_0 A}{d} \quad (\text{geometry only})$$

C increases with A : larger overlapping area enables more charge storage with the same $V_a - V_b$

C decreases with d : larger separation requires less charge transfer to reach same $V_a - V_b$.

Example 25-2

Example 25-3

Two concentric spherical conducting surfaces

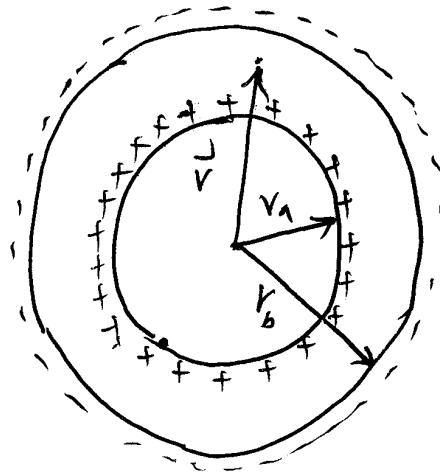
From Gauss' law,

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \cdot \frac{Q}{r^2} \hat{r}$$

Potential difference between inner and outer shell

$$V_a - V_b = \frac{Q}{4\pi\epsilon_0} \cdot \left(\frac{1}{r_a} - \frac{1}{r_b} \right)$$

$$C = \frac{Q}{V_a - V_b} = \frac{4\pi r_a r_b \epsilon_0}{r_b - r_a} \quad \#$$



$$\# C: \text{Farad} = \text{C}^2/\text{Nm}$$

$$\epsilon_0 = 8.85 \times 10^{-12} \text{ C}^2/\text{Nm}^2$$

$$= 8.85 \times 10^{-12} \text{ F/m}$$

$$= 8.85 \text{ pF/m}$$

When $\Delta r \equiv r_b - r_a \ll r_a$, $4\pi r_a r_b \approx 4\pi r_a^2$, $\Delta V \approx d$

$$C \approx \frac{\epsilon_0 A}{d} \text{ (parallel-plate capacitor)}$$

When $r_b = +\infty$, C (single spherical conducting sphere) $= 4\pi r_a \epsilon_0$

Example 25-4 : read it yourself / Discussion

Electric field from a line charge or charges on a long cylinder

Electric potential from a line charge or charges on a long cylinder

Capacitance (BNC) of two concentric cylindrical shells of conductors per unit length *

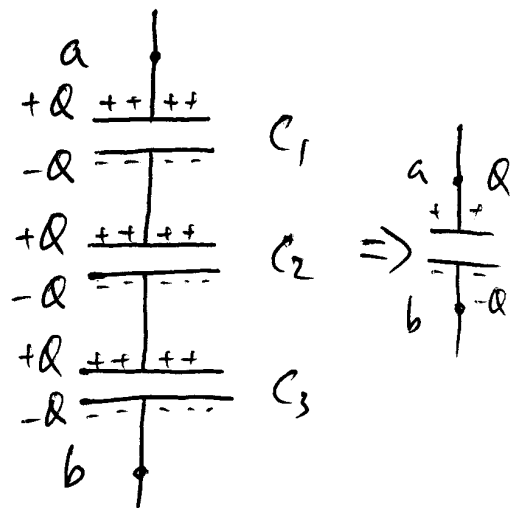
Capacitors in series and in parallel:

Capacitors in series:

(effectively increasing d , thus the total $C \downarrow$)

$$\frac{Q}{C} = V_a - V_b = \frac{Q}{C_1} + \frac{Q}{C_2} + \frac{Q}{C_3}$$

$$\boxed{\frac{1}{C} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3} + \dots}$$

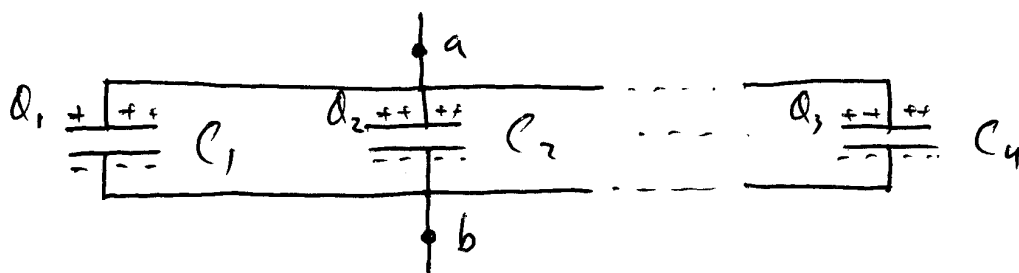


With n identical capacitors in series, d is increased by a factor of n , and thus C is expected to drop by a factor of n :

$$\frac{1}{C} = \frac{1}{C_1} + \dots + \frac{1}{C_n} = \frac{n}{C_1} \quad \text{or} \quad C = C_1/n.$$

Capacitors in parallel:

Effectively increasing A , thus the total $C \uparrow$.



$$C = \frac{Q}{V_a - V_b} = \frac{Q_1 + Q_2 + \dots + Q_n}{V_a - V_b} = C_1 + C_2 + \dots + C_n$$

When n identical capacitors are in parallel, d is fixed, only A is increased by a factor of n , and thus $C \sim \epsilon_0 A/d$ is expected to increase by n

$$C = C_1 + C_2 + \dots + C_n = nC_1$$

*

Example 25-6

Example 25-7

Dielectrics

Insulating materials stuffed in between the two conductors of a capacitor that make moving electric charges move easily, thus for the same charge Q , stored electrostatic energy is less by a factor K

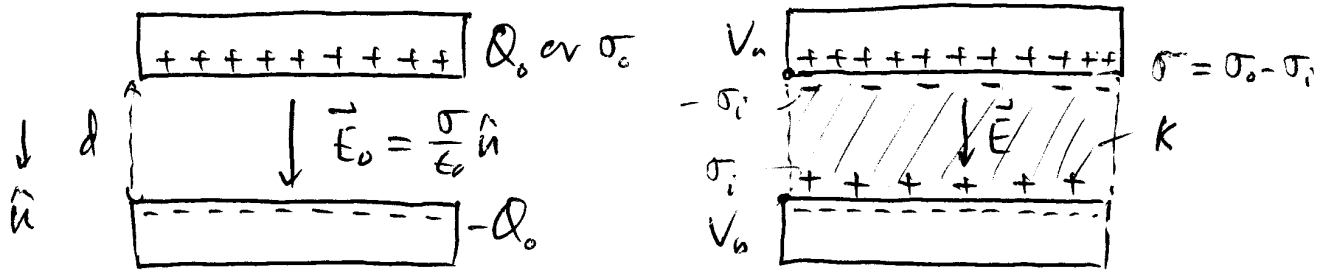
$$\Delta U_k = \frac{Q^2}{2C_k} = \frac{1}{K} \Delta U = \frac{1}{K} \left(\frac{Q^2}{2C_0} \right)$$

K : dielectric constant of an insulating material (dielectrics)

$$C_k = K C_0 \quad K = \frac{C_k}{C_0}$$

Dielectric effect (K) comes from the tendency of a dielectric to reduce the external applied electric field by a factor of K . Such a tendency is a result of motions (restricted) of two types of electric charges along opposite directions under the applied electric field.

- Reduction of electric field in a dielectric and the capacitance of a capacitor filled with the dielectric



$$E = \frac{\sigma_0 - \sigma_i}{\epsilon_0} = \frac{1}{k} \epsilon_0 E_0 = \frac{\sigma_0}{k \epsilon_0} \quad (\text{dropped by } k)$$

$$(V_a - V_b) = Ed = \frac{1}{k} (E_0 d) = \frac{1}{k} (V_a - V_b)_0 \quad (\downarrow \text{ by } k)$$

$$C = \frac{Q_0}{V_a - V_b} = \frac{Q_0}{(V_a - V_b)_0 / k} = k \frac{Q_0}{(V_a - V_b)_0} = k C_0$$

From $(\sigma_0 - \sigma_i) = \sigma_0 / k$, $\sigma_i = \frac{k-1}{k} \sigma_0$

induced surface charge

Example: Water has $k=80$, $\sigma_i = \sigma_0$, so that the electric field inside water is almost totally "cancelled". Other materials are not so good: (But water is often contaminated with ions).

Example: Capacitance of a partly filled capacitor

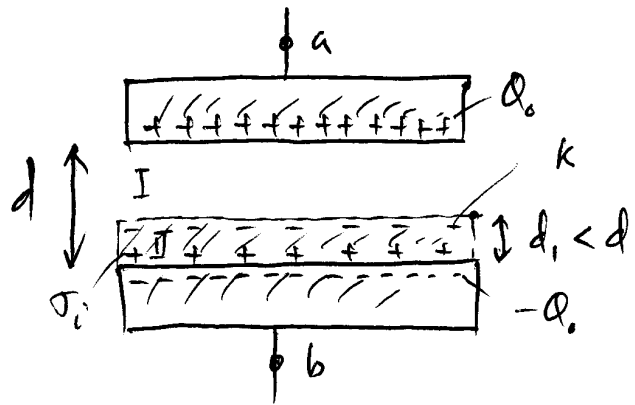
Method #1: (from $C = Q/V$)

In Region I,

$$E_I = \frac{\sigma_0}{\epsilon_0} = \frac{Q_0}{\epsilon_0 A}$$

In region II,

$$E_{II} = \frac{E_I}{k} = \frac{1}{k} \left(\frac{Q_0}{\epsilon_0 A} \right)$$



Total potential drop:

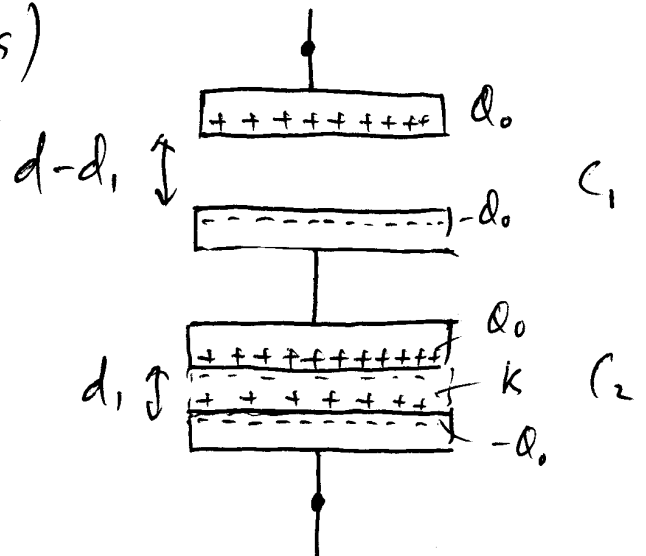
$$V_a - V_b = E_I \cdot (d - d_1) + E_{II} d_1 = \frac{Q_0}{\epsilon_0 A} \left((d - d_1) + \frac{d_1}{k} \right)$$

$$\therefore C = \frac{Q_0}{V_a - V_b} = \frac{\epsilon_0 A}{(d - d_1) + d_1/k}$$

Method #2: (capacitors in series)

$$C_1 = \frac{\epsilon_0 A}{d - d_1}$$

$$C_2 = k \frac{\epsilon_0 A}{d_1}$$



$$\frac{1}{C} = \frac{1}{C_1} + \frac{1}{C_2} = \frac{(d - d_1) + d_1/k}{\epsilon_0 A}$$

- Storage of electrostatic energy in a capacitor with and without dielectric filling

Without dielectric filling,

$$\Delta U = \frac{Q^2}{2C} = \frac{\epsilon_0}{2} (V_a - V_b)^2$$

Energy density inside a parallel-plate capacitor is uniform

$$\Delta U = u (Ad) = \frac{1}{2} \left(\frac{\epsilon_0 A}{d} \right) (E \cdot d)^2 = \frac{\epsilon_0}{2} E^2$$

$$\therefore \boxed{u = \frac{\epsilon_0}{2} E^2}$$

True even when \vec{E} is not uniform.

With dielectric filling,

$$\Delta U_k = k \frac{\epsilon_0}{2} (V_a - V_b)_k^2 = k \cdot \left(\frac{\epsilon_0}{2} E^2 \right) \cdot (Ad)$$

$$\boxed{u_k = \frac{\Delta U_k}{(Ad)} = \frac{k \epsilon_0}{2} E^2}$$

Example 25-10 #11

• Gauss' law in dielectrics (optimal)

$$\oint \vec{E} \cdot d\vec{A} = \frac{\Delta A}{\epsilon_0} (\sigma_o - \sigma_i)$$

LHS:

$$\oint \vec{E} \cdot d\vec{A} = (\vec{E}_{\text{conductor}}) \cdot (-\Delta A \hat{u}) + (\vec{E}) \cdot (\Delta A \cdot \hat{u})$$

$$= (\dots) + \frac{1}{\kappa} (\vec{E}_o) \cdot (\Delta A \cdot \hat{u})$$

By moving $(\Delta A / \epsilon_0) (-\sigma_i)$ to LHS:

$$\frac{1}{\kappa} (\vec{E}_o) \cdot (\Delta A \cdot \hat{u}) + \left(\frac{\sigma_i}{\epsilon_0}\right) \cdot \Delta A = \frac{1}{\kappa} (\epsilon_0 \Delta A) + \frac{\kappa-1}{\kappa} E_o \Delta A$$

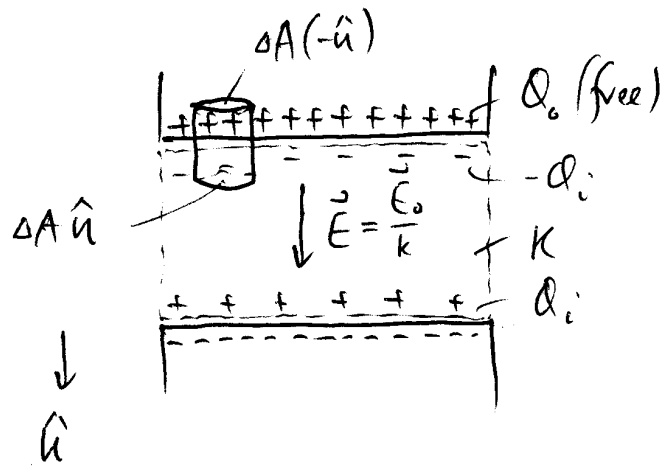
$$= \vec{E}_o \cdot (\Delta A \cdot \hat{u}) = (\kappa \vec{E}) \cdot (\Delta A \hat{u})$$

We have

$$\oint (\kappa \vec{E}) \cdot d\vec{A} = \frac{Q_f}{\epsilon_0} \quad (\text{since } \vec{E}_{\text{conductor}} = 0)$$

Generally, we define $\vec{D} = \kappa \epsilon_0 \vec{E}$,

$$\oint \vec{D} \cdot d\vec{A} = Q_f \text{ (inside)}$$



Chapt. 25

Week 15 Electric Current and
Ohm's law for current
in homogeneous, condensed
materials (solids, liquids, etc)

Electric current:

flow of electric charge, typically
through a given cross-sectional surface
 S .

$$I \left| \text{through } S = \frac{\Delta Q}{\Delta t} \right| \text{through } S \text{ in a given direction}$$

SI unit: ampere (A) = Coulomb/sec.

The given direction is specified by the
surface normal.

$$I \left| \text{through } S = \int_S \vec{J} \cdot (\hat{n} dA) = \int_S \vec{J} \cdot d\vec{A}$$

\vec{J} is the electric current density

$$\vec{J} = |\vec{J}| \hat{J} = J \hat{J}$$

\hat{J} is the unit vector that specifies the direction of electric current;

$J = |\vec{J}|$ is the absolute magnitude of electric current passing through a unit area that is perpendicular to \hat{J}

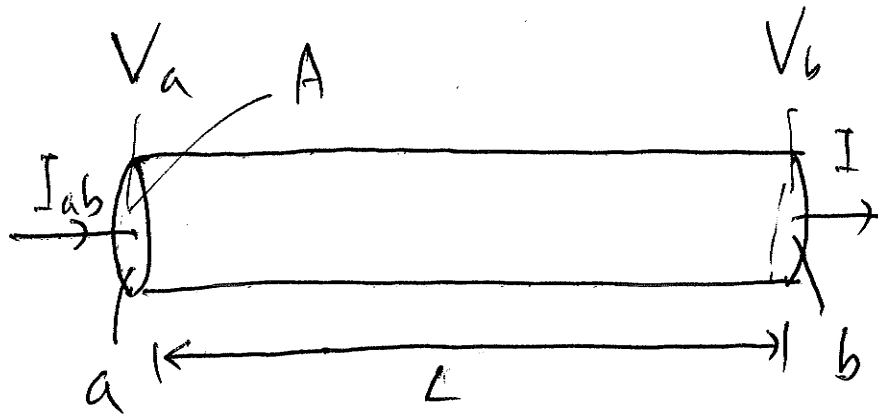
SI unit of J : $A/m^2 = \text{ampere}/m^2$

In a solid or a liquid, if electric charged particles have a velocity \vec{v}_q , and carry a charge q per particle, and have a volume density n_q , then the electric current density contributed by this collection (group) of charged particles (charged carriers) is

$$\vec{J}_q = n_q \cdot q \cdot \vec{v}_q$$

q can be positive or negative; the direction of \vec{J} is determined by the product of q and \vec{v}_q . \vec{v}_q can be driven by many forces.

Ohm's law (only electrostatic force)



$$(V_a - V_b) \propto I_{ab} = -I_{ba}$$

Or,

$$(V_a - V_b) = I_{ab} R \quad (\text{Ohm's law})$$

Proportionality constant:

R : resistance (S.I. unit: ohm = $\frac{\text{Volt}}{\text{Amp}}$)

When L doubles, ΔV needs to be doubled in order to maintain I , thus $R \propto L$;

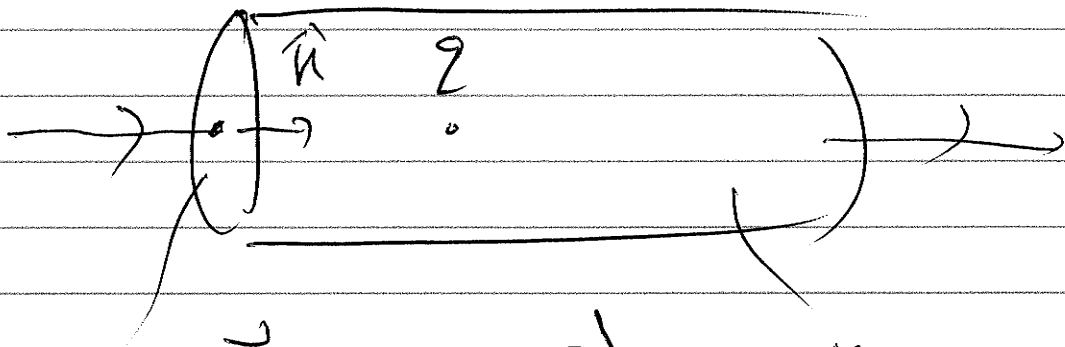
When A doubles, I doubles under same ΔV , thus $R \propto 1/A$:

$$R = \rho \frac{L}{A}$$

ρ : resistivity (ohm.m or $\Omega \cdot m$)
material dependent.

Ohm's law: (general forces)

$$\vec{\mathcal{E}} \rightarrow$$



$$\vec{F}_{\text{eng}} = \rho \vec{\mathcal{E}} \quad n_l \cdot \vec{\mathcal{E}}$$

$$m \frac{d\vec{v}_g}{dt} = \rho \vec{\mathcal{E}} - \frac{m}{\tau} \vec{v}_g$$

$$\Rightarrow \rho \vec{\mathcal{E}} = \frac{m}{\tau} \vec{v}_g$$

$$\langle \vec{v}_g \rangle = \frac{\rho \cdot \tau}{m} \vec{\mathcal{E}}$$

$$\vec{J} = n \cdot \rho \cdot \vec{v}_g = \frac{n \rho^2 \tau}{m} \vec{\mathcal{E}}$$

$$\underline{I} = A \hat{n} \cdot \vec{J} = \frac{n \rho^2 \tau}{m} \cdot A \vec{\mathcal{E}} \cdot \hat{n}$$

$$I_{ab} L = \int_a^b I dl = \frac{n_e e^2 \tau A}{m} \int_a^b \vec{E} \cdot d\vec{l}$$

$$\int_a^b \vec{E} \cdot d\vec{l} = I_{ab} \underbrace{\left(\frac{m}{n_e e^2 \tau A} \right)}_R \cdot \frac{L}{A}$$

Across a resistor, $\vec{E} = E$

$$V_a - V_b = I_{ab} R$$

$$R = \frac{m}{n_e e^2 \tau A} \cdot \frac{L}{A} = \rho \frac{L}{A}$$

Across a battery, $\vec{E} = \vec{E}_e + \vec{E}$

$$\int_c^d (\vec{E}_v + \vec{E}_i) \cdot d\vec{l} = \int_{cd} V_i$$

$$\int_c^d \vec{E}_v \cdot d\vec{l} + (V_c - V_d) = \int_{cd} V_i$$

$$\left| \int_c^d \vec{E}_v \cdot d\vec{l} \right| \equiv \mathcal{E}$$

If $\vec{E}_v \cdot d\vec{l} > 0$,

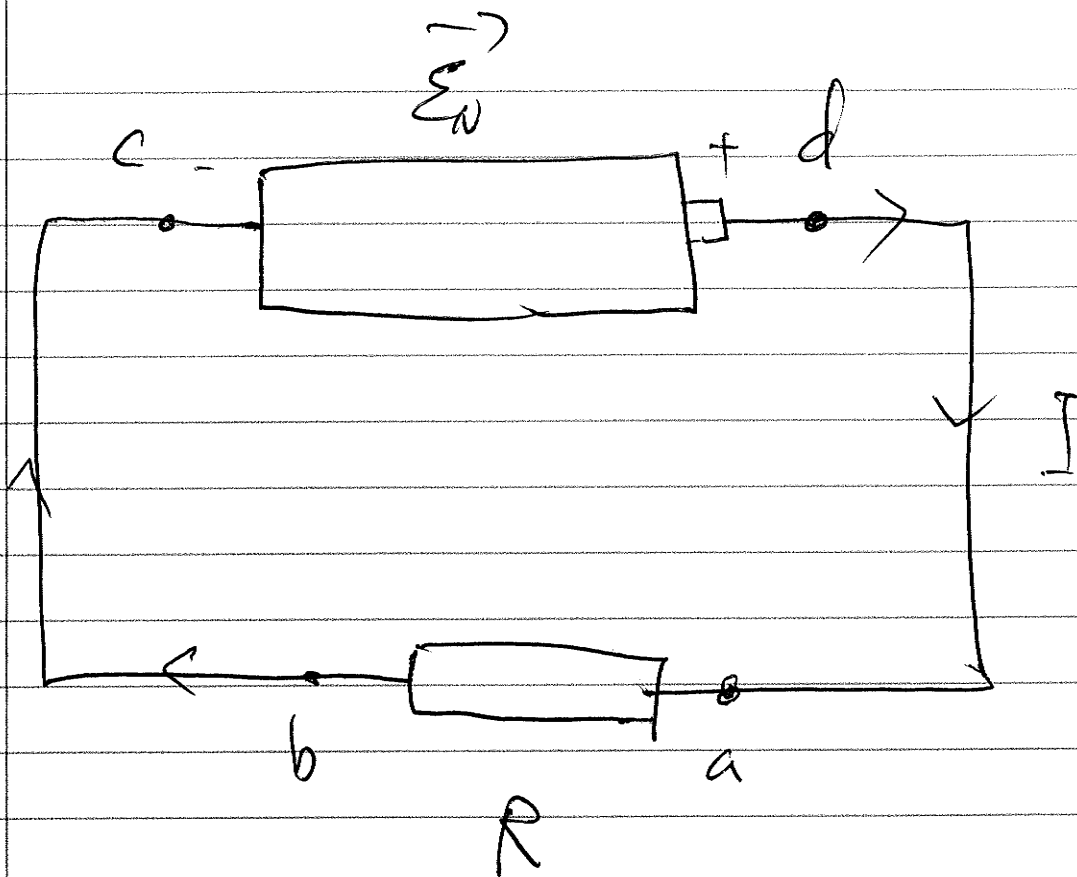
$$\int_{c^{(-)}}^{d^{(+)}} \vec{E}_v \cdot d\vec{l} = \mathcal{E} = \int_{c^{(-)}}^{d^{(+)}} \vec{E}_v \cdot d\vec{l}$$

$$\mathcal{E} + (V_c^{(-)} - V_d^{(+)}) = \int_{cd} V_i$$

Ideal battery, $r_i = 0$; open-circuit battery

$$I_{cd} = 0 \text{ or } V_i = 0$$

$$\mathcal{E} = V_d^{(+)} - V_c^{(-)} > 0 \Rightarrow V_d^{(+)} > V_c^{(-)}$$



Steady-current $I_{ab} = I_{cd}$

Across R :

$$I_{ab} R = V_a - V_b$$

Across battery

$$I_{cd} \cdot r_i = \mathcal{E} + (V_c^{(-)} - V_d^{(+)})$$

But $V_c^{(-)} - V_d^{(+)} = -(V_a - V_b)$

$$\mathcal{E} = I \cdot (r_i + R)$$

$$\Rightarrow I = \frac{\mathcal{E}}{R + r_i}$$

Another look

$$\oint \vec{E} \cdot d\vec{\ell} = 0$$

$$\int_a^b \vec{E} \cdot d\vec{\ell} + \int_{c(-)}^d(+)\vec{E} \cdot d\vec{\ell} = 0$$

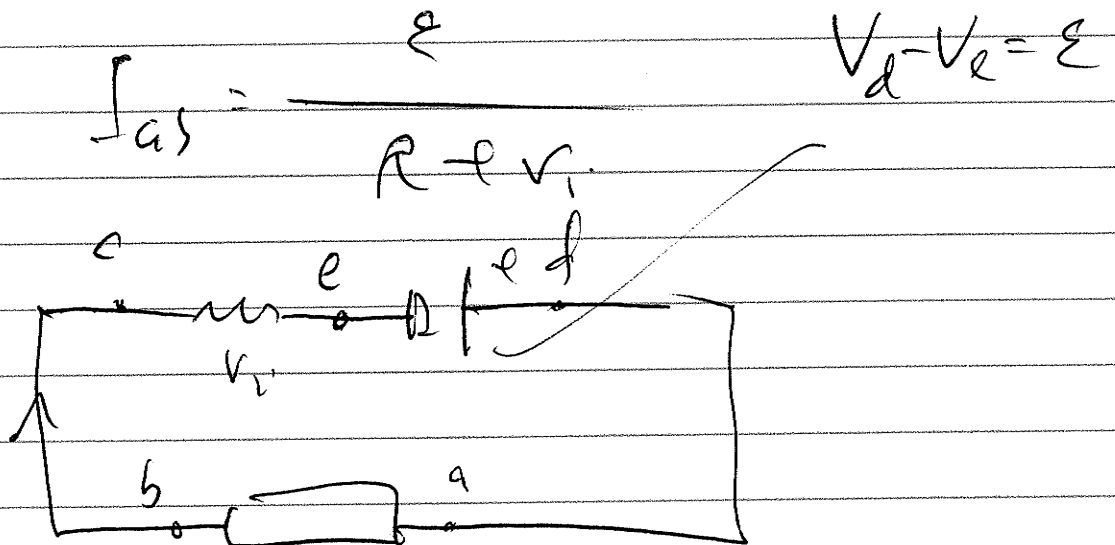
||

||

$$I_{as} R$$

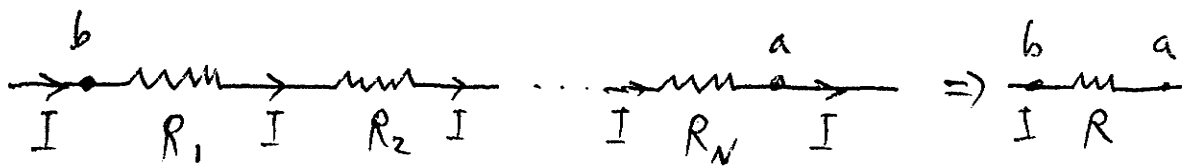
$$-I_{cd} r_i - \mathcal{E}$$

$$\Rightarrow I_{as} (R + r_i) - \mathcal{E} = 0$$



Chapt. 26

- Resistors in series



Equivalent of increasing the total length of a resistive wire, $R = \rho L / \Delta S \propto L$, so we expect

$$R = R_1 + R_2 + \dots + R_N$$

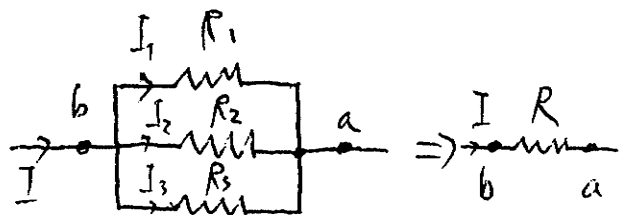
Generally,

$$V_b - V_a = RI$$

$$R = \frac{V_b - V_a}{I} = \frac{\Delta V_1 + \Delta V_2 + \dots + \Delta V_N}{I} = R_1 + R_2 + \dots + R_N$$

- Resistors in parallel.

Equivalent of increasing cross-section area ΔS ,
 $1/R = \Delta S / \rho L \propto \Delta S$

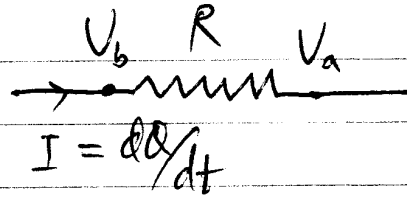


$$\frac{1}{R} = \frac{1}{R_1} + \frac{1}{R_2} + \dots + \frac{1}{R_N}$$

$$\leftarrow \frac{V_b - V_a}{R} = \frac{V_a - V_a}{R_1} + \frac{V_b - V_a}{R_2} + \dots$$

- Power dissipation in a resistor R

During dt , electro-static potential energy loss to the resistor (as the charges dQ has gained a net kinetic energy)



$$dU = (V_b - V_a) \cdot dQ = (V_b - V_a) \cdot I \cdot dt = V \cdot I \cdot dt$$

The power loss (dissipation) in a resistor R :

$$P = \frac{dU}{dt} = \frac{dW}{dt} = V \cdot I = \frac{V^2}{R} = I^2 R$$

Power generated by an emf source

$$P_{\mathcal{E}} = \mathcal{E} \cdot I \quad (\text{work done per unit time by a source of emf})$$

Example 26-9

Example 27-1

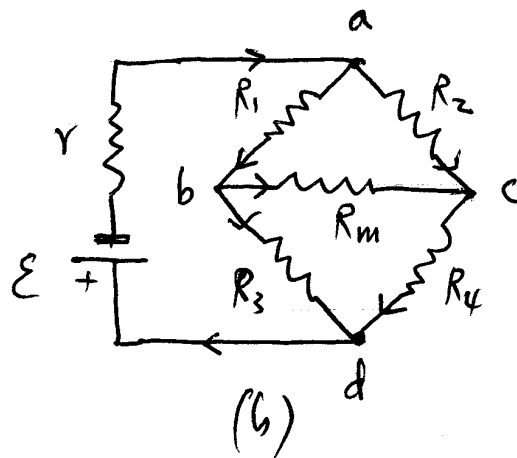
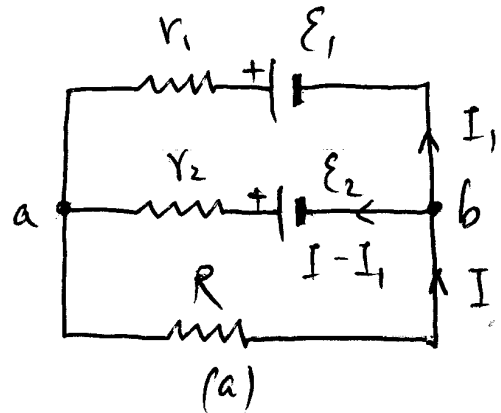
• Direct-current circuits

Kirchoff's Rules

Rule #1. (Junction rule)

Algebraic sum of the currents into a junction (where three or more circuit branches meet) is zero so that no net charge is accumulated or drained from the junction

$$\sum I = 0 \text{ or } \sum I_{in} = \sum I_{out}$$



Rule #2. (Loop rule)

Algebraic sum of the potential difference (drop or rise) is zero:

$$\oint \vec{E} \cdot d\vec{l} = \sum V = 0$$

There are same number of independent loops (including a fresh branch) as of unknown currents, completely solvable.

Example (a)

$$\begin{cases} (R - r_2) I - r_2 I_1 = \mathcal{E}_2 \\ R I - r_1 I = \mathcal{E}_1 \end{cases}$$

Lower loop: $-IR + \mathcal{E}_2 - (I - I_1) \cdot r_2 = 0$

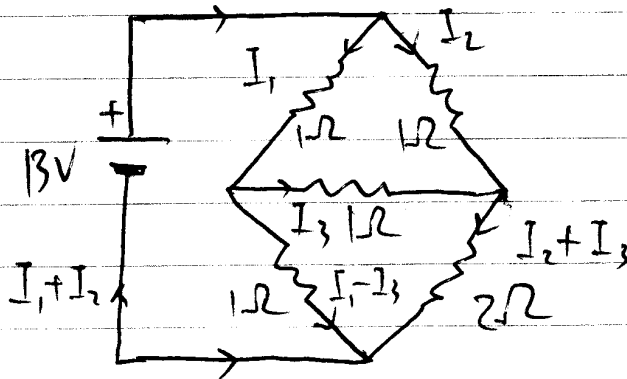
Larger loop: $-IR + \mathcal{E}_1 - I \cdot r_1 = 0$

Two unknowns, two equations

Example (b)

Three independent currents to be determined;
Three independent loops that enable setting
up three linear equations for solving for
the current.

Example 27-6



Kirchoff Rules in practice

1. Assign a current (magnitude & direction) in each branch of the circuit. Apply the Junction Rule so that you only have the minimum number of currents that are independent of each, while currents in other branches can be obtained as a linear combination of these independent currents.
2. Identify an equal number of independent loops that each contains at least one branch of the circuit not shared by other loops; and assign a loop direction.
3. Along the direction of each loop, identify the potential difference, given the orientation of the emf and the assigned current

Emf \mathcal{E} : from low to high $+\mathcal{E}$
 from high to low $-\mathcal{E}$

Resistor R : loop direction along the current: $-IR$
 loop direction against the current: $+IR$.

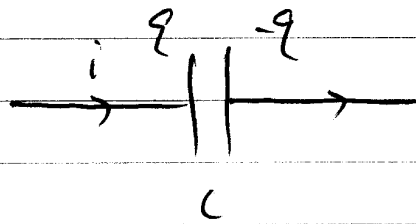
4. When solved $I > 0$, I is along the assigned direction

4. (continue) when solved $I < 0$, I in the branch of interest is along the opposite direction to the assigned one.

5. If a current i (time-varying case) encounters a capacitor C , then put Q on the first plate, $-Q$ on the second plate, and the potential difference along the assigned current direction

is

$$\left(-\frac{Q}{C}\right)$$



and

$$i = \frac{dQ}{dt}$$

$Q(t=0)$ should be known.

If the loop direction is opposite to the assigned direction of i , then the potential difference

is

$$\left(\frac{Q}{C}\right)$$

• Resistance - capacitance circuits (RC-circuits)

Current and potential difference vary with time, but slow enough that Kirchoff Rules apply: charges can only be accumulated on capacitors;

$$\oint \vec{E} \cdot d\vec{l} = 0$$

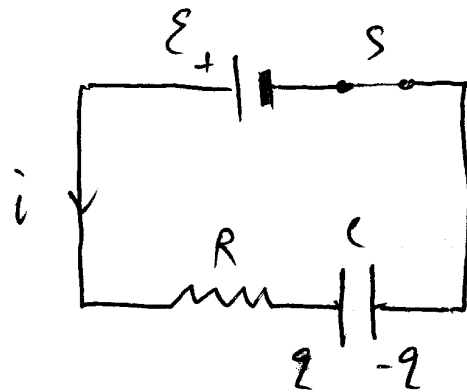
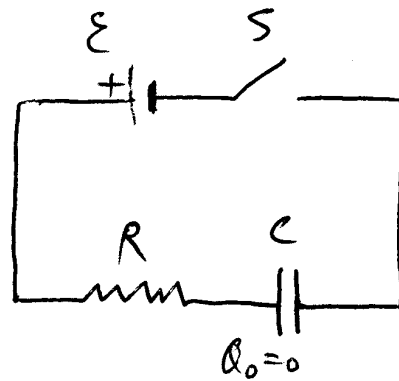
When s is closed, along a ccw loop,

$$\begin{cases} -iR - \frac{q}{C} + \varepsilon = 0 \\ i = \frac{dq}{dt}, \quad q(0) = 0 \end{cases}$$

$$\begin{cases} \frac{dq}{dt} + \frac{q}{RC} = \frac{\varepsilon}{R} \\ q(t=0) = 0 \end{cases} \Rightarrow \frac{d}{dt} (q - \varepsilon C) = -\frac{1}{RC} (q - \varepsilon C)$$

$$q(t) - \varepsilon C = (q(0) - \varepsilon C) e^{-t/RC}$$

$$\therefore q(t) = \varepsilon C (1 - e^{-t/RC}), \quad i(t) = \frac{dq}{dt} = \frac{\varepsilon}{R} e^{-t/RC}$$

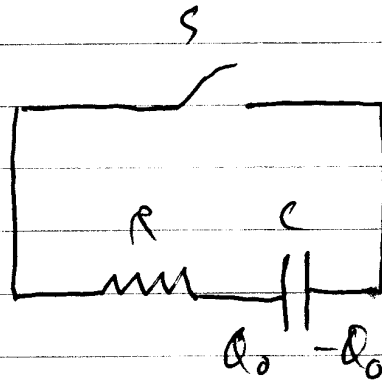


At $t=0$, $q(0)=0$, the capacitor appears as a short with no resistance, so that the potential on R equals \mathcal{E} .

At $t=\infty$, $q(\infty)=\mathcal{E}C$, or $i(+\infty)=0$, the capacitor appears as an open with infinite resistance, so that the potential drop on R is zero, while the potential drop across C is \mathcal{E} .

- Discharging a capacitor & energy conservation
When S is closed,

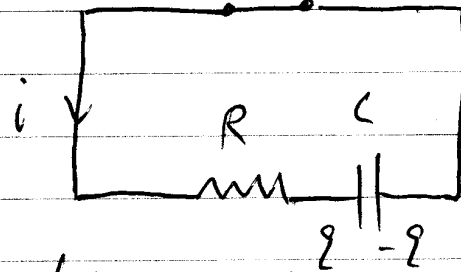
$$\begin{cases} -iR - q/C = 0 \\ i = \frac{dq}{dt}, \quad q(0) = Q_0 \end{cases}$$



$$\frac{dq}{dt} = -\frac{q}{RC}$$

$$q(t) = Q_0 e^{-t/RC}$$

$$i = \frac{dq}{dt} = -\frac{Q_0}{RC} e^{-t/RC}$$



flowing in the opposite direction to the assigned.

Time constant $\tau = RC$

Energy stored in the capacitor before discharging

$$U_0 = \frac{Q_0^2}{2C}$$

Energy dissipated in the resistor during discharging

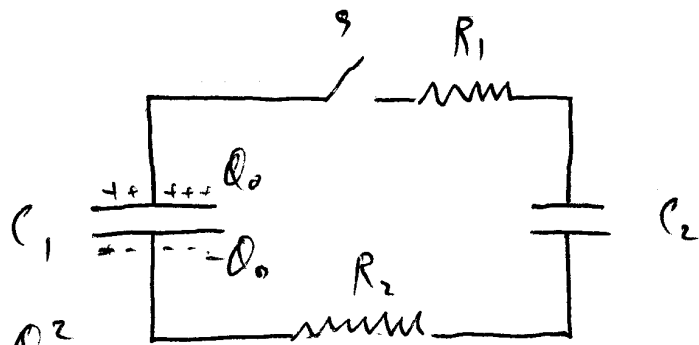
$$\begin{aligned} \Delta U &= \int_0^{+\infty} \frac{dW}{dt} \cdot dt = \int_0^{+\infty} dt \cdot (i^2 R) \\ &= \int_0^{+\infty} \left(-\frac{Q_0}{RC}\right)^2 \cdot R \cdot e^{-2t/RC} \cdot dt \\ &= \frac{Q_0^2}{2C} \cdot \int_0^{+\infty} e^{-2t/RC} d\left(\frac{2t}{RC}\right) \\ &= \frac{Q_0^2}{2C} \end{aligned}$$

Example: (Optional)

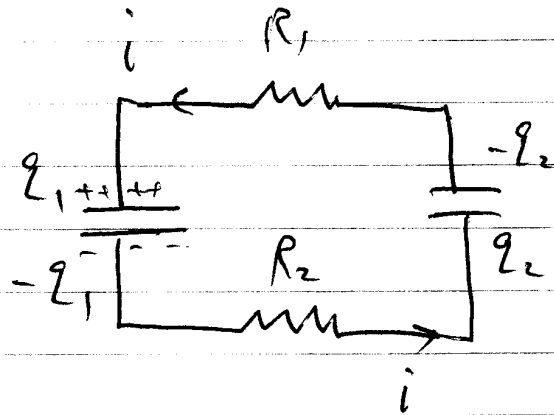
Energy stored $U_0 = \frac{Q_0^2}{2C_1}$
After S is closed,

$$U = \frac{Q_0^2}{2(C_1 + C_2)}$$

$$\text{Energy loss: } U_0 - U = \frac{C_2 \cdot Q_0^2}{2C_1(C_1 + C_2)}$$



$$\begin{cases} -iR_1 - q_1/c_1 - iR_2 - q_2/c_2 = 0 \\ q_1 - q_2 = Q_0 \\ i = \frac{dq_1}{dt} \\ q_1(0) = Q_0 \end{cases}$$



$$\frac{dq_1}{dt} (R_1 + R_2) = -\frac{q_1}{c_1} - \frac{q_1 - Q_0}{c_2}$$

$$\frac{dq_1}{dt} = -\frac{(c_1 + c_2)}{(R_1 + R_2) \cdot c_1 \cdot c_2} \cdot \left(q_1 - \frac{c_1}{c_1 + c_2} Q_0 \right)$$

$$\therefore q_1(t) - \frac{c_1}{c_1 + c_2} Q_0 = \left(q_1(0) - \frac{c_1}{c_1 + c_2} Q_0 \right) e^{-\frac{(c_1 + c_2) \cdot t}{(R_1 + R_2) \cdot c_1 \cdot c_2}}$$

$$\therefore q_1(t) = \frac{c_1 \cdot Q_0}{c_1 + c_2} + \frac{c_2 \cdot Q_0}{c_1 + c_2} e^{-\frac{(c_1 + c_2) \cdot t}{(R_1 + R_2) \cdot c_1 \cdot c_2}}$$

$$i = \frac{dq_1(t)}{dt} = -\frac{Q_0}{(R_1 + R_2) \cdot c_1} e^{-\frac{(c_1 + c_2) \cdot t}{(R_1 + R_2) \cdot c_1 \cdot c_2}}$$

$$\Delta U \Big|_{\text{loss in } R_1 \text{ \& } R_2} = \int_0^{\infty} dt i^2 (R_1 + R_2) = \frac{c_2 \cdot Q_0^2}{2c_1 (c_1 + c_2)} *$$

Chapter 27. Magnetic forces

- Magnetic forces between permanent "magnets"
Solid materials containing Fe and a number of other elemental materials exert forces on each other, even when carrying no ~~atoms~~ net electric charges.
They are magnets.

- A magnet of any shape has two opposite ends (or faces) that are called magnetic poles.

When freely suspended, one magnetic pole of a magnet points to the north pole of the Earth, and is called "the north pole" of the magnet. The other magnetic pole points to the south pole of the Earth, and is called "the south pole" of the magnet.

A compass needle is a needle-shaped magnet with its two ends closer to the two magnetic poles.

- Like magnetic poles repel each other

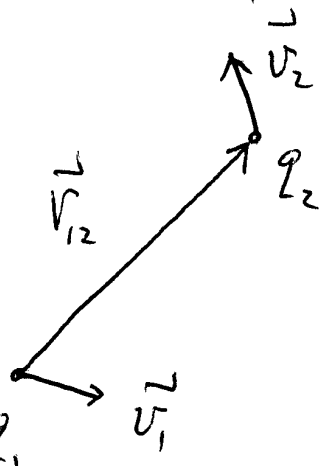
Opposite magnetic poles attract each other

(But how they work is a bit complicated,)

- Magnetic force by a moving charge on another moving charge

Lorentz-Biot-Savart law of magnetic force:
(magnetic counterpart of Coulomb's law)

Force of a moving point charge (q_1, \vec{v}_1) on another moving point charge (q_2, \vec{v}_2) at a field position \vec{r}_{12} from the source



$$\vec{F}_M (1 \text{ on } 2) = \frac{\mu_0}{4\pi} \frac{q_2 \vec{v}_2 \times (\vec{q}_1 \vec{v}_1 \times \hat{r}_{12})}{r_{12}^2}$$

Magnetic field \vec{B} produced by a moving point charge (q_1, \vec{v}_1) at a field position \vec{r} from q_1

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \frac{q_1 \vec{v}_1 \times \hat{r}}{r^2} \quad (\text{S.I. unit: tesla or T})$$

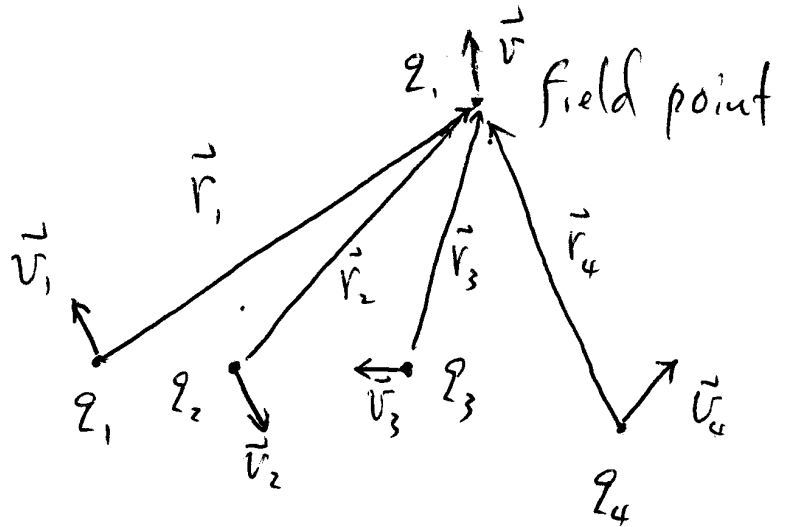
$$\vec{F}_M (1 \text{ on } 2) = q_2 \vec{v}_2 \times \vec{B}(\vec{r}) = q_2 \vec{v}_2 \times \vec{B}$$

$$1 \text{ tesla} = 1 \text{ T} = 1 \text{ N/A}\cdot\text{m} = 10^4 \text{ gauss}$$

$$\mu_0 = 4\pi \times 10^{-7} \text{ N}\cdot\text{s}^2/\text{C}^2 = 4\pi \times 10^{-7} \text{ N/A}^2 = 4\pi \times 10^{-7} \text{ T}\cdot\text{m/A}$$

- Magnetic field \vec{B} produced a collection of moving electric charges ($q_1, \vec{v}_1; q_2, \vec{v}_2; \dots; q_N, \vec{v}_N$)

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{q_1 \vec{v}_1 \times \hat{r}_1}{r_1^2} + \frac{\mu_0}{4\pi} \frac{q_2 \vec{v}_2 \times \hat{r}_2}{r_2^2} + \dots + \frac{\mu_0}{4\pi} \frac{q_N \vec{v}_N \times \hat{r}_N}{r_N^2}$$

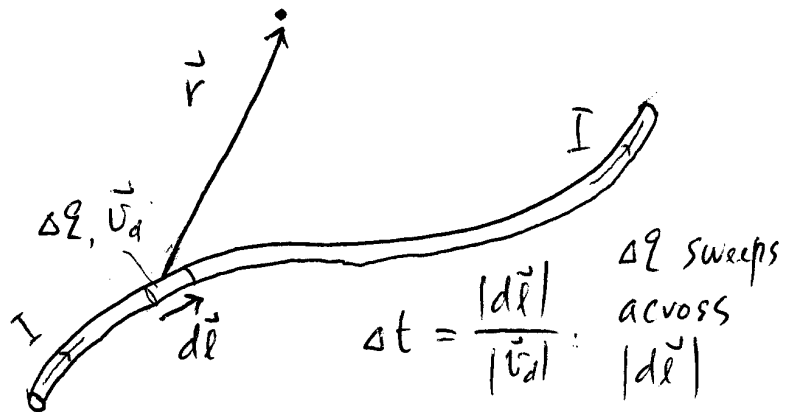


Magnetic force on a moving point charge (q, \vec{v}) at the field point

$$\vec{F}_M = q \vec{v} \times \vec{B}$$

- Magnetic field \vec{B} produced by a segment of current-carrying thin wire

$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{\Delta q \cdot \vec{v}_d \times \hat{r}}{r^2} = \frac{\mu_0}{4\pi} \frac{\Delta q \cdot d\vec{l} \times \hat{r}}{\Delta t \cdot r^2} = \frac{\mu_0}{4\pi} \frac{I d\vec{l} \times \hat{r}}{r^2}$$



$$\vec{B} = \int \frac{\mu_0}{4\pi} \cdot \frac{I d\vec{l} \times \hat{r}}{r^2}$$

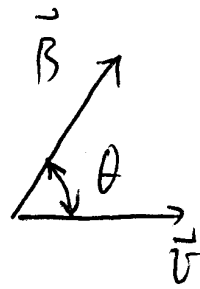
Magnetic force felt by a moving charge (q, \vec{v}) in a magnetic field \vec{B}

$$\vec{F}_M = q \vec{v} \times \vec{B} = q \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ v_x & v_y & v_z \\ B_x & B_y & B_z \end{vmatrix}$$

$$= q(v_y B_z - v_z B_y) \hat{i} + q(v_z B_x - v_x B_z) \hat{j} + q(v_x B_y - v_y B_x) \hat{k}$$

$$\vec{F}_M \perp \vec{v}$$

$$\vec{F}_M \perp \vec{B}$$



$$|\vec{F}_M| = |q| v B \sin \theta$$

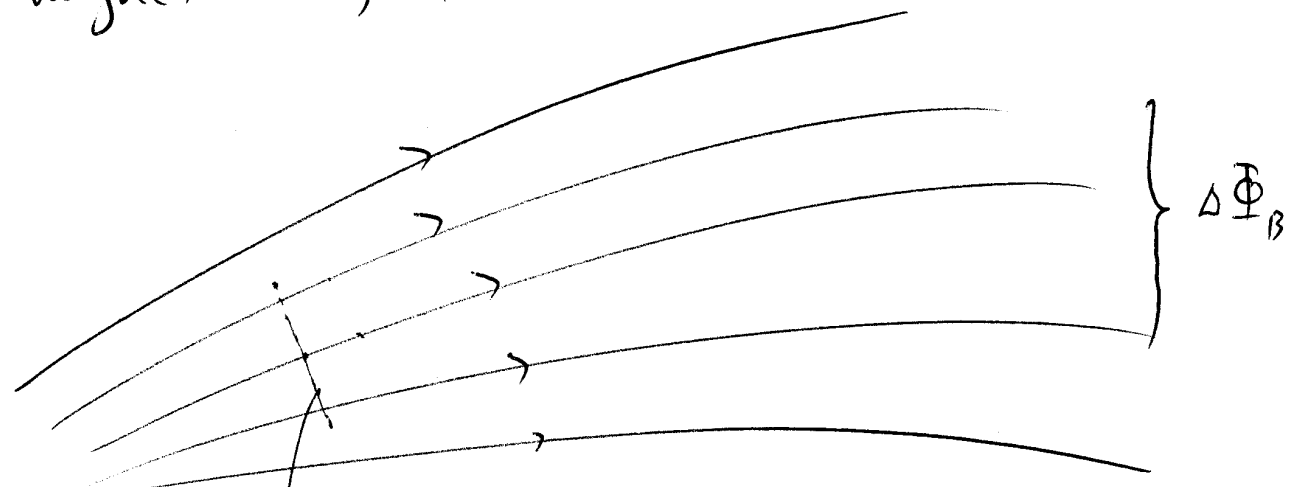
Example 29-1

Example 29-2

Example 28-1

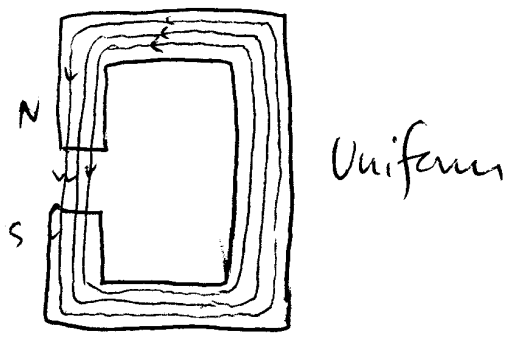
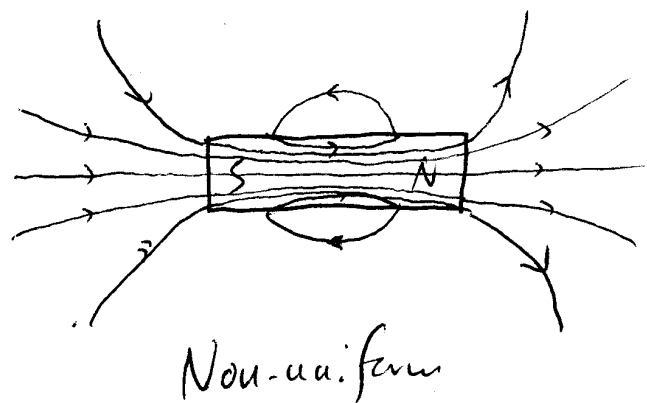
• Magnetic field lines and magnetic flux through a directed (vector) surface element

The distribution of a magnetic field $\vec{B}(\vec{r})$ can be represented by a set of magnetic field lines such that the direction of the lines is along that of \vec{B} , and the number density (i.e., number of the field lines crossing a unit surface area that is perpendicular to \vec{B}) equals the magnitude of \vec{B} .



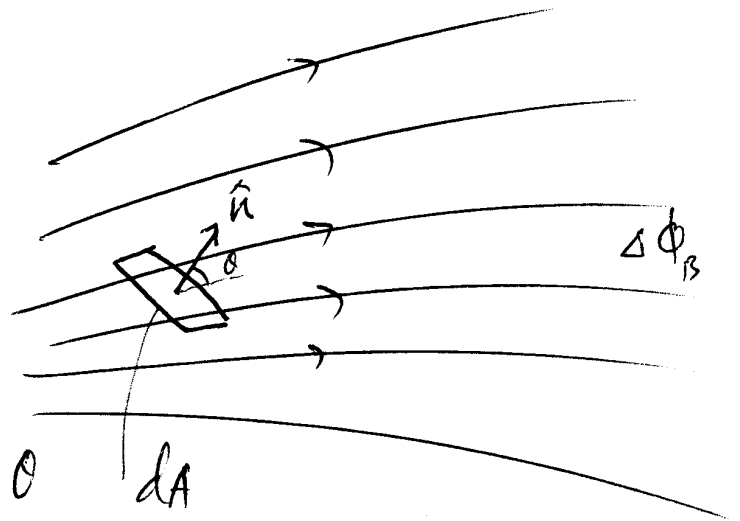
$$\vec{B} = \left| \frac{\Delta\Phi_B}{\Delta A} \right| \hat{n}$$

No beginning!
No end!



Magnetic flux through a directed (vector) area element $d\vec{A} = dA \hat{n}$

— magnetic field lines passing through a directed surface element (cross-section)

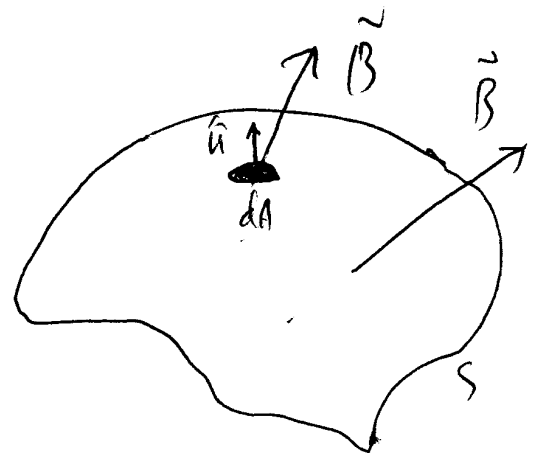


$$d\Phi_B = \vec{B} \cdot d\vec{A} = B dA \cos \theta$$

S.I. unit of Φ_B : weber (Wb) $1 \text{ Wb} = 1 \text{ T} \cdot \text{m}^2$

Magnetic flux through an open surface S

$$\Phi_B = \int_S \vec{B} \cdot d\vec{A}$$



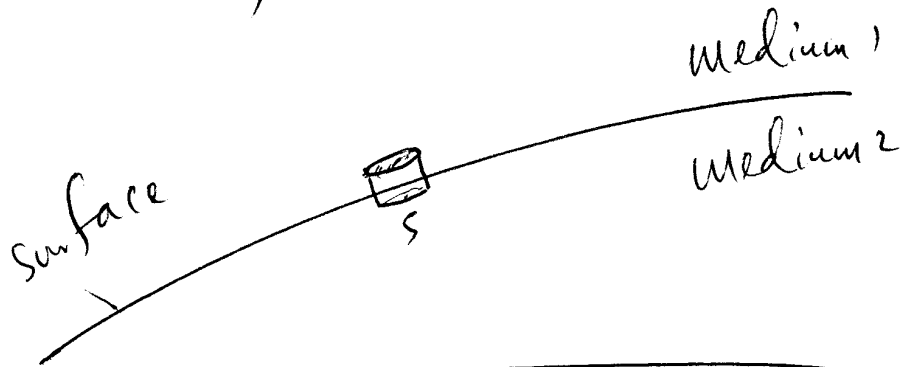
Gauss' law of magnetic flux

$$\oint_S \vec{B} \cdot d\vec{A} = 0$$

— no magnetic monopoles
magnetic field lines are closed loops



Unlike Gauss' law of electric flux that we can use under symmetric conditions to determine the magnitude of electric field, we cannot use Gauss' law of magnetic flux to determine $|\vec{B}|$ under symmetric situation.



from $\oint_s \vec{B} \cdot d\vec{A} = 0$, $\vec{B}_1 \cdot \hat{n} = \vec{B}_2 \cdot \hat{n}$

- Motion of charged particles in a magnetic field \vec{B} without friction (impedance)

First, since $\vec{F}_M = q\vec{v} \times \vec{B}$, the work done by the magnetic force alone per unit time

$$\frac{dw}{dt} = \vec{F}_M \cdot \vec{v} = q \vec{v} \cdot (\vec{v} \times \vec{B}) = 0$$

So \vec{F}_M only changes the direction of a moving charged particle's velocity, not the magnitude of the velocity so that the kinetic energy is conserved in a magnetic field alone.

Charged particle in a constant magnetic field

$$\vec{B} = B_0 \hat{k}$$

Decompose the velocity of a q -charged particle

$$\vec{v} = \vec{v}_\perp + v_\parallel \hat{k} \quad \vec{v}_\perp \text{ in } x\text{-}y \text{ plane}$$

Since $\vec{F}_M = q\vec{v} \times \vec{B}$ is only in x - y plane

$$\frac{d}{dt}(v_\parallel \hat{k}) = 0 \quad \text{The particle moves along } \hat{k} \text{ at a constant speed } v_\parallel.$$

In x - y plane, $|\vec{v}_\perp|$ has to be a constant. Acceleration by the magnetic force \vec{F}_M is

$$\left| \frac{\vec{F}_M}{m} \right| = \frac{|q| v_\perp B}{m}$$

is also a constant. Thus the particle executes a circular motion, - cyclotron motion, with a radius r such that

$$m \frac{v_\perp^2}{r_c} = |\vec{F}_M| = |q| \cdot v_\perp \cdot B$$

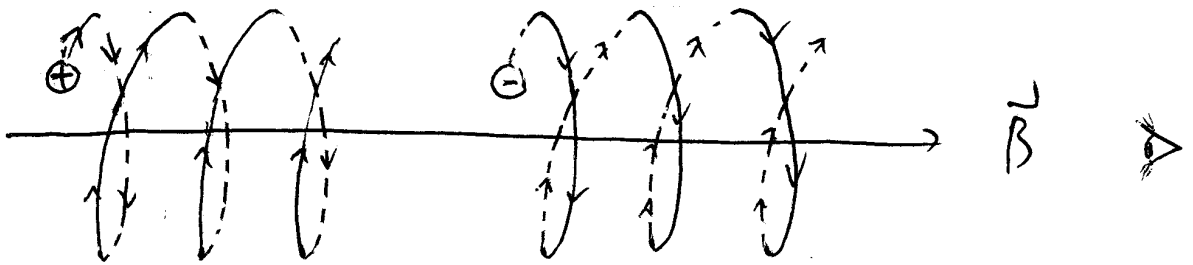
$$\therefore \text{Cyclotron radius: } r_c = \frac{m v_\perp}{|q| \cdot B}$$

cyclotron frequency (number of cycles per unit time)

$$f_c = \frac{v_{\perp}}{2\pi r_c} = \frac{q \cdot B}{2\pi m}$$

Angular cyclotron frequency (radian swept per unit time)

$$\omega_c = 2\pi \cdot f_c = \frac{q \cdot B}{m}$$



$$v_{\parallel} > 0$$

clockwise

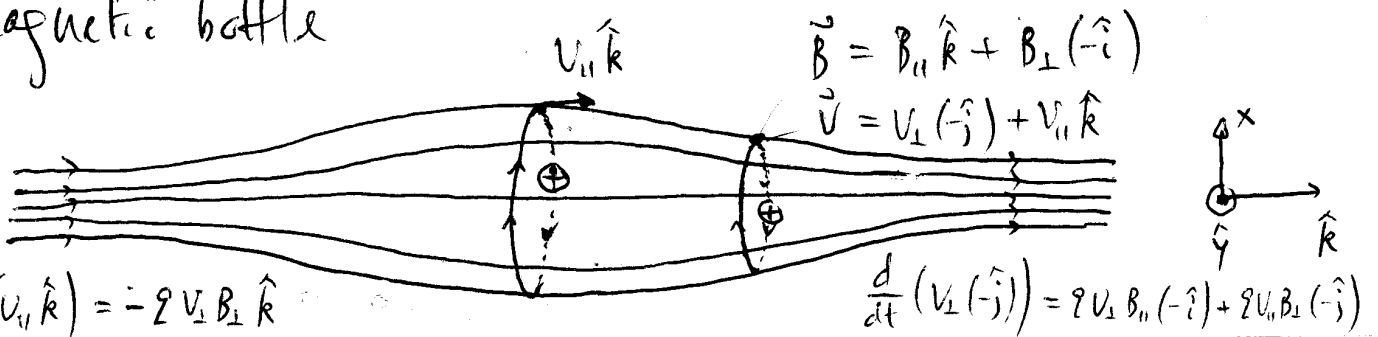
$$v_{\parallel} > 0$$

counter-clockwise

Example 28-4

(Replacing proton with electron, $v_c = R = ?$)

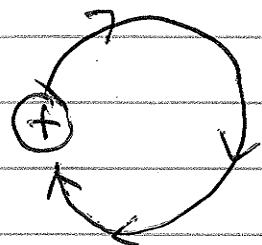
• Magnetic bottle



970

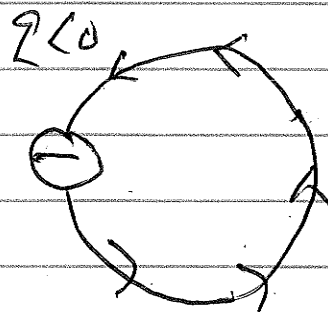
$$\vec{B} = B_0 \hat{k}$$

$$\vec{B} \parallel \hat{k} \odot$$



$$\vec{v} = \vec{v}_1 + \vec{v}_2$$

$$\frac{d\vec{v}}{dt} = q \vec{v} \times \vec{B}$$



$$m \frac{d}{dt} (\vec{v}_1 + \vec{v}_2) = q \vec{v}_1 \times \vec{B}$$

$$\Rightarrow \frac{d}{dt} \vec{v}_2 = 0, \quad \vec{v}_2 = \text{constant}$$

$$\Rightarrow \frac{d}{dt} \vec{v}_1 = q \vec{v}_1 \times \vec{B} / m$$

$$\Rightarrow \frac{d}{dt} \vec{v}_1 = \left(-\frac{q}{m} \vec{B} \right) \times \vec{v}_1$$

This describes a circular motion with a constant angular velocity

$$\vec{\omega}_c = -\frac{q}{m} \vec{B}$$

$$\omega_c = \frac{qB_0}{m}$$

$$\hat{\omega}_c \parallel \hat{k} \quad | \quad q < 0; \quad \hat{\omega}_c \parallel -\hat{k} \quad | \quad q > 0$$

Since $d\vec{v}_\perp/dt$ is perpendicular to \vec{v}_\perp , the magnitude of \vec{v}_\perp is a constant.

Since $\vec{B} \perp \vec{v}_\perp$, $\vec{a} = - (q/m) \vec{B} \times \vec{v}_\perp$ is a constant in magnitude and is always perpendicular to \vec{v}_\perp .

Thus \vec{a} is the centripetal acceleration that keeps the particle on a circle of radius R_c and moving a constant linear speed v_\perp :

$$\frac{|q|B_0 v_\perp}{m} = \frac{v_\perp^2}{R_c}$$

$$R_c = \frac{m v_\perp}{|q| B_0}$$

$$T_c = \frac{2\pi R_c}{v_\perp} = \frac{2\pi m}{|q| B_0}$$

$$f_c = \frac{1}{T_c} = \frac{|q| B_0}{2\pi m}$$

$$\omega_c = \frac{2\pi}{T_c} = 2\pi f_c = \frac{|q| B_0}{m}$$

Or,

$$\frac{d\vec{v}_\perp}{dt} = \left(-\frac{q}{m}\vec{B}\right) \times \vec{v}_\perp$$

$$\text{Let } q > 0, \vec{\omega}_c = -\left(\frac{q}{m}\right)\vec{B} = \left(\frac{qB_0}{m}\right)(-\hat{k}) \equiv \omega_c(-\hat{k})$$

$$\begin{cases} \frac{dv_x}{dt} = \omega_c v_y \\ \frac{dv_y}{dt} = -\omega_c v_x \end{cases}$$

$$\Rightarrow \frac{d^2 v_x}{dt^2} + \omega_c^2 v_x = 0$$

$$\begin{cases} v_x(t) = v_\perp \cos \omega_c t \\ v_y(t) = \frac{1}{\omega_c} \frac{dv_x}{dt} = -v_\perp \sin \omega_c t \end{cases}$$

$$\frac{dx}{dt} = v_\perp \cos \omega_c t$$

$$\begin{cases} x(t) = x_0 + \frac{v_\perp}{\omega_c} \sin \omega_c t \\ y(t) = y_0 + \frac{v_\perp}{\omega_c} \cos \omega_c t \end{cases}$$

Circular motion (centered) around (x_0, y_0)
with $R_c = v_\perp / \omega_c = \frac{mv_\perp}{qB}$ (clockwise)

$$\text{Let } \mathcal{L} < 0, \quad \vec{\omega}_c = \frac{|\mathcal{L}| \cdot \vec{B}}{m} = \frac{|\mathcal{L}| B_0}{m} \cdot \hat{k} = \omega_c \hat{k}$$

$$\frac{dv_x}{dt} = -\omega_c v_y$$

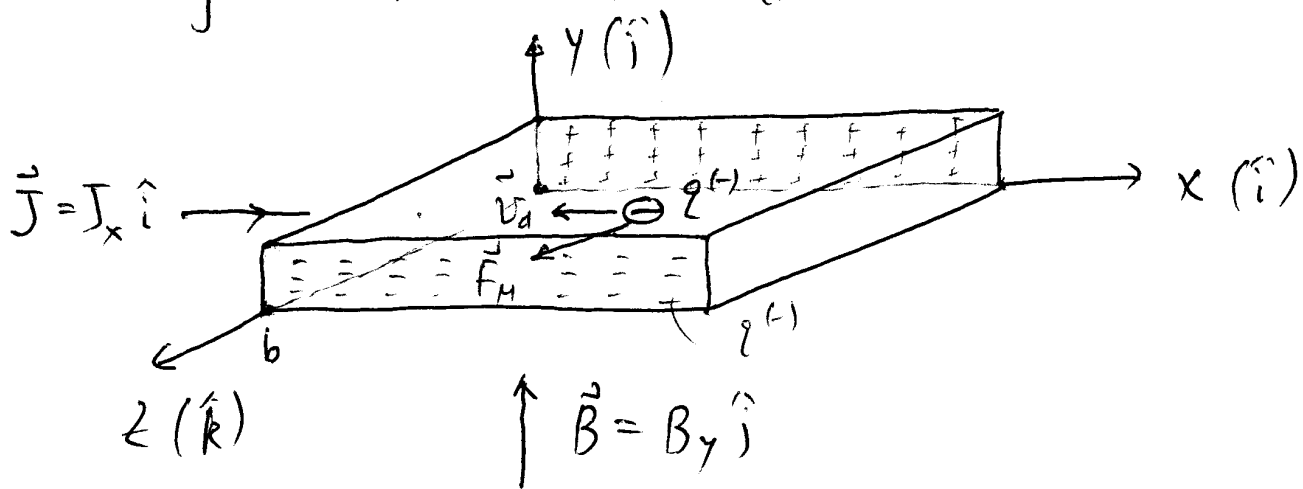
$$\frac{dv_y}{dt} = \omega_c v_x$$

$$\begin{cases} v_x(t) = v_{\perp} \cos \omega_c t \\ v_y(t) = -\frac{1}{\omega_c} \frac{dv_x}{dt} = v_{\perp} \sin \omega_c t \end{cases}$$

$$\begin{cases} x(t) = x_0 + \frac{v_{\perp}}{\omega_c} \sin \omega_c t \\ y(t) = y_0 - \frac{v_{\perp}}{\omega_c} \cos \omega_c t \end{cases}$$

Again circular motion (centered at $\{x_0, y_0\}$) with radius $R_c = v_{\perp} / \omega_c = m v_{\perp} / |\mathcal{L}| B_0$, counter-clockwise, with a constant angular velocity $\omega_c = |\mathcal{L}| B / m$ and thus a constant linear velocity $v = \omega_c R_c = v_{\perp}$.

- Impeded motion of charged particles in a constant magnetic field: Hall effect



Magnetic force on the negative charge carrier $q^{(-)}$

$$\vec{F}_M = q^{(-)} \vec{v}_d^{(-)} \times \vec{B} = |q^{(-)} \vec{v}_d^{(-)}| B_y \hat{k}$$

causing $q^{(-)}$ to pile up at the surface $z=b$, and leaving equal amount of positive charge on the opposite surface, $z=0$. This flow of $q^{(-)}$ stops when the electrostatic force produced by the accumulated charges cancel the magnetic force.

$$\vec{F}_{(on\ q^{(-)})} = q^{(-)} (\vec{E}_H + \vec{v}_d^{(-)} \times \vec{B}) = 0$$

Hall electric field

$$\vec{E}_H = -\vec{v}_d^{(-)} \times \vec{B} = + |\vec{v}_d^{(-)}| B_y \hat{k}$$

Hall voltage

$$V_H = V(z=b) - V(z=0) = -|v_d^{(-)}| \cdot B_y \cdot b < 0$$

Hall coefficient

$$R_H \equiv \frac{E_z}{J_x \cdot B_y} = \frac{+|\vec{v}_d^{(-)}| \cdot B_y}{|q^{(-)}| n^{(-)} \cdot |\vec{v}_d^{(-)}| \cdot B_y} = \frac{(-1)}{q^{(-)} n^{(-)}} > 0$$

If $q^{(+)}$ is the charge carrier, $n^{(+)}$ is the density

$$\vec{F}_H (\text{on } q^{(+)}) = q^{(+)} \vec{v}_d^{(+)} \times \vec{B} = |q^{(+)} \vec{v}_d^{(+)}| \cdot B_y \hat{k},$$

thus piling up $q^{(+)}$ at $z=b$, while leaving negative charge at $z=0$.

Hall electric field. $\vec{E}_H (q^{(+)}) = -|\vec{v}_d^{(+)}| \cdot B_y \cdot \hat{k} = E_z \hat{k}$

Hall voltage: $V_H = V(z=b) - V(z=0) = |\vec{v}_d^{(+)}| \cdot B_y \cdot b > 0$

Hall coefficient: $R_H = \frac{(-1)}{q^{(+)} \cdot n^{(+)}} < 0$

V_H & R_H reveal charge type and charge density n !

• Magnetic force on current-carrying conductors

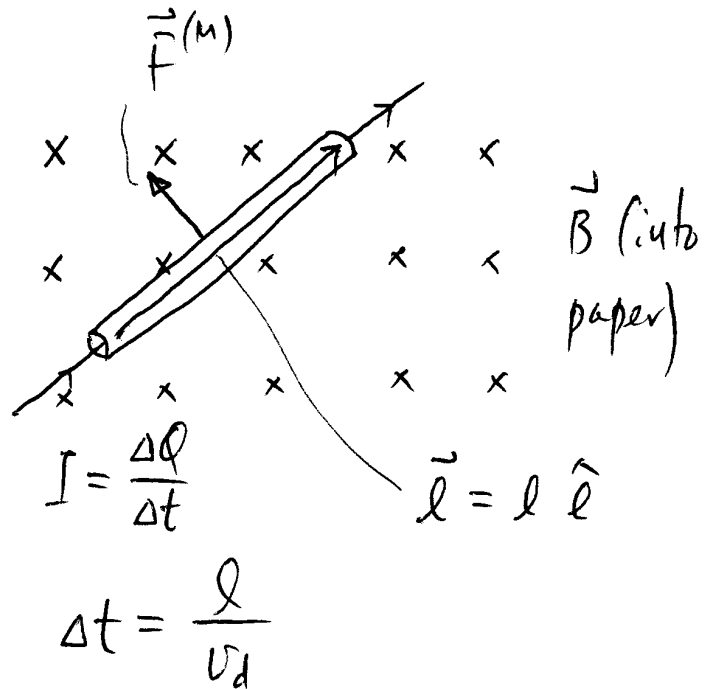
Magnetic force on a straight current-carrying segment (I, \vec{l}) in a uniform magnetic field \vec{B}

$$\vec{F}^{(M)} = \Delta q \vec{v}_d \times \vec{B}$$

If electrons carry the current, $\Delta q^{(+)} < 0$,

$$\vec{v}_d^{(+)} = v_d^{(+)} (-\hat{l})$$

$$I = -\frac{\Delta q^{(+)}}{\Delta t}$$



$$\vec{F}^{(M)} = \Delta q^{(+)} \vec{v}_d^{(+)} \times \vec{B}$$

$$= \left(-\frac{\Delta q^{(+)}}{\Delta t} \right) \left(v_d^{(+)} (-\hat{l}) \cdot \frac{l}{v_d^{(+)}} (-1) \right) \times \vec{B}$$

$$= I \vec{l} \times \vec{B} \quad \#$$

If positive charges carry the current, $\Delta q^{(+)} > 0$, $\vec{v}_d^{(+)} = v_d^{(+)} \hat{l}$

$$I = \frac{\Delta q^{(+)}}{\Delta t}, \text{ thus } \vec{F}^{(M)} = \Delta q^{(+)} \vec{v}_d^{(+)} \times \vec{B} = \left(\frac{\Delta q^{(+)}}{\Delta t} \right) \left(v_d^{(+)} \hat{l} \cdot \frac{l}{v_d^{(+)}} \right) \times \vec{B}$$

$$= I \vec{l} \times \vec{B} \quad \#$$

Generally, regardless what carries the current I ,

$$\vec{F}_{\text{on } \vec{l}}^{(M)} = I \vec{l} \times \vec{B}$$

Magnetic force on a curved current-carrying wire in a non-uniform magnetic field \vec{B}

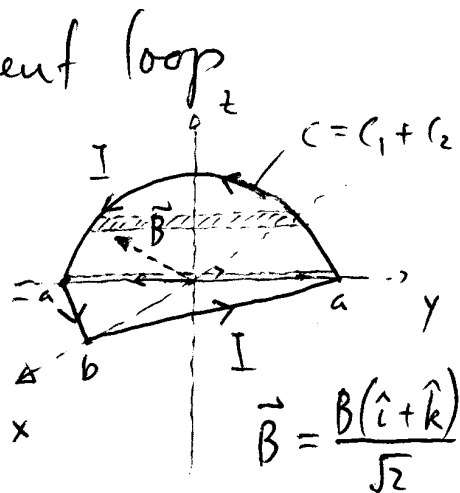
$$d\vec{F}_{\text{on } d\vec{l}}^{(M)} = I d\vec{l} \times \vec{B} \quad (\text{locally straight } d\vec{l} \text{ in a locally uniform } \vec{B})$$

$$\vec{F}^{(M)} = \int d\vec{F}^{(M)} = \int I d\vec{l} \times \vec{B}$$

Example 28-8

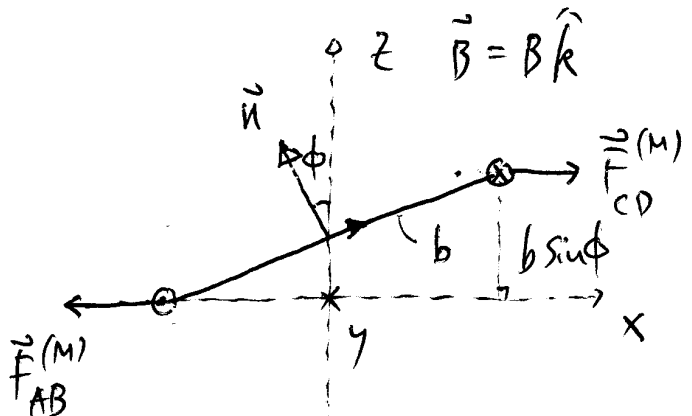
• Magnetic force and torque on a current loop

$$\vec{F}^{(M)} = \oint_C I d\vec{l} \times \vec{B} = \oint_{C_1} + \oint_{C_2}$$



Rectangular current-loop ($a \times b$) in a uniform \vec{B}

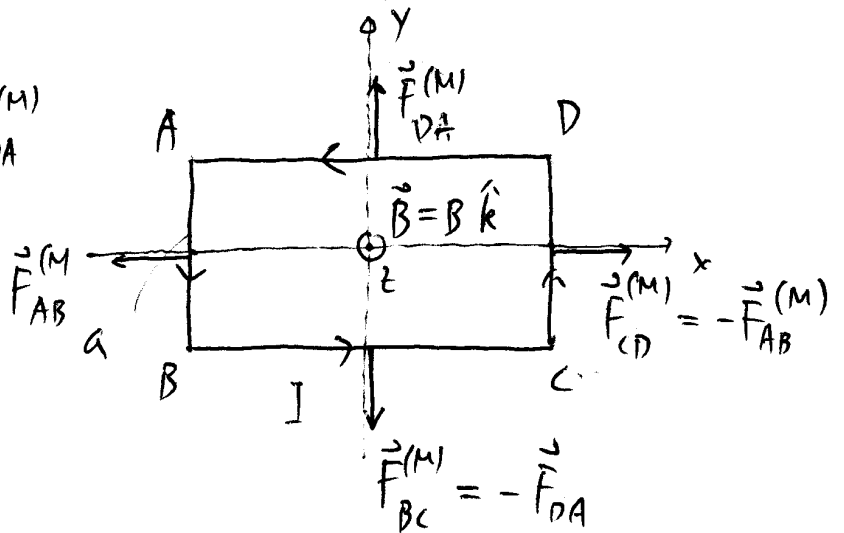
\hat{n} : normal unit vector for the rectangular loop chosen by the right-hand rule



$$\vec{F}^{(M)} = \oint I d\vec{r} \times \vec{B}$$

$$= \vec{F}_{AB}^{(M)} + \vec{F}_{BC}^{(M)} + \vec{F}_{CD}^{(M)} + \vec{F}_{DA}^{(M)}$$

$$= 0$$



Net force on a current loop in a uniform \vec{B} is zero.

(Top-view)

But $\vec{F}_{AB}^{(M)}$ and $\vec{F}_{CD}^{(M)}$ are along two different lines that are apart by $b \sin \phi$, thus exert a torque on the loop

$$|\vec{\tau}| = |\vec{F}_{CD}^{(M)}| \cdot b \cdot \sin \phi = I \cdot a \cdot B \cdot b \cdot \sin \phi = (Iab) \cdot B \cdot \sin \phi$$

along the direction of $\hat{n} \times \vec{B}$. Define magnetic moment $\vec{\mu} = I(ab\hat{n})$

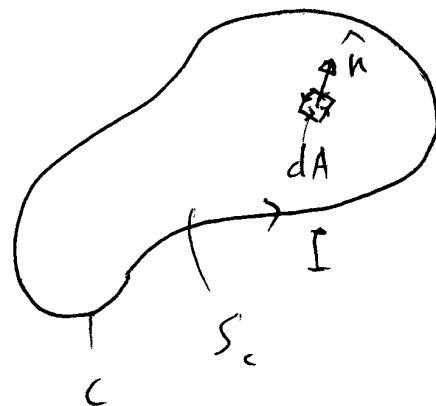
$$\vec{\tau} = \vec{\mu} \times \vec{B} \quad (\text{like } \vec{\tau} = \vec{p} \times \vec{E} \text{ for an electric dipole})$$

An arbitrary current-loop (c) in a uniform \vec{B}

$$\vec{F}^{(M)} = \oint_c I d\vec{l} \times \vec{B} = 0$$

$$\vec{\tau} = \vec{\mu} \times \vec{B}$$

The magnetic dipole moment $\vec{\mu}$ is defined and computed as follows:



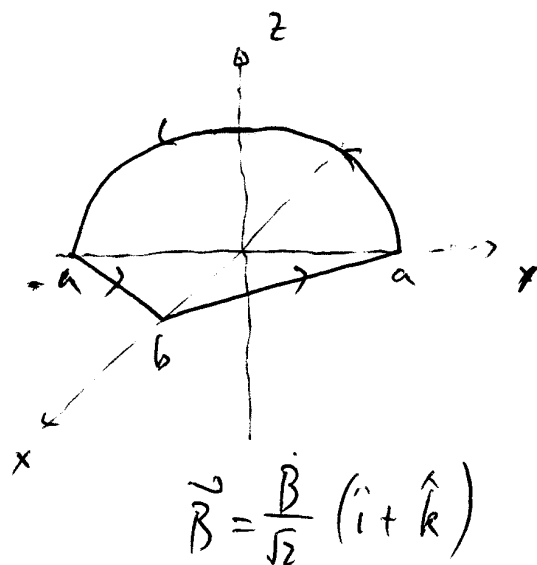
Let S_c be a surface that covers the current loop, and an area element $d\vec{A} = \hat{n} dA$ is chosen by the right-hand rule

$$\vec{\mu} = \iint_{S_c} I d\vec{A} = I \iint_{S_c} d\vec{A} = I \vec{A}$$

Example:

$$\begin{aligned} \vec{\mu} &= I \iint_{S_c} d\vec{A} = I (\vec{A}_1 + \vec{A}_2) \\ &= I \left(\frac{\pi}{2} a^2 \hat{i} + ab \hat{k} \right) \end{aligned}$$

$$\vec{\tau} = \vec{\mu} \times \vec{B} = \frac{IB}{\sqrt{2}} \left(ab - \frac{\pi}{2} a^2 \right) \hat{j}$$



Proof of two equivalent definitions of magnetic dipole moment $\vec{\mu}$

$$\vec{\mu} = I \iint_{S_c} d\vec{A} = I \iint_{S_c} \hat{n} dA \quad \dots (1)$$

$$\vec{\mu} = \frac{I}{2} \oint_c \vec{r} \times d\vec{l} \quad \dots (2)$$

Let \hat{t} be a unit vector, we only need to prove

$$\hat{t} \cdot \iint_{S_c} \hat{n} dA = \hat{t} \cdot \left(\frac{I}{2} \oint_c \vec{r} \times d\vec{l} \right) \quad \dots (3)$$

From the right-hand side

$$\hat{t} \cdot \left(\frac{I}{2} \oint_c \vec{r} \times d\vec{l} \right) = \oint_c \left(\frac{I}{2} \hat{t} \times \vec{r} \right) \cdot d\vec{l}$$

Using the Stokes Theorem,

$$\oint_c \vec{f} \cdot d\vec{l} = \iint_{S_c} (\nabla \times \vec{f}) \cdot d\vec{A}$$

and

$$\begin{aligned}\nabla \times (\hat{t} \times \vec{r}) &= (\vec{r} \cdot \nabla) \hat{t} - (\nabla \cdot \hat{t}) \vec{r} - (\hat{t} \cdot \nabla) \vec{r} \\ &\quad + (\nabla \cdot \vec{r}) \cdot \hat{t} \\ &= 2\hat{t}\end{aligned}$$

thus

$$\begin{aligned}\oint_C (\frac{1}{2} \hat{t} \times \vec{r}) \cdot d\vec{l} &= \frac{1}{2} \iint_{S_C} \nabla \times (\hat{t} \times \vec{r}) \cdot d\vec{A} \\ &= \iint_{S_C} \hat{t} \cdot d\vec{A} \\ &= \hat{t} \cdot \iint_{S_C} d\vec{A}\end{aligned}$$

Thus (3) is valid. Thus (b) = (2)

General proof of $\vec{\tau} = \vec{\mu} \times \vec{B}$ for
an arbitrary current loop in
a constant magnetic field \vec{B}

$$\vec{\mu} = I \int_{S_c} d\vec{A} = \int_{S_c} \hat{n} dA \cdot I$$

By definition,

$$\begin{aligned} \vec{\tau} &= \oint_C \vec{r} \times (I d\vec{\ell} \times \vec{B}) \\ &= \oint_C I d\vec{\ell} (\vec{r} \cdot \vec{B}) - \oint_C I \vec{B} (\vec{r} \cdot d\vec{\ell}) \end{aligned}$$

But $\vec{r} \cdot d\vec{\ell} = \frac{1}{2} d(r^2)$, thus

$$\oint_C I \vec{B} (\vec{r} \cdot d\vec{\ell}) = I \vec{B} \oint_C d\left(\frac{r^2}{2}\right) = 0$$

$$\therefore \vec{\tau} = \oint_C I d\vec{\ell} (\vec{r} \cdot \vec{B})$$

Using $\oint_C \psi d\vec{\ell} = \int_{S_c} d\vec{A} \times (\nabla \psi)$ and $\psi \equiv \vec{r} \cdot \vec{B}$

and $\nabla(\vec{a} \cdot \vec{b}) = (\vec{a} \cdot \nabla)\vec{b} + (\vec{b} \cdot \nabla)\vec{a} + \vec{a} \times (\nabla \times \vec{b}) + \vec{b} \times (\nabla \times \vec{a})$

Now

$$\begin{aligned}\nabla(\vec{r} \cdot \vec{B}) &= (\vec{r} \cdot \nabla)\vec{B} + (\vec{B} \cdot \nabla)\vec{r} + \vec{r} \times (\nabla \times \vec{B}) \\ &\quad + \vec{B} \times (\nabla \times \vec{r}) \\ &= \vec{B}\end{aligned}$$

thus

$$\vec{C} = \oint_c I d\vec{l}(\vec{r} \cdot \vec{B})$$

$$= I \iint d\vec{A} \times (\nabla(\vec{r} \cdot \vec{B}))$$

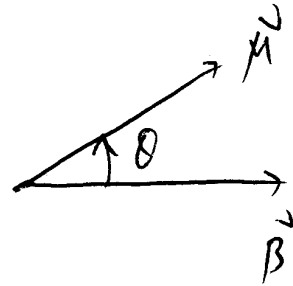
$$= \iint I d\vec{A} \times \vec{B}$$

$$= \vec{\mu} \times \vec{B} \quad \#$$

Potential energy of a magnetic moment $\vec{\mu}$ in a uniform magnetic field

$$U^{(m)} = -\vec{\mu} \cdot \vec{B} \quad (\text{like } U^{(e)} = -\vec{p} \cdot \vec{E})$$

$$U^{(m)}(\theta) - U^{(m)}(0) = \int_0^\theta \mu B \sin \theta \, d\theta = \mu B (1 - \cos \theta)$$

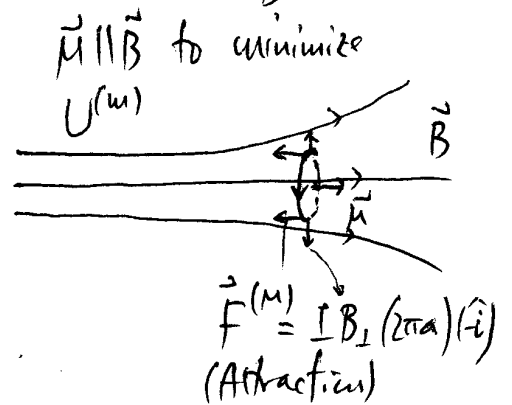
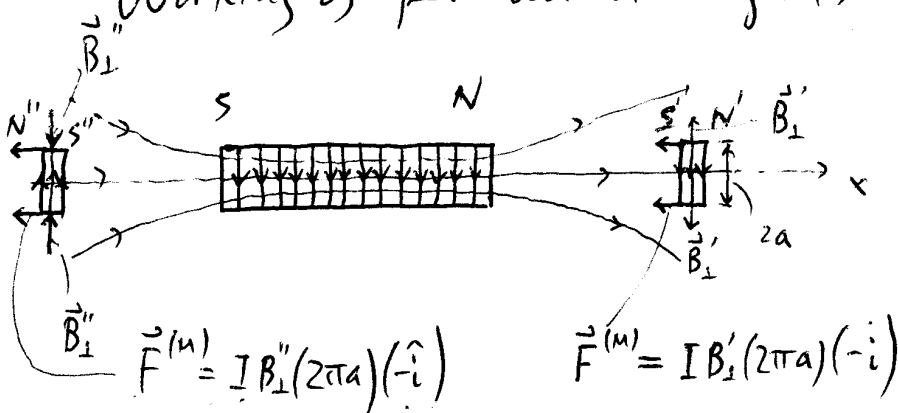


Example 28-9

Example 28-10

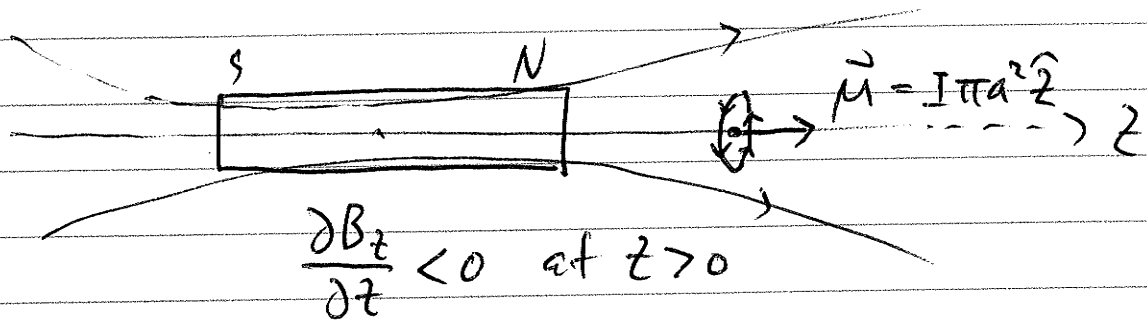
Magnetic dipoles in non-uniform magnetic fields \vec{B}

Working of permanent magnets and "induced" magnets



Equivalence of magnetic force of a non-uniform magnetic field \vec{B} on a magnetic dipole moment $\vec{\mu} = I\vec{A}$

Method #1: Potential energy approach

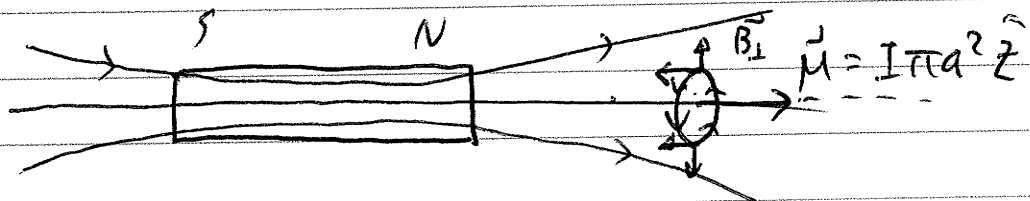


$$U^{(m)} = -\vec{\mu} \cdot \vec{B} = -\pi a^2 I B(z)$$

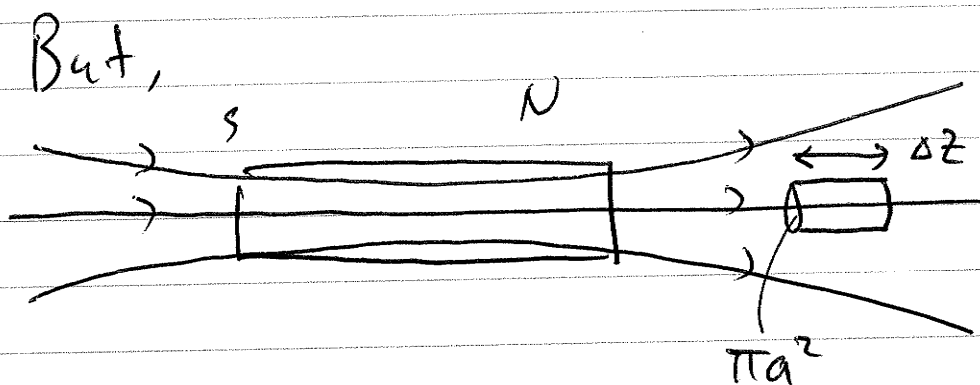
$$\vec{F}^{(m)} = -\nabla U^{(m)} = +\hat{z} \frac{\partial}{\partial z} (\pi a^2 I B(z))$$

$$= I \pi a^2 \left(\frac{\partial B}{\partial z} \right) \hat{z} = -I \pi a^2 \left| \frac{\partial B}{\partial z} \right| \hat{z}$$

Method #2: Lorentz force by \vec{B}_\perp



$$\vec{F}^{(m)} = \oint I d\vec{\ell} \times \vec{B} = \oint I d\vec{\ell} \times \vec{B}_\perp = -2\pi a I |B_\perp| \hat{z}$$



$$\oint_{\text{Cylinder}} \vec{B} \cdot d\vec{A} = 0 = \pi a^2 (B_z(z + \Delta z) - B_z(z)) + 2\pi a \Delta z B_{\perp}(z)$$

Thus

$$-\frac{\partial B}{\partial z} = \frac{2}{a} B_{\perp}(z)$$

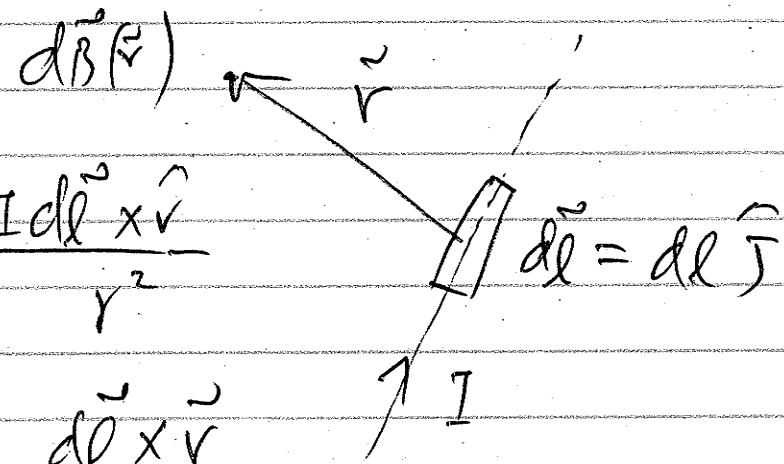
or

$$\left| \frac{\partial B}{\partial z} \right| = \frac{2}{a} |B_{\perp}(z)|$$

As a result, the two methods yield the same result, but from two "reversing" angles.

Chapt. 18.

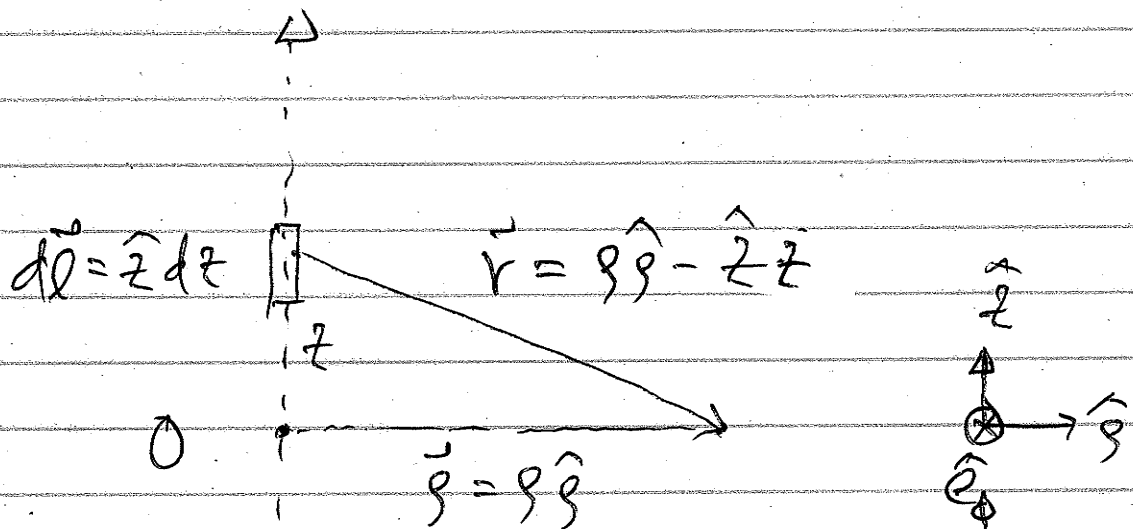
Calculation of \vec{B} field from current-carrying wire



$$d\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \frac{I d\vec{l} \times \hat{r}}{r^2}$$

$$= \frac{\mu_0 I}{4\pi} \frac{d\vec{l} \times \vec{r}}{r^3}$$

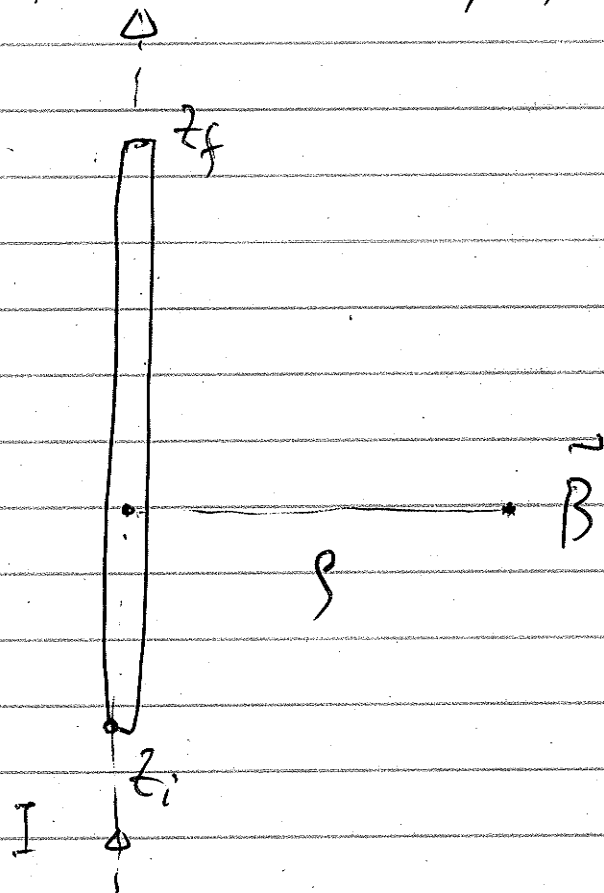
Choose $\hat{j} \parallel d\vec{l}$ along positive z-axis.



$$d\vec{B}(\vec{r}) = \frac{\mu_0 I}{4\pi} \frac{(dz \hat{z}) \times (\rho \hat{j} - z \hat{k})}{r^3}$$

$$= \frac{\mu_0 I}{4\pi} \frac{\rho \cdot dz}{(z^2 + \rho^2)^{3/2}} \hat{e}_\phi$$

$\vec{B}(\rho)$ from a finite straight segment of current-carrying wire



$$\vec{B}(\rho) = \int_{z_i}^{z_f} d\vec{B} = \frac{\mu_0 I \rho}{4\pi} \hat{e}_\phi \int_{z_i}^{z_f} \frac{dz}{(\rho^2 + z^2)^{3/2}}$$

$$= \frac{\mu_0 I}{4\pi \rho} \hat{e}_\phi \left(\frac{z_f}{\sqrt{z_f^2 + \rho^2}} - \frac{z_i}{\sqrt{z_i^2 + \rho^2}} \right)$$

Special cases: Infinitely long straight wire ($z_f = +\infty, z_d = -\infty$)

$$\vec{B}(\rho) \Big|_{\text{infinite}} = \frac{\mu_0 I}{2\pi \rho} \hat{e}_\phi$$

Ampere's law

$$\oint_c \vec{B} \cdot d\vec{e} = \oint_c \vec{B} \cdot (\hat{z} dz + \hat{s} d\rho + \rho d\phi \hat{e}_\phi)$$

$$= \frac{\mu_0 I}{2\pi} \oint_c \left(\frac{1}{\rho}\right) (\rho d\phi)$$

$$= \mu_0 I$$

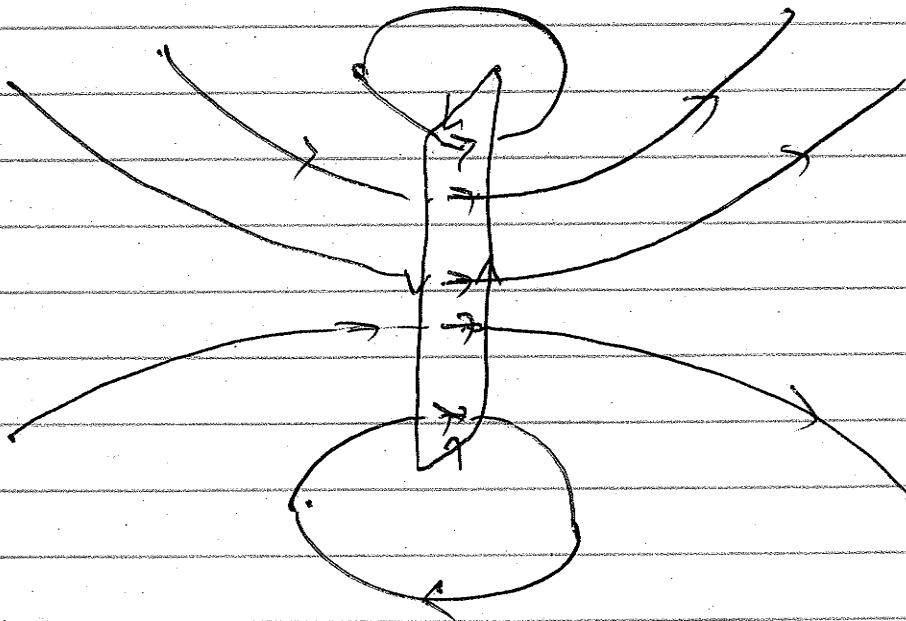
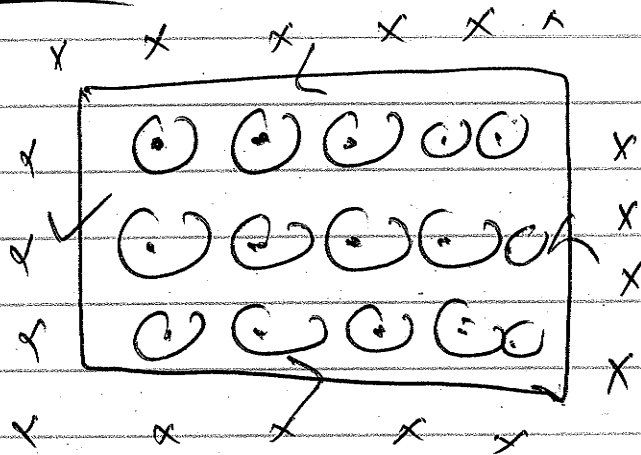
$$= \iint_{S_c} \mu_0 \vec{J} \cdot d\vec{A}$$

$$= \mu_0 \iint_{S_c} \vec{J} \cdot d\vec{A}$$

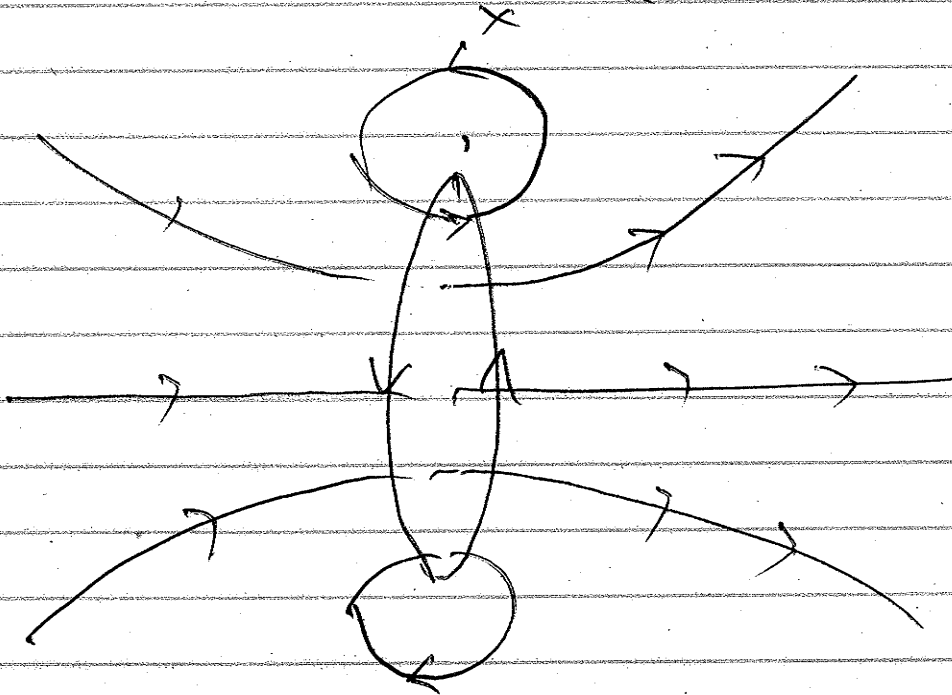
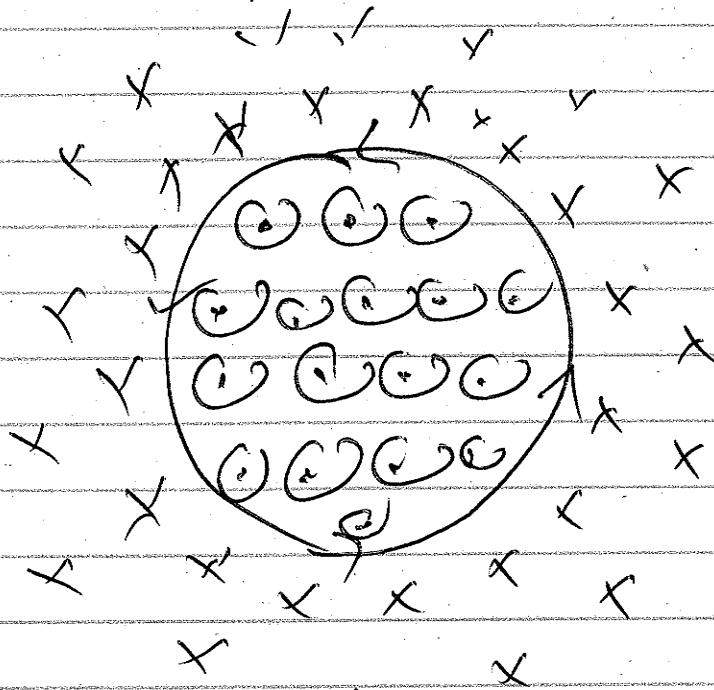
$$\oint_c \vec{B} \cdot d\vec{e} = \mu_0 I \Big|_{\text{through } c} = \mu_0 \iint_{S_c} \vec{J} \cdot d\vec{A} \Big|_{\text{current through } S_c}$$

Superposition of \vec{B} from multiple
straight current carrying
segments

Example #1



Example #2



Example #3

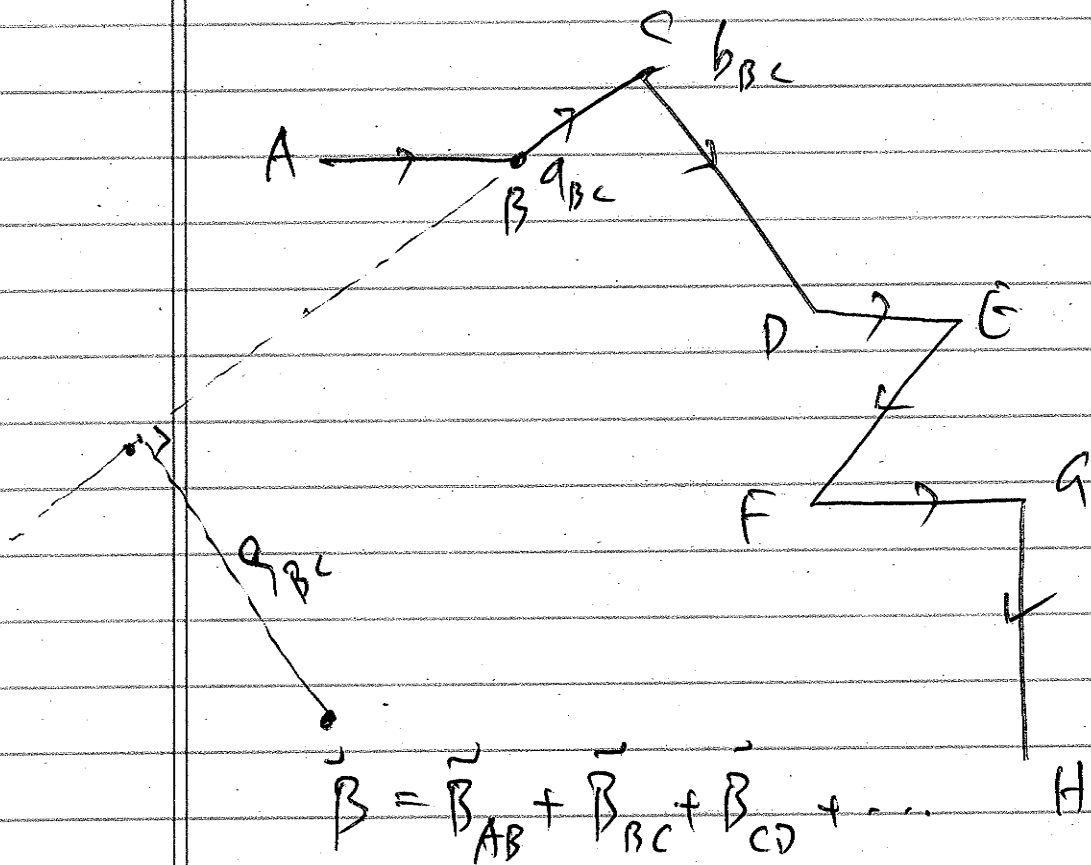
1)
$$\vec{B}(\rho) = \hat{e}_\phi \frac{\mu_0 I}{4\pi \rho} \left(\frac{b}{\sqrt{b^2 + \rho^2}} - \frac{(-a)}{\sqrt{a^2 + \rho^2}} \right)$$

$$= \hat{e}_\phi \frac{\mu_0 I}{4\pi \rho} \left(\frac{b}{\sqrt{b^2 + \rho^2}} + \frac{a}{\sqrt{a^2 + \rho^2}} \right)$$

2)
$$\vec{B}(\rho) = \hat{e}_\phi \frac{\mu_0 I}{4\pi \rho} \left(\frac{b}{\sqrt{b^2 + \rho^2}} - \frac{a}{\sqrt{a^2 + \rho^2}} \right)$$

3)
$$\vec{B}(\rho) = \hat{e}_\phi \frac{\mu_0 I}{4\pi \rho} \left(\frac{-b}{\sqrt{b^2 + \rho^2}} - \frac{-a}{\sqrt{a^2 + \rho^2}} \right)$$

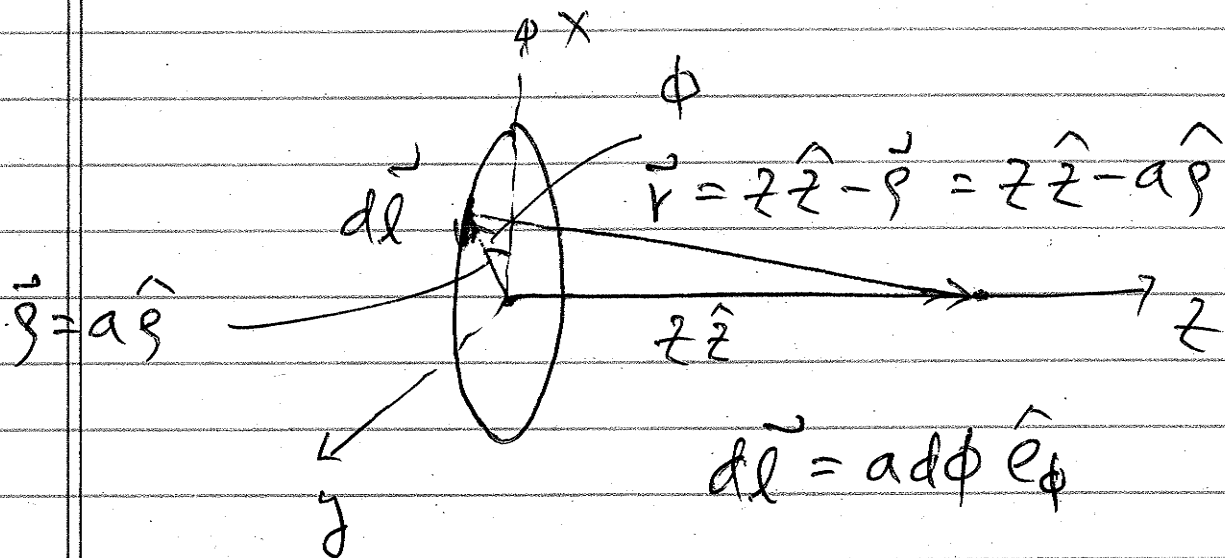
Superposition of \vec{B} from multiple straight segments



$$\vec{B}_{BC} = \hat{e}_{\phi, BC} \cdot \frac{\mu_0 I}{4\pi r_{BC}} \cdot \left(\frac{b_{BC}}{\sqrt{b_{BC}^2 + r_{BC}^2}} - \frac{a_{BC}}{\sqrt{a_{BC}^2 + r_{BC}^2}} \right)$$

etc.

$\vec{B}(z)$ on the axis of a circular current loop



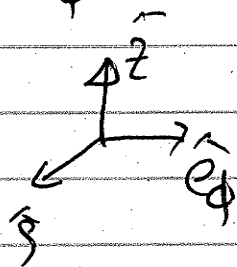
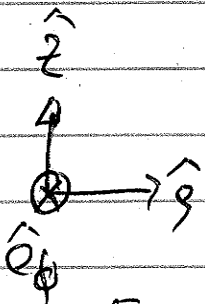
$$d\vec{B} \Big|_{d\vec{l}} = \frac{\mu_0 I}{4\pi} \frac{d\vec{l} \times (z\hat{z} - a\hat{\phi})}{(a^2 + z^2)^{3/2}}$$

$$= \frac{\mu_0 I \cdot d\phi}{4\pi \cdot (a^2 + z^2)^{3/2}} (az\hat{\rho} + a^2\hat{z})$$

$$\oint \hat{\rho} d\phi = 0 ;$$

$$\vec{B} = \oint d\vec{B} = \frac{\mu_0 I \cdot a^2}{2(a^2 + z^2)^{3/2}} \hat{z}$$

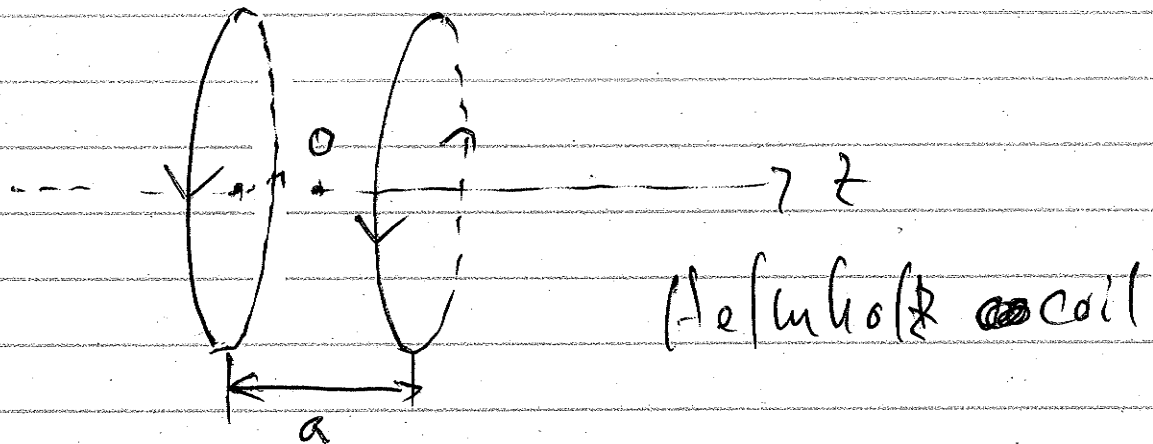
$$\vec{B}(z) = \hat{z} \cdot \frac{\mu_0 I \cdot a^2}{2 \cdot (a^2 + z^2)^{3/2}}$$



$$\hat{e}_\phi \times \hat{z} = \hat{\rho}$$

$$\hat{e}_\phi \times \hat{\rho} = -\hat{z}$$

Production of uniform magnetic field along z-axis with a pair of circular current loops



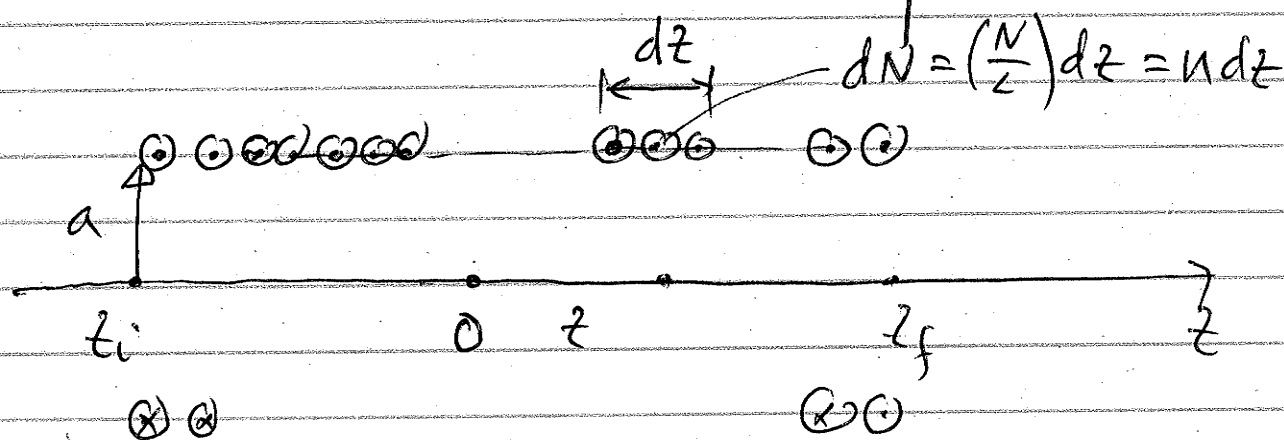
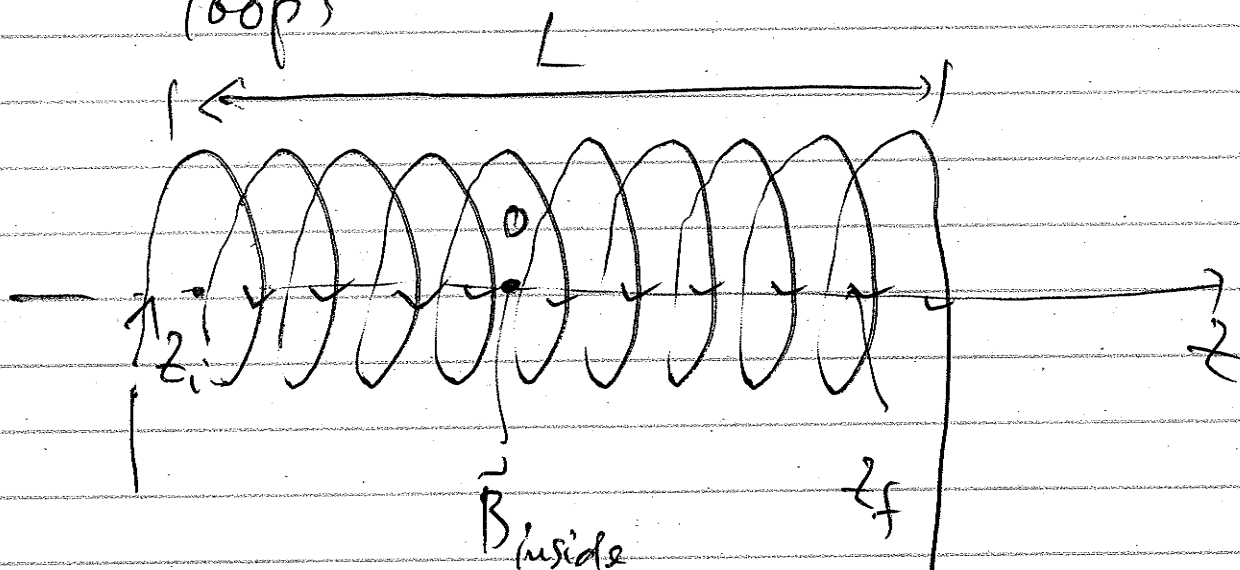
$$\vec{B}(z) = \hat{z} \frac{\mu_0 I a^2}{z} \left[\frac{1}{(a^2 + (z + a/2)^2)^{3/2}} + \frac{1}{(a^2 + (z - a/2)^2)^{3/2}} \right]$$

Helmholtz coils

$$\frac{dB}{dz} @ z=0 = 0$$

$$\frac{d^2B}{dz^2} @ z=0 = 0$$

$\vec{B}(z)$ along the axis of a regular array of circular current carrying loops



$$d\vec{B} = \hat{z} \frac{\mu_0 I dN \cdot a^2}{z^2} \frac{1}{(a^2 + z^2)^{3/2}}$$

$$\vec{B} = \hat{z} \frac{\mu_0 I \cdot n}{z} a^2 \int_{z_i}^{z_f} \frac{dz}{(a^2 + z^2)^{3/2}}$$

$$= \hat{z} \frac{\mu_0 I n}{z} \left(\frac{z_f}{\sqrt{a^2 + z_f^2}} - \frac{z_i}{\sqrt{a^2 + z_i^2}} \right)$$

Deep inside a long solenoid so that
 $z_f \rightarrow +\infty, z_i \rightarrow -\infty$

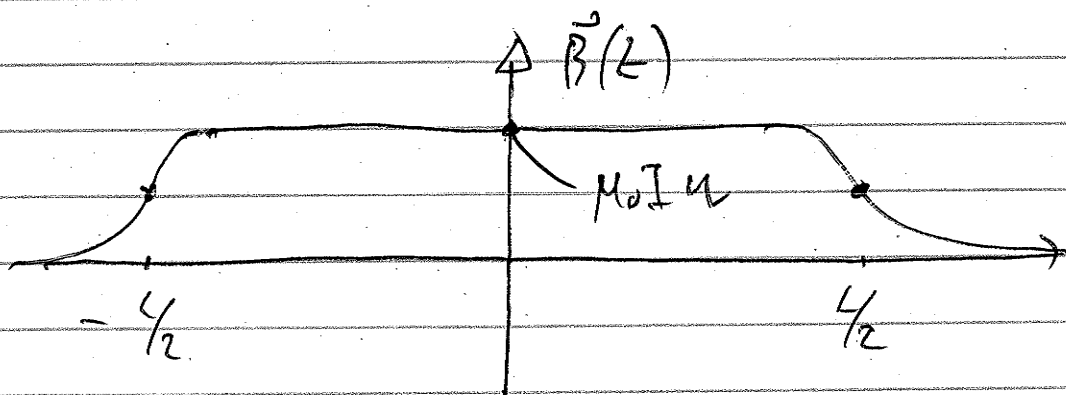
$$\vec{B}_{\text{inside}} = \hat{z} \mu_0 I n = \hat{z} \mu_0 I \left(\frac{N}{L} \right)$$

At either end of a long solenoid,
either $z_f \rightarrow +\infty, z_i = 0$; or $z_f = 0, z_i \rightarrow -\infty$,

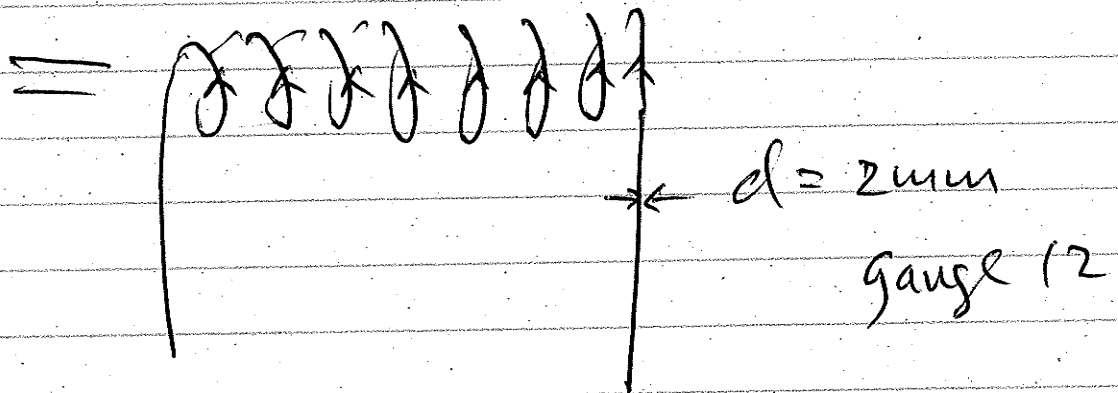
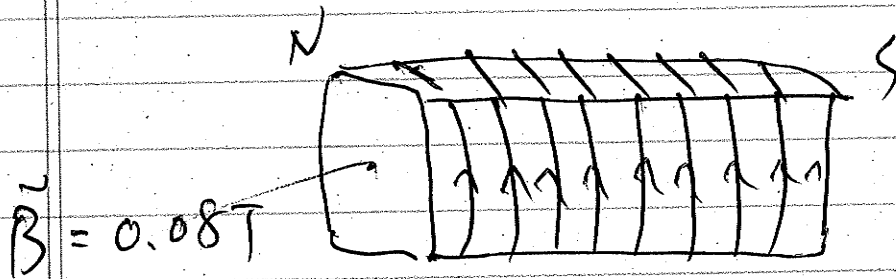
$$\vec{B}_{\text{end}} = \hat{z} \frac{1}{2} \mu_0 I n = \frac{1}{2} \vec{B}_{\text{inside}}$$

Beyond the ends of a long solenoid

$$\vec{B}(z)_{\text{outside}} \sim \hat{z} \frac{\mu_0 I n}{2} \cdot \frac{a^2}{z^2} \rightarrow 0$$



Rectangular permanent magnet



$$\frac{N}{l} = \frac{(l/d)}{l} = \frac{1}{d} = 500 \text{ m}^{-1}$$

$$|\vec{B}|_{\text{edge}} = \frac{1}{2} \mu_0 I \left(\frac{N}{l} \right) = 0.08 \text{ T}$$

$$\therefore I_{\text{equivalent}} = \frac{2 |\vec{B}|_{\text{edge}}}{\mu_0 (N/l)} \approx 280 \text{ Amp!!!}$$

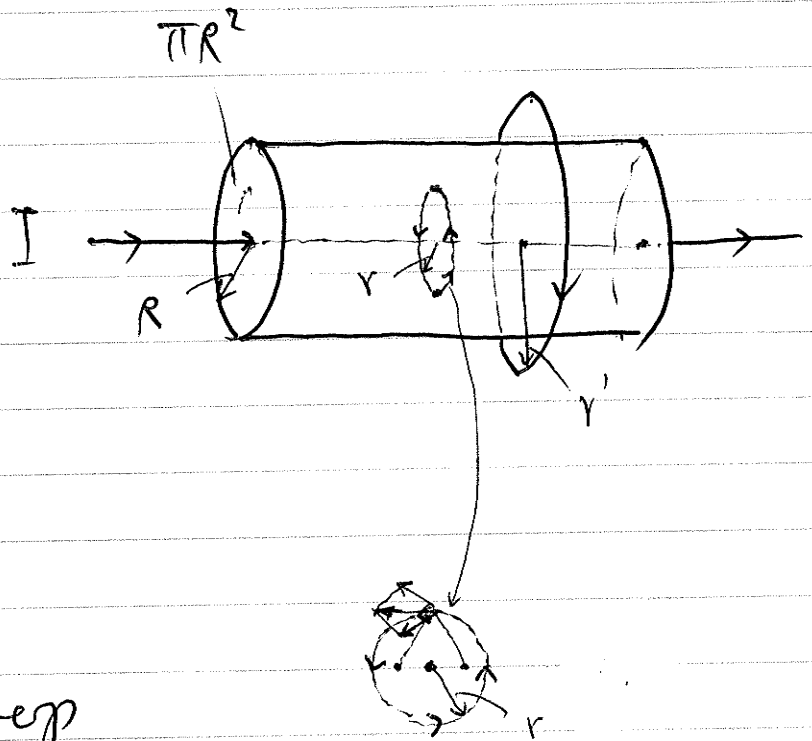
Maximum current rating of 12 gauge wire = 43 Amp.

If $d = 1 \text{ mm}$, $I_{\text{equivalent}} = 140 \text{ Amp}$ (Max = 16 Amp)

- Magnetic field inside and outside a current-carrying cylindrical wire with a uniform current density

By symmetry, there can be no axial component of \vec{B} (inside/outside)

Also by symmetry, there can be no radial component of \vec{B} (inside/outside)



Along the smaller loop (inside)

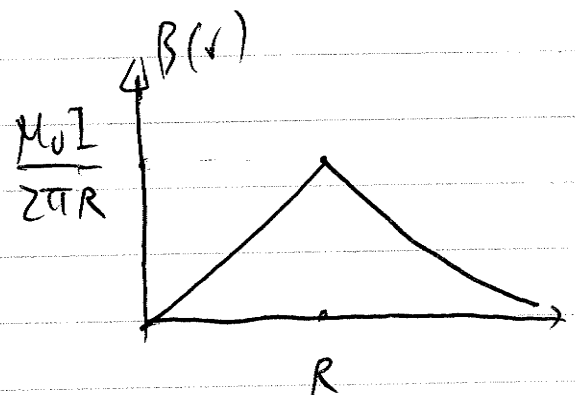
$$\oint_{C'} \vec{B} \cdot d\vec{\ell} = B(r) \cdot 2\pi r = \mu_0 \left(\frac{\pi r^2}{\pi R^2} \right) \cdot I$$

$$B(r) \Big|_{r < R} = \frac{\mu_0 I}{2\pi R^2} r$$

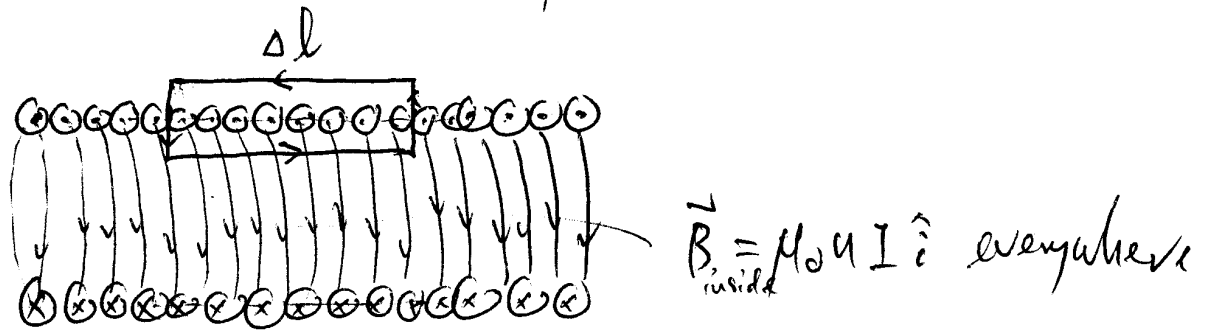
Along the bigger loop,

$$\oint_{C'} \vec{B} \cdot d\vec{\ell} = B(r') \cdot 2\pi r' = \mu_0 I$$

$$B(r' > R) = \frac{\mu_0 I}{2\pi} \frac{1}{r'}$$



- Magnetic field outside a solenoid or a bar of magnet with S- and N-poles at the ends



$$\oint_C \vec{B} \cdot d\vec{\ell} = \Delta l (B_{\text{inside}} - B_{\text{outside}} \hat{i})$$

$$= \mu_0 \Delta l n I$$

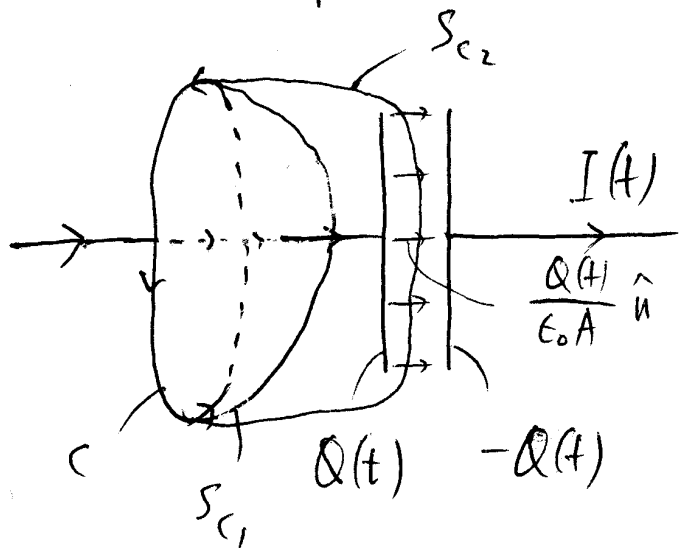
But $B_{\text{inside}} = \mu_0 n I \Rightarrow \boxed{B_{\text{outside}} \hat{i} = 0}$

- Displacement current I_D and Ampere's law:

$$\oint_C \vec{B} \cdot d\vec{\ell} = \iint_{S_{c1}} \mu_0 \vec{J} \cdot d\vec{A}$$

$$= \iint_{S_{c2}} \mu_0 \vec{J} \cdot d\vec{A}$$

But no \vec{J} through S_{c2} !!



Maxwell added another current to fix this mathematical inconvenience.

$$\vec{J}_D = \epsilon_0 \frac{d\vec{E}}{dt} \quad \text{or} \quad \kappa \epsilon_0 \frac{d\vec{E}}{dt} \quad (\text{in dielectric})$$

$$I_D = \iint_{S_c} \vec{J}_D \cdot d\vec{A} = \kappa \epsilon_0 \frac{d}{dt} \underbrace{\iint_{S_c} \vec{E} \cdot d\vec{A}}_{\phi_E}$$

Inside capacitor, $\vec{J} = 0$, but $\vec{J}_D = \epsilon_0 \frac{d}{dt} \vec{E}$,

$$I_D = \iint_{S_c} \vec{J}_D \cdot d\vec{A} = \iint_{S_c} \epsilon_0 \frac{d}{dt} \left(\frac{Q}{\epsilon_0 A} \hat{u} \right) \cdot \hat{u} dA = \frac{dQ}{dt}$$

So, generally

$$\oint_c \vec{B} \cdot d\vec{\ell} = \mu_0 (I_{\text{free}} + I_D)_{\text{encl.}}$$

Derivation of Ampere's law and Maxwell's
Displacement current from
Biot-Savart law

$$\vec{B}(\vec{r}) = \left(\frac{\mu_0}{4\pi}\right) \iiint d\vec{r}' \vec{j}' \times \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3}$$

(Biot-Savart law)

Now,

$$\begin{aligned} \oint_C \vec{B} \cdot d\vec{\ell} &= \iint_{S_C} (\nabla \times \vec{B}) \cdot d\vec{s} \\ &= \left(\frac{\mu_0}{4\pi}\right) \iint_{S_C} d\vec{s} \cdot \iiint d\vec{r}' \nabla \times \left(\vec{j}' \times \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right) \\ &= \left(\frac{\mu_0}{4\pi}\right) \cdot \iint_{S_C} d\vec{s} \cdot \iiint d\vec{r}' \nabla \times \left(\nabla \frac{1}{|\vec{r} - \vec{r}'|} \times \vec{j}' \right) \end{aligned}$$

from $\nabla \times (\vec{a} \times \vec{b}) = \vec{a} (\nabla \cdot \vec{b}) - \vec{b} (\nabla \cdot \vec{a}) + (\vec{b} \cdot \nabla) \vec{a} - (\vec{a} \cdot \nabla) \vec{b}$

$$\nabla \times \left(\nabla \frac{1}{|\vec{r} - \vec{r}'|} \times \vec{j}' \right) = -\vec{j}' \nabla^2 \left(\frac{1}{|\vec{r} - \vec{r}'|} \right) + (\vec{j}' \cdot \nabla) \nabla \frac{1}{|\vec{r} - \vec{r}'|}$$

(∇ only acts on \vec{r} , not on \vec{r}').

Integrate the second term by part and assuming that \vec{j}' vanishes at infinity

$$\begin{aligned}
 & \iiint d\vec{r}' (\vec{j}' \cdot \nabla) \nabla \frac{1}{|\vec{r} - \vec{r}'|} \\
 &= \nabla \iiint d\vec{r}' (\vec{j}' \cdot \nabla) \frac{1}{|\vec{r} - \vec{r}'|} \\
 &= -\nabla \iiint d\vec{r}' (\vec{j}' \cdot \nabla') \frac{1}{|\vec{r} - \vec{r}'|} \quad (\nabla' \text{ acts on } \vec{r}' \text{ only}) \\
 &= \nabla \iiint d\vec{r}' \frac{\nabla' \cdot \vec{j}'}{|\vec{r} - \vec{r}'|}
 \end{aligned}$$

From the charge conservation

$$\nabla' \cdot \vec{j}' + \frac{\partial \rho_f'}{\partial t} = 0$$

We have

$$\begin{aligned}
 & \iiint d\vec{r}' (\vec{j}' \cdot \nabla) \nabla \frac{1}{|\vec{r} - \vec{r}'|} = \frac{d}{dt} \left(-\nabla \iiint d\vec{r}' \frac{\rho_f'}{|\vec{r} - \vec{r}'|} \right) \\
 &= (4\pi\epsilon_0) \frac{d}{dt} \vec{D}
 \end{aligned}$$

Finally

$$\oint_C \vec{B} \cdot d\vec{\ell} = \left(\frac{\mu_0}{4\pi} \right) \left\{ \iint_{S_c} d\vec{s} \cdot \vec{j} - \iiint d\vec{v}' \cdot \vec{j}' \nabla^2 \left(\frac{1}{|\vec{r}-\vec{r}'|} \right) + 4\pi\epsilon_0 \frac{d\vec{D}}{dt} \right\}$$

$$-\nabla^2 \frac{1}{|\vec{r}-\vec{r}'|} = 4\pi \delta(\vec{r}-\vec{r}')$$

so

$$\oint_C \vec{B} \cdot d\vec{\ell} = \mu_0 \iint_{S_c} d\vec{s} \cdot \vec{j} + \mu_0 \epsilon_0 \frac{d}{dt} \iint_{S_c} \vec{D} \cdot d\vec{s}$$

or

$$\oint_C \vec{B} \cdot d\vec{\ell} = \mu_0 I + \mu_0 \epsilon_0 \frac{d}{dt} \iint_{S_c} \vec{D} \cdot d\vec{s}$$

In differential equation form,

$$\nabla \times \vec{B} = \mu_0 \vec{j} + \mu_0 \epsilon_0 \frac{\partial \vec{D}}{\partial t}$$

✱

Proof that $\nabla \cdot \vec{B} = 0$

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \iiint d\sigma' \vec{J}(\vec{r}') \times \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3}$$

$$\nabla \cdot \vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \iiint d\sigma' \nabla \cdot \left(\vec{J}(\vec{r}') \times \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right)$$

Since $\nabla \cdot (\vec{a} \times \vec{b}) = \vec{b} \cdot (\nabla \times \vec{a}) - \vec{a} \cdot (\nabla \times \vec{b})$
and ∇ only acts on \vec{r} , then

$$\begin{aligned} & \nabla \cdot \left(\vec{J}(\vec{r}') \times \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right) \\ &= - \vec{J}(\vec{r}') \cdot \left(\nabla \times \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right) \end{aligned}$$

Since $\nabla \times (\psi \vec{a}) = \nabla \psi \times \vec{a} + \psi \nabla \times \vec{a}$, with

$$\psi = \frac{1}{|\vec{r} - \vec{r}'|^3}, \quad \vec{a} = \vec{r} - \vec{r}'$$

$$\begin{aligned} \nabla \times (\psi \vec{a}) &= \nabla \left(\frac{1}{|\vec{r} - \vec{r}'|^3} \right) \times (\vec{r} - \vec{r}') + \frac{1}{|\vec{r} - \vec{r}'|^3} (\nabla \times (\vec{r} - \vec{r}')) \\ &= 0 \end{aligned}$$

Thus

$$\nabla \cdot \vec{B} = 0$$

This can also show classically as follows:

Since each current segment $dv' \vec{j}(\vec{r}')$ produces ~~the~~ circulating magnetic fields about $\vec{j}(\vec{r}')$, these magnetic flux either never cut through a closed surface, or exit as many times through a closed surface as enter. So the net flux through a close surface is zero.

By the principle of superposition, the magnetic field (flux) as described by

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \iiint dv' \vec{j}(\vec{r}') \times \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3}$$

through a close surface is always zero.

$$\oint_S \vec{B} \cdot d\vec{A} = 0$$

Chapt. 29

- Magnetic induction (Faraday's law) (Week 10)

$$\left\{ \begin{array}{l} \oint \vec{E} \cdot d\vec{A} = \frac{Q_{in}}{\epsilon_0} \\ \oint \vec{E} \cdot d\vec{l} = 0 \Rightarrow -\frac{d}{dt} \int \vec{B} \cdot d\vec{A} \quad (\text{Faraday's law}) \\ \oint \vec{B} \cdot d\vec{A} = 0 \\ \oint \vec{B} \cdot d\vec{l} = \mu_0 I + \kappa \mu_0 \epsilon_0 \frac{d}{dt} \int \vec{E} \cdot d\vec{A} \end{array} \right.$$

$$\frac{1}{c^2} \Rightarrow \frac{\kappa}{c^2} = \frac{1}{v^2}$$

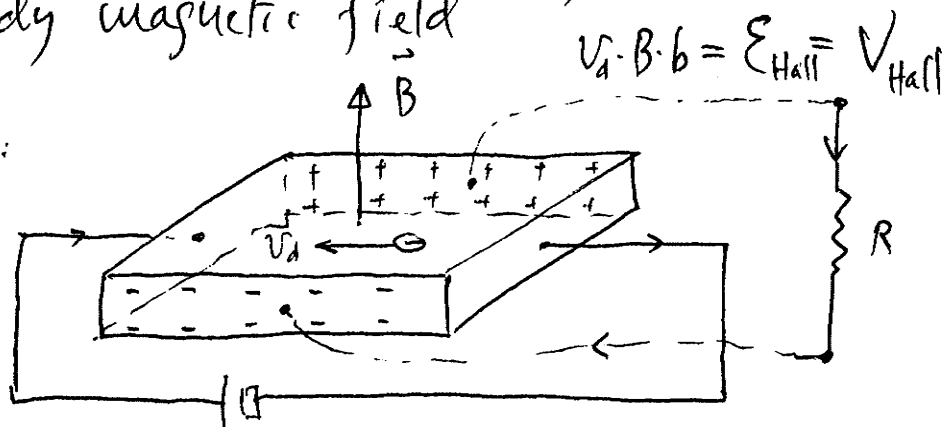
$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$$

$$v = \frac{c}{n} = \frac{c}{\sqrt{\kappa}}$$

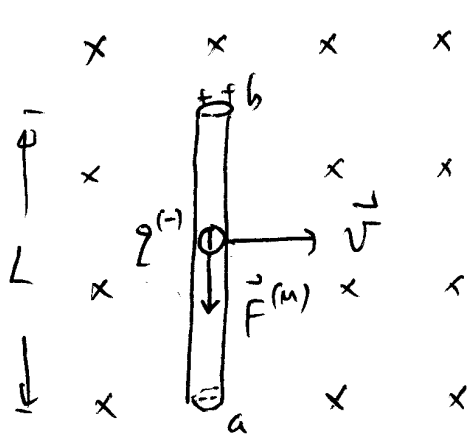
- Electromotive forces produced by moving charges in a steady magnetic field

Hall Effect:

(Special case of motem-emf)



Moving conducting rod in a uniform magnetic field



\vec{B} (into the board)

$$\mathcal{E} = \int_a^b \frac{\vec{F}^{(M)}(\text{on } q^{(-)})}{q^{(-)}} \cdot d\vec{\ell}$$

$$d\vec{\ell} \parallel \vec{v} \times \vec{B}$$

$$= \int_a^b \frac{q^{(-)}(\vec{v} \times \vec{B}) \cdot d\vec{\ell}}{q^{(-)}}$$

$$= v \cdot B \cdot L$$

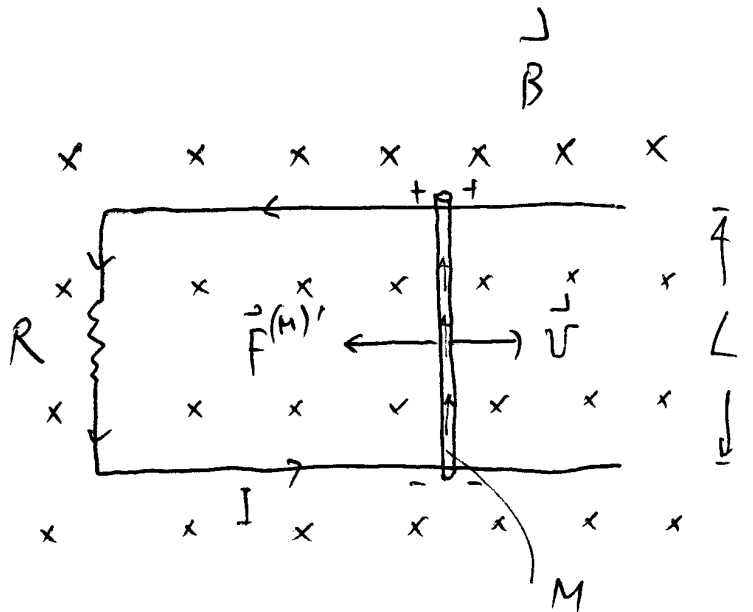
$$\boxed{\mathcal{E}_{\text{em}} = v \cdot B \cdot L}$$

Example 30-7

A rod slides frictionlessly to right with a velocity \vec{v}

$$\mathcal{E} = v \cdot B \cdot L$$

$$I = \frac{\mathcal{E}}{R} = \frac{vBL}{R}$$



Additional magnetic force on the rod

$$\vec{F}^{(M)'} = I \vec{L} \times \vec{B}$$

decelerates the rod so that

$$M \frac{dv}{dt} = -ILB = -\frac{B^2 L^2}{R} v$$

$$v(t) = v_0 e^{-(B^2 L^2 / MR) \cdot t} = v_0 e^{-t/\tau_c}$$

With $B = 0.2 \text{ T}$, $L = 0.1 \text{ m}$, $M = 0.01 \text{ kg}$, $R = 0.1 \Omega$

$$\tau_c = \frac{MR}{(BL)^2} = \frac{0.01 \times 0.1}{(0.2)^2 (0.1)^2} = 2.5 \text{ s.}$$

Power dissipation in R :

$$P = I^2 R = \frac{\mathcal{E}^2}{R} = \frac{B^2 L^2}{R} v^2 = \frac{B^2 L^2}{R} v_0^2 e^{-2t/\tau_c}$$

$$U = \int_0^{\infty} P dt = \frac{M}{2} v_0^2 \quad (\text{all the initial kinetic energy})$$

Example 30-11, read it yourself

\Rightarrow Eddy current demonstration

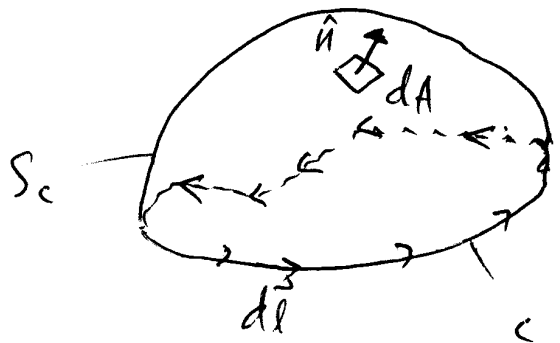
- Electro motive force produced by changing magnetic field

Faraday's Law

A change in the magnetic flux through a close loop with a designated direction induces a net emf along the loop, and the emf equals to the negative of the time rate of the flux change

$$\Phi_B = \iint_{S_c} \vec{B} \cdot d\vec{A}$$

With \hat{u} of $d\vec{A} = dA \hat{u}$ chosen to obey Right hand rule with the designated loop direction

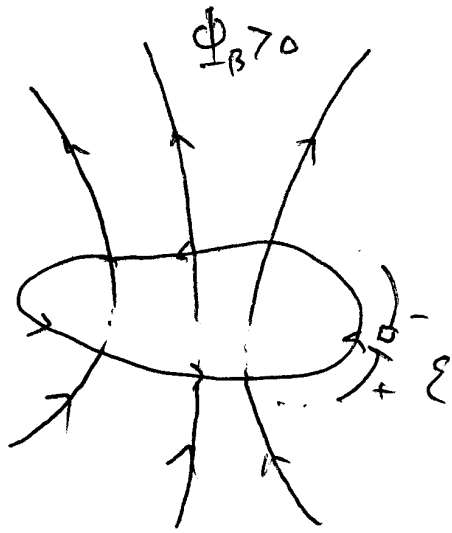


$$\mathcal{E} \text{ (along the loop direction)} = - \frac{d}{dt} \Phi_B = - \frac{d}{dt} \iint_{S_c} \vec{B} \cdot d\vec{A}$$

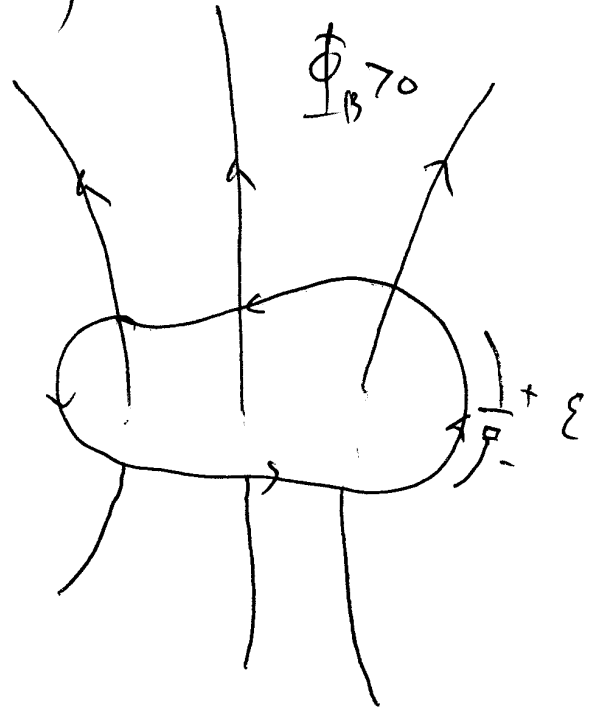
Since the induced emf would produce a current that, in turn, generate a magnetic flux to compensate the "loss" of the original magnetic flux

Lenz's Law: The direction of a magnetic induced emf is such as to oppose the cause of the induction.

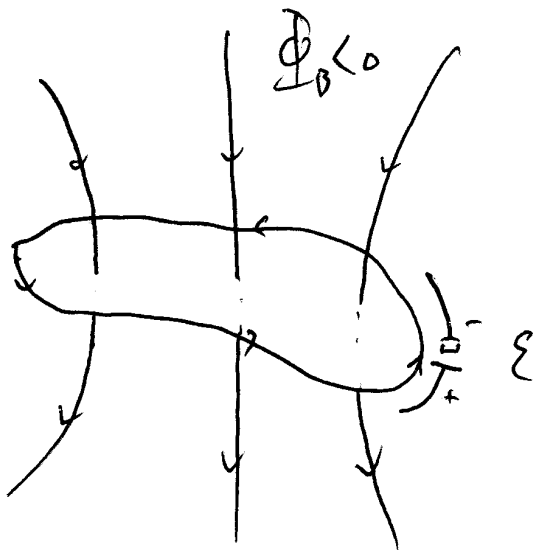
Direction of Induced EMF: (Lenz's Law)



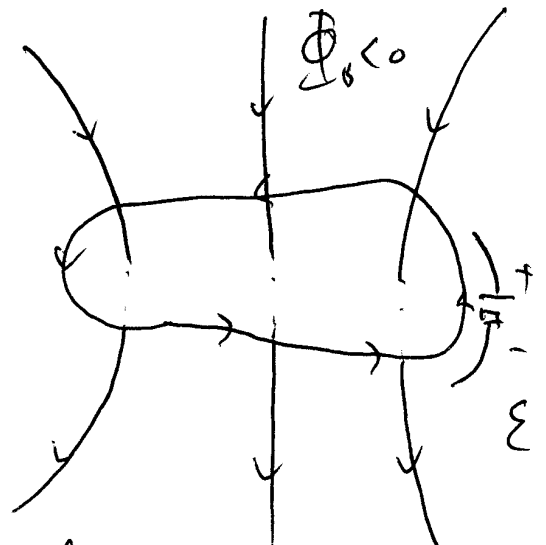
$$\frac{d\Phi_B}{dt} \uparrow, \quad \epsilon < 0$$



$$\frac{d\Phi_B}{dt} \downarrow, \quad \epsilon > 0$$



$$\frac{d\Phi_B}{dt} \uparrow \quad (\vec{B} \downarrow), \quad \epsilon < 0$$



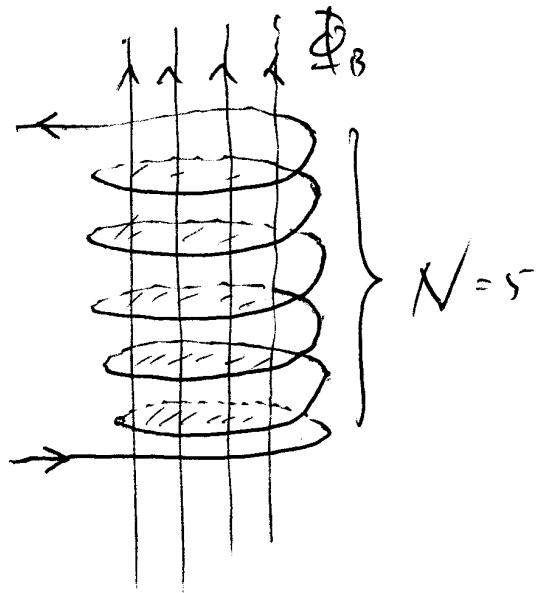
$$\frac{d\Phi_B}{dt} \downarrow \quad (\vec{B} \uparrow), \quad \epsilon > 0$$

Magnetic induction through a close loop with N identical turns

Along each turn,

$$\Delta \mathcal{E} = - \frac{d\Phi_B}{dt}$$

$$\mathcal{E} = N \cdot \Delta \mathcal{E} = - N \frac{d\Phi_B}{dt}$$



Example 30-1

Example 30-3

- Induced electric field by changing magnetic field.
What is the driving force F_u that leads to $\mathcal{E} = \int \frac{\vec{F}_u}{q} \cdot d\vec{l}$?
There is nothing else in space, can't be chemical force such as what is in a dry battery
Nothing is moving in a close loop (yet), can't be a magnetic force (between moving charges)

It is a circulating electric field \vec{E} :

$$\vec{F}_u = q \vec{E}$$

$$\mathcal{E} = \oint (\vec{F}_u \cdot d\vec{\ell}) / q = \oint \vec{E} \cdot d\vec{\ell}$$

$$\oint \vec{E} \cdot d\vec{\ell} = - \frac{d}{dt} \iint \vec{B} \cdot d\vec{A} \quad (\text{Faraday's law})$$

This "magnetically induced" electric field is non-conservative, or a transverse field such that

$$\oint \vec{E}_{\text{non}} \cdot d\vec{\ell} = \oint \vec{E}_T \cdot d\vec{\ell} \neq 0$$

$$\nabla \times \vec{E}_{\text{non}} = \nabla \times \vec{E}_T \neq 0$$

It is to be distinguished from the electro-static field \vec{E}_c produced by electric charges (longitudinal field)

$$\oint \vec{E}_c \cdot d\vec{\ell} = 0$$

Generally, $\vec{E} = \vec{E}_c + \vec{E}_N = \vec{E}_L + \vec{E}_T$ (Maxwell's equations)

Example 30-12

General Proof of Motion EMF being
equivalent to Faraday's law without
any induced transverse electric field \vec{E}_T

— EMF induced by relative motion of a
magnet and a conducting loop (wire)
can be equally well described by

$$\mathcal{E} = - \frac{d}{dt} \iint_{S_c} \vec{B} \cdot d\vec{A} \quad (\text{with care})$$

and

$$\mathcal{E} = \oint_c d\vec{l} \cdot (\vec{v} \times \vec{B})$$

In the absence of mobile charges, motion
emf is zero, amounting to nothing.

Yet time change in magnetic field \vec{B}
in the absence of any motion always produces
a transverse electric field \vec{E}_T so that

$$\oint_c \vec{E}_T \cdot d\vec{l} = - \frac{d}{dt} \iint_{S_c} \vec{B} \cdot d\vec{A}$$

The key is that the motional emf

$$\mathcal{E} = \oint d\vec{\ell} \cdot (\vec{v} \times \vec{B})$$

can be computed through

$$\oint_S \vec{B} \cdot d\vec{S} = 0$$

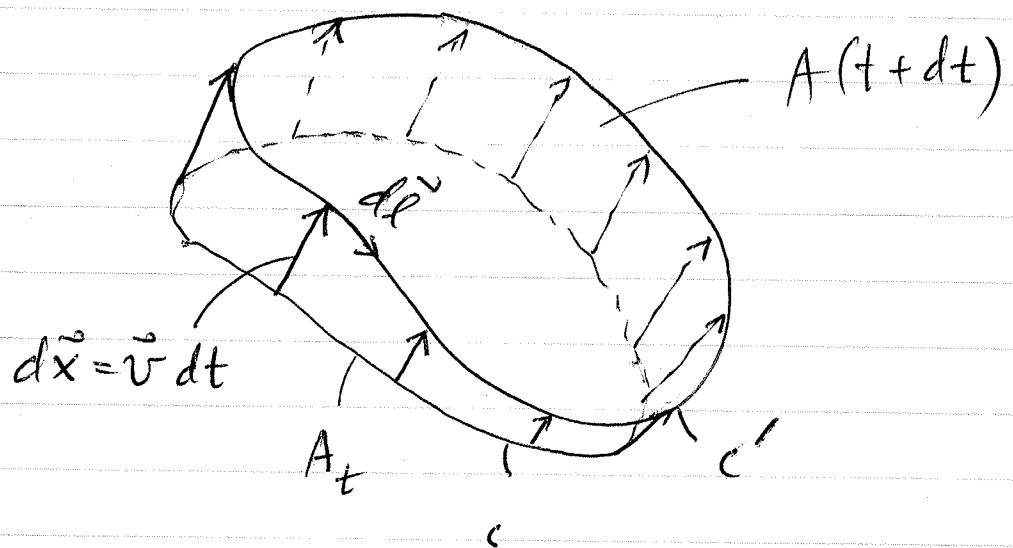
using a generalized Faraday's induction law

$$\mathcal{E}_{\text{total}} = - \frac{d}{dt} \iint_{S_i} \vec{B} \cdot d\vec{S}$$

$$= - \iint_{S_i \text{ (fixed)}} \left(\frac{\partial \vec{B}}{\partial t} \right) \cdot d\vec{S}$$

$$- \frac{d}{dt} \iint_{S_i \text{ (varying)}} \vec{B} \text{ (fixed)} \cdot d\vec{S}$$

Let c be a closed wire loop at an instant t ; at a later time, the same wire loop moves to a new position c' .



The magnetic flux leaving the box as shown is zero

$$\oiint_S \vec{B} \cdot d\vec{A} = 0 = \iint_{A(t)} \vec{B} \cdot d\vec{A} + \iint_{A(t+dt)} \vec{B} \cdot d\vec{A} + \oint_c \vec{B} \cdot (d\vec{l} \times d\vec{x})$$

$$\iint_{A(t)} \vec{B} \cdot d\vec{A} = - \iint_{S_c} \vec{B} \cdot d\vec{A} \Big|_{t+t} ; \quad \iint_{A(t+dt)} \vec{B} \cdot d\vec{A} = \iint_{S_c} \vec{B} \cdot d\vec{A} \Big|_{t+dt}$$

Thus

$$\iint_{A(t)} \vec{B} \cdot d\vec{A} + \iint_{A(t+dt)} \vec{B} \cdot d\vec{A} = dt \left(\frac{d}{dt} \iint_{S_c} \vec{B} \cdot d\vec{A} \right)$$

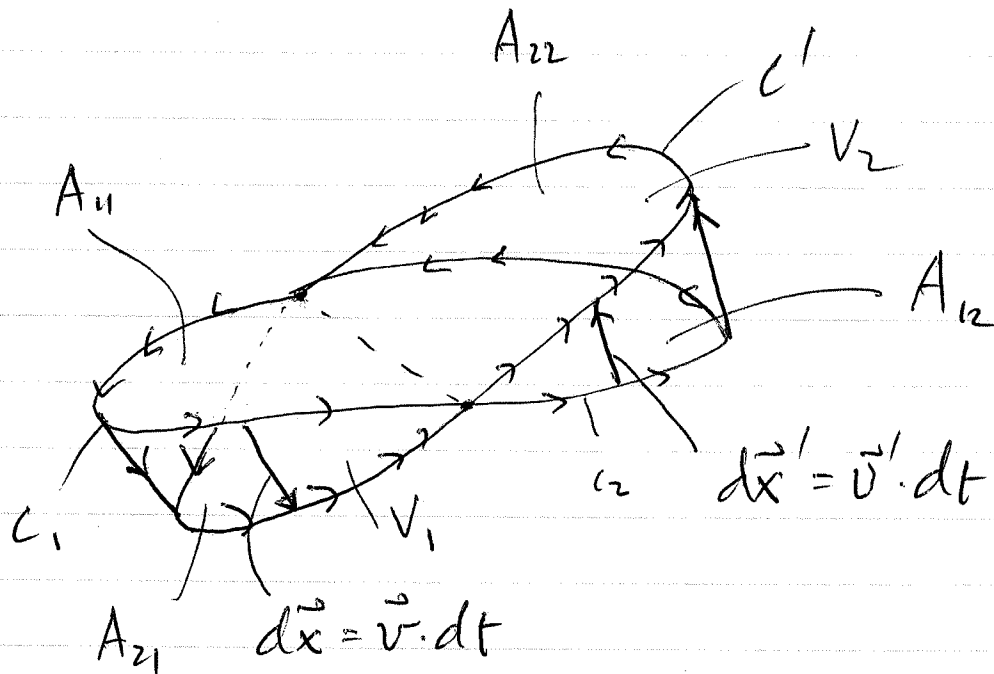
But

$$\begin{aligned} \oint_C \vec{B} \cdot (d\vec{\ell} \times d\vec{x}) &= dt \oint_C \vec{B} \cdot (d\vec{\ell} \times \vec{v}) \\ &= dt \oint_C (d\vec{\ell} \times \vec{v}) \cdot \vec{B} \\ &= dt \oint_C d\vec{\ell} \cdot (\vec{v} \times \vec{B}) \end{aligned}$$

$$\therefore \frac{d}{dt} \iint_{S_c} \vec{B} \cdot d\vec{A} + \oint_C d\vec{\ell} \cdot (\vec{v} \times \vec{B}) = 0$$

$$\therefore \oint_C d\vec{\ell} \cdot (\vec{v} \times \vec{B}) = - \frac{d}{dt} \iint_{S_c} \vec{B} \cdot d\vec{A}$$

It is possible that two "halves" of a close wire loop move in "opposite" directions as in form of rotation about two points on the loop. We then have the following situation:



Apply Gauss' law to each volume

$$\oint_{V_1} \vec{B} \cdot d\vec{s} = 0 = \iint_{A_{11}(t)} \vec{B} \cdot d\vec{s} - \iint_{A_{21}(t+dt)} \vec{B} \cdot d\vec{s} + \int_{c_1} \vec{B} \cdot (\vec{v} \times d\vec{\ell}) dt = 0 \quad \dots \textcircled{1}$$

$$\iint_{V_2} \vec{B} \cdot d\vec{s} = 0 = \iint_{A_{22}(t+dt)} \vec{B} \cdot d\vec{s} - \iint_{A_{12}(t)} \vec{B} \cdot d\vec{s}$$

$$+ \int_{C_2} \vec{B} \cdot (d\vec{\ell} \times \vec{v}) \cdot dt \quad \dots \quad (2)$$

- (1) + (2) :

$$0 = \iint_{S_{C'}(t+dt)} \vec{B} \cdot d\vec{s} - \iint_{S_C(t)} \vec{B} \cdot d\vec{s} + \oint_C \vec{B} \cdot (d\vec{\ell} \times \vec{v}) \cdot dt$$

$$\therefore dt \left(- \frac{d}{dt} \iint_{S_C} \vec{B} \cdot d\vec{s} \right) = \left(\oint_C d\vec{\ell} \cdot (\vec{v} \times \vec{B}) \right) \cdot dt$$

$$\therefore \oint_C d\vec{\ell} \cdot (\vec{v} \times \vec{B}) = - \frac{d}{dt} \iint_{S_C} \vec{B} \cdot d\vec{A}$$

The total induced emf

$$\mathcal{E} = \oint_{C_{\text{moving}}} d\vec{l} \cdot (\vec{E} + \vec{v} \times \vec{B})$$

$$= - \iint_{S_{C_{\text{fixed}}}} \frac{\partial \vec{B}}{\partial t} \cdot d\vec{A}$$

$$- \frac{d}{dt} \iint_{S_{C_{\text{moving}}}} \vec{B}(\text{fixed}) \cdot d\vec{A}$$

In special relativity, if for each line segment $d\vec{l}$ with a velocity \vec{v} relative to the static magnetic field \vec{B} , then in the frame of $d\vec{l}$, the line segment (static) ($x'-y'-z'$ frame) feels a static magnetic field $\vec{B}' \cong \vec{B}$, but also an electric field $\vec{E} = \vec{v} \times \vec{B}$. \vec{E} acts as the source of emf.

$$\mathcal{E} = \oint_C \vec{E} \cdot d\vec{l} = \oint_C d\vec{l} \cdot (\vec{v} \times \vec{B}) \quad \#$$

Another way to look at it is

$$\mathcal{E} = \oint d\vec{l} \cdot (\vec{E}_T + \vec{E}_{\text{relativity}})$$

$$\oint_C d\vec{l} \cdot \vec{E}_T = - \iint_{S_C} \left(\frac{\partial \vec{B}}{\partial t} \right) \cdot d\vec{s}$$

$$\vec{E}_{\text{relativity}} = \vec{v} \times \vec{B}$$

General Faraday's Induction Law

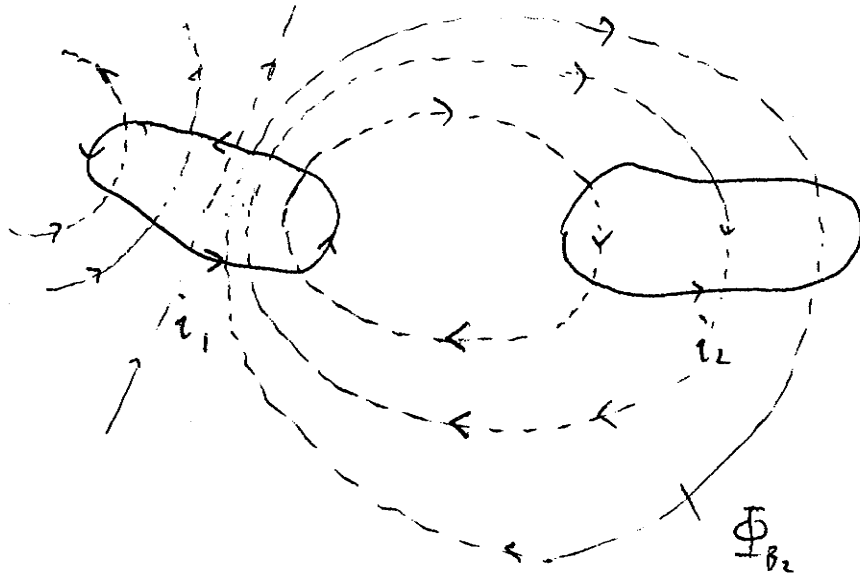
$$\begin{aligned}\mathcal{E} &= \oint_c d\vec{\ell} \cdot (\vec{E}_T + \vec{v} \times \vec{B}) = - \frac{d}{dt} \iint_{S_c} \vec{B} \cdot d\vec{A} \\ &= - \left(\frac{d}{dt} \iint_{S_c \text{ moving}} \vec{B}(\text{fixed}) \cdot d\vec{A} + \iint_{S_c \text{ fixed}} \frac{\partial \vec{B}}{\partial t} \cdot d\vec{A} \right)\end{aligned}$$

If there are N identical turns coils coincide with the loop c , then each turn produces the same \mathcal{E} that connects in series with the rest $N-1$ turns,

$$\begin{aligned}\mathcal{E}(N \text{ turns}) &= N \oint_c d\vec{\ell} \cdot (\vec{E}_T + \vec{v} \times \vec{B}) \\ &= - N \frac{d}{dt} \iint_{S_c} \vec{B} \cdot d\vec{A} \\ &= - \frac{d}{dt} (N \Phi_B)\end{aligned}$$

Chapt. 30

- Mutual Inductance and self inductance



A current in loop 1 produces a net magnetic flux through a second loop Φ_{B2} (proportional to i_1). A time change in i_1 causes Φ_{B2} to change accordingly, thus induces an emf in loop 2

$$\mathcal{E}_2 = - \frac{d\Phi_{B2}}{dt} = - M_{21} \frac{di_1}{dt}$$

M_{21} : mutual inductance. (S.I. unit: Henry, $1\text{H} = \text{W} \cdot \text{A}$)

Similarly, a time change in i_2 in loop 2 causes the magnetic flux Φ_{B1} (produced by i_2) to change, leading to an emf in loop 1

$$\mathcal{E}_1 = - \frac{d\Phi_{B1}}{dt} = - M_{12} \frac{di_2}{dt}$$

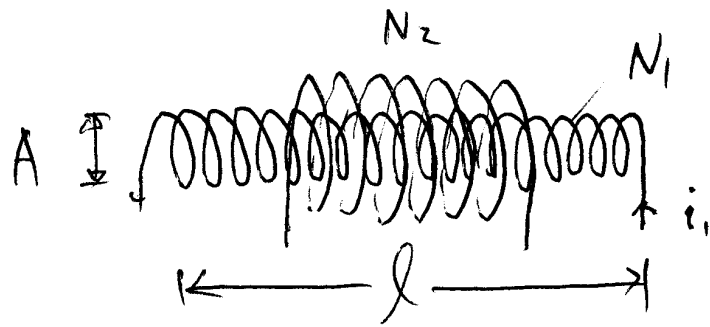
$$\boxed{M_{21} = M_{12}}$$

Example 31-1. Mutual inductance between two solenoids

$$\Phi_{B2} = A \cdot \mu_0 \left(\frac{N_1}{\ell} \right) \cdot i_1$$

$$\mathcal{E}_2 = - \frac{d\Phi_{B2}}{dt} \cdot N_2$$

$$= - \frac{\mu_0 \cdot A \cdot N_1 \cdot N_2}{\ell} \cdot \frac{di_1}{dt}$$



$$\therefore M_{12} = M_{21} = M = \frac{\mu_0 \cdot A \cdot N_1 \cdot N_2}{\ell} \quad (\text{function of geometry})$$

With $\ell = 0.5 \text{ m}$, $A = 10 \text{ cm}^2$, $N_1 = 1000$, $N_2 = 10$, $M = 20 \mu\text{H}$

With $i_2 = 2 \times 10^6 \text{ (A/s)} \cdot t$, $di_2/dt = 2 \times 10^6 \text{ A/s}$, $\mathcal{E}_1 = -50 \text{ V}$

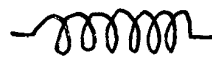
Self-inductance

A time change in the current in a close loop causes the self-induced magnetic flux through the loop to change, and in turn produces an emf in the loop

$$\mathcal{E} = - \frac{d\Phi_B}{dt} = -L \frac{di}{dt} \quad L: \text{self-inductance.}$$

If a close loop consists of N identical turns,

$$L = \frac{N\Phi_B}{i}$$

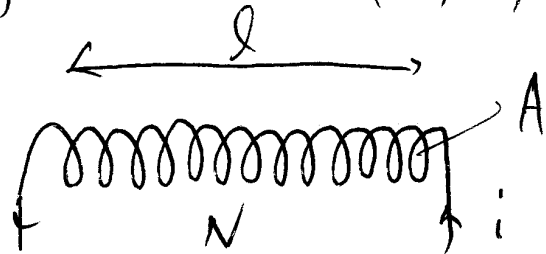


A circuit component specifically designed to have a well-defined self-inductive effect is an inductor with an inductance L .

Because of the self-induction, the current in a close loop cannot ~~be~~ change suddenly.

Example: self-inductance of a solenoid (l, A, N)

$$\Phi_B = \mu_0 \cdot \left(\frac{N}{l}\right) \cdot i \cdot N$$



$$L = \frac{\Phi_B}{i} = \frac{\mu_0 \cdot A \cdot N^2}{l}$$

with $l = 0.5 \text{ m}$, $A = 10 \text{ cm}^2$, $N = 1000$, $L = 2.5 \text{ mH}$.

• Magnetic energy storage in an inductor:

Increase an electric current from zero to a finite value I through an inductor, an extra work is done against the self-induced emf.

$$\frac{dW_{\text{extra}}}{dt} = i|\mathcal{E}| = i \cdot L \cdot \frac{di}{dt}$$

$$\therefore dW_{\text{extra}} = d\left(\frac{L}{2} i^2\right)$$

$$W_{\text{extra}} = \int_0^I dW_{\text{extra}} = \frac{L}{2} I^2$$

This work is not done to push charges through viscous medium, and must lead to magnetic energy increase that is stored somewhere.

$$U_m = \frac{L}{2} I^2 \quad (\text{in an inductor}).$$

Magnetic energy density u_m :

Since the only thing that has changed is the magnetic field inside the inductor (solenoid),

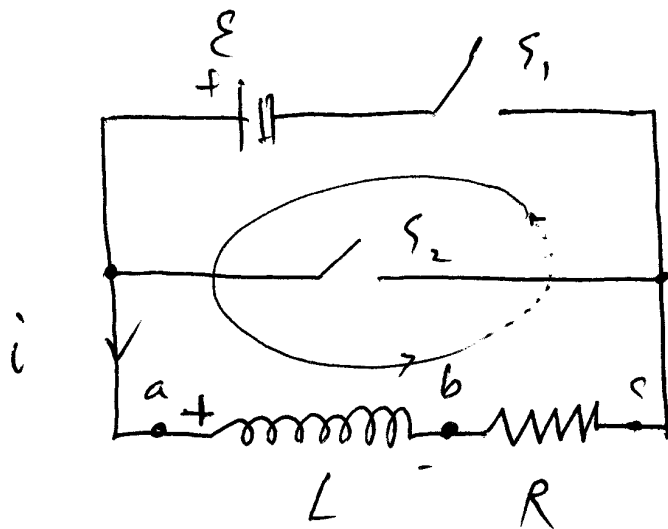
$$U_m = (Al) \cdot u_m = \frac{l}{2} \frac{\mu_0 A \cdot N^2}{l} I^2 = (Al) \cdot \frac{1}{2\mu_0} (\underbrace{\mu_0 N I}_B)^2$$

$$\therefore \boxed{u_m = \frac{1}{2\mu_0} B^2}$$

$$\boxed{u_E = \frac{\epsilon_0}{2} E^2}$$

• Resistor-Inductor (R-L) circuit

Initially, S_1 & S_2 are open. Close S_1 , a current starts to build up instead of jumping to \mathcal{E}/R , due to the self-induced \mathcal{E} that opposes the change.



By Kirchhoff rule, the electric potential drop along a-b-c-a:

$$\begin{cases} L \frac{di}{dt} + iR - \mathcal{E} = 0 \\ i(0) = 0 \end{cases}$$

$$\frac{di}{dt} = -\left(i - \frac{\mathcal{E}}{R}\right) \cdot \frac{R}{L}$$

$$i(t) = \left(1 - e^{-(R/L) \cdot t}\right) \cdot \frac{\mathcal{E}}{R} \quad i(t \rightarrow \infty) = \frac{\mathcal{E}}{R}$$

When S_2 is closed, $I_0 = \mathcal{E}/R$ cannot die out suddenly,

$$L \frac{di}{dt} + iR = 0 \quad i(t) = I_0 e^{-(R/L) \cdot t} \quad \tau_{RL} = \frac{L}{R}$$

Energy dissipation during "current die-down":

$$P(t) = i^2(t) \cdot R = I_0^2 R e^{-(2R/L) \cdot t}$$

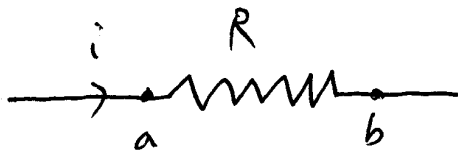
$$\Delta U = \int_0^{\infty} P(t) \cdot dt = I_0^2 R \cdot \int_0^{\infty} dt e^{-(2R/L) \cdot t} = \frac{L}{2} I_0^2$$

the stored energy inside an inductor (solenoid).

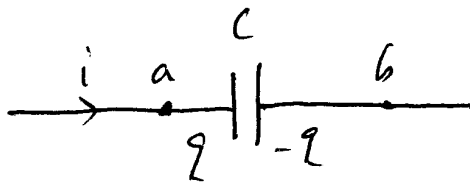
Example 31-7

Kirchhoff Rules for R, C, L:

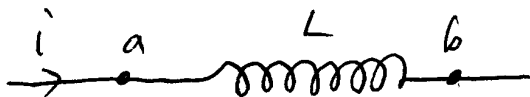
Let a current i flows into any one of these three components, and put q on the first plate of a capacitor that i runs into,



$$V_a - V_b = iR$$



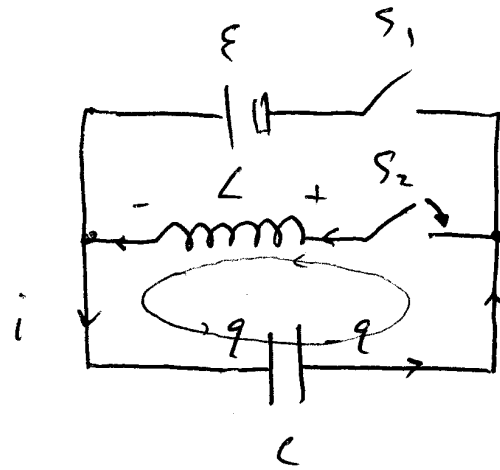
$$V_a - V_b = \frac{q}{C}, \quad i = \frac{dq}{dt}$$



$$V_a - V_b = L \frac{di}{dt}$$

• L-C Circuit and oscillation

Initially, open s_2 , close s_1 , until C is charged to $Q_0 = \epsilon C$. Then open s_1 . Now close s_2 , what happens?



$$\begin{cases} L \frac{di}{dt} + \frac{q}{C} = 0 \\ i = \frac{dq}{dt} \\ q(0) = Q_0, \quad i(0) = 0 \end{cases}$$

$$L \frac{d^2q}{dt^2} + \frac{q}{C} = 0 \quad \frac{d^2q}{dt^2} + \frac{q}{LC} = 0$$

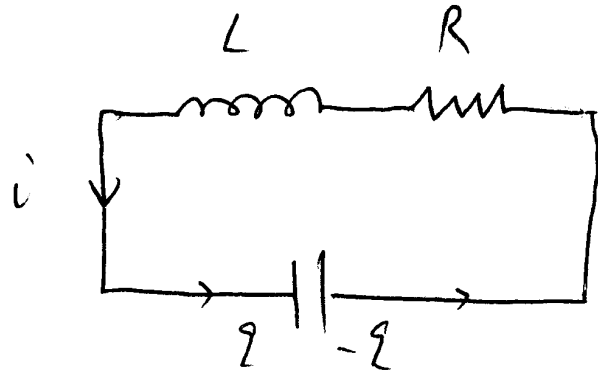
$$q(t) = A \cos \omega_0 t + B \sin \omega_0 t \quad \omega_0^2 = \frac{1}{LC}$$

Since $\frac{dq}{dt} = i \Big|_{t=0} = 0$, $B = 0$

$$\begin{cases} q(t) = Q_0 \cos\left(\frac{t}{\sqrt{LC}}\right) \\ i(t) = -\frac{Q_0}{\sqrt{LC}} \sin\left(\frac{t}{\sqrt{LC}}\right) \end{cases}$$

If the inductor and the rest of the circuit have a small resistance R ,

$$\begin{cases} L \frac{di}{dt} + iR + \frac{q}{C} = 0 \\ i(0) = 0 \\ q(0) = Q_0 \\ \frac{dq}{dt} = i \end{cases}$$



$$L \frac{d^2q}{dt^2} + R \frac{dq}{dt} + \frac{q}{C} = 0$$

Let $q(t) = A e^{-\lambda t}$, $L\lambda^2 - R\lambda + \frac{1}{C} = 0$ *

$$\lambda = \frac{R \pm \sqrt{R^2 - 4L/C}}{2L} = \frac{R}{2L} \pm i \sqrt{\frac{1}{LC} - \left(\frac{R}{2L}\right)^2}$$

Quality factor (Q).

$$Q \equiv \frac{\text{Energy stored}}{\text{Energy loss per oscillation cycle}} \cdot (2\pi) = \frac{\omega L}{R}$$

(1) Under-damped oscillation: $\frac{1}{LC} > \left(\frac{R}{2L}\right)^2$ or $\omega_0 > R/2L$

$$q(t) \cong Q_0 e^{-(R/2L)t} \cdot \cos\left[\left(\omega_0 \sqrt{1 - (R/2L\omega_0)^2}\right) \cdot t\right],$$

(2) Over-damped: $\frac{1}{LC} < \left(\frac{R}{2L}\right)^2$, $q(t) \cong Q_1 e^{-(R/L)t} + Q_2 e^{-t/RC}$ *

Chapt. 32

Maxwell's Equations & Electromagnetic waves

- Electromagnetic waves

Four Maxwell's Equations (really only two are needed) predict that \vec{E} and \vec{B} generate each other, lead to waves that propagate at the speed of light in vacuum, and carry energy here and there, and "activate" electric circuits at a speed only limited by the speed of light

$$\oiint \vec{E} \cdot d\vec{A} = \frac{Q_{in}}{\epsilon_0} \quad (1)$$

$$\oint_C \vec{E} \cdot d\vec{l} = -\frac{d}{dt} \iint_{S_C} \vec{B} \cdot d\vec{A} \quad (2)$$

$$\oiint \vec{B} \cdot d\vec{A} = 0 \quad (3)$$

$$\oint_C \vec{B} \cdot d\vec{l} = \mu_0 I + \kappa \mu_0 \epsilon_0 \frac{d}{dt} \iint_{S_C} \vec{E} \cdot d\vec{A} \quad (4)$$

In vacuum or media with no free (net) charge Q_{in} , and no current I ,

$$\oiint \vec{E} \cdot d\vec{A} = 0 \quad (1)'$$

$$\oint_C \vec{B} \cdot d\vec{l} = \kappa \mu_0 \epsilon_0 \frac{d}{dt} \iint_{S_C} \vec{E} \cdot d\vec{A} \quad (4)'$$

Transverse electric field \vec{E} and transverse magnetic field \vec{B} satisfy wave equations of the form

$$\begin{cases} \frac{\partial^2 \psi}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 \psi}{\partial t^2} \\ \psi(x, t) \end{cases}$$

and propagate at the same speed v .

$$\begin{aligned} \text{Let } \vec{E} &= \hat{j} E(x, t) \\ \vec{B} &= \hat{z} B(x, t) \end{aligned}$$

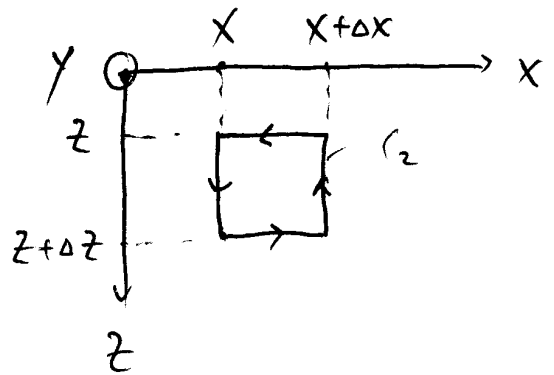
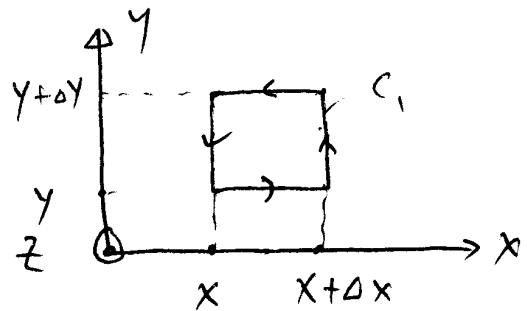
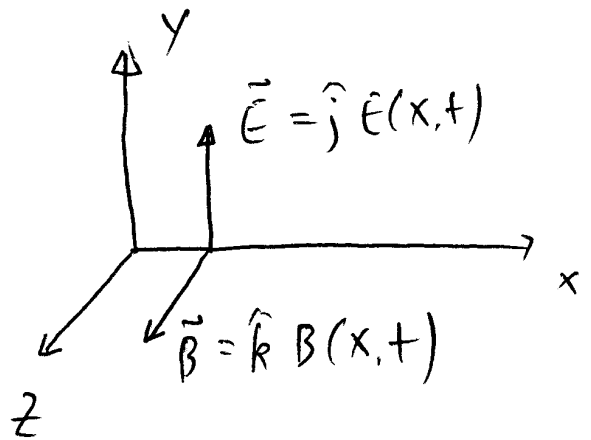
(plane-wave)

Integrate \vec{E} along C_1 :

$$\oint_{C_1} \vec{E} \cdot d\vec{l} = (E(x+\Delta x) - E(x)) \cdot \Delta y$$

$$- \iint_{S_{C_1}} \frac{\partial}{\partial t} \vec{B} \cdot d\vec{A} = - \frac{\partial B}{\partial t} \cdot \Delta x \cdot \Delta y$$

$$\boxed{\frac{\partial E}{\partial x} = - \frac{\partial B}{\partial t}}$$



Integrate \vec{B} along C_2 .

$$\oint_{C_2} \vec{B} \cdot d\vec{l} = -\left(B(x+\Delta x) - B(x)\right) \Delta z$$

$$\iint_{S_{C_2}} \kappa \mu_0 \epsilon_0 \frac{\partial}{\partial t} \vec{E} \cdot d\vec{A} = \kappa \mu_0 \epsilon_0 \frac{\partial E}{\partial t} \cdot \Delta x \Delta z$$

$$\therefore \boxed{-\frac{\partial B}{\partial x} = \kappa \mu_0 \epsilon_0 \frac{\partial E}{\partial t}}$$

Now

$$\frac{\partial^2 E}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial E}{\partial x} \right) = \frac{\partial}{\partial x} \left(-\frac{\partial B}{\partial t} \right) = \frac{\partial}{\partial t} \left(-\frac{\partial B}{\partial x} \right) = \kappa \mu_0 \epsilon_0 \frac{\partial^2 E}{\partial t^2}$$

$$\therefore \boxed{\frac{\partial^2 E}{\partial x^2} = \kappa \mu_0 \epsilon_0 \frac{\partial^2 E}{\partial t^2}}$$

$$v = \frac{1}{\sqrt{\kappa}} \frac{1}{\sqrt{\mu_0 \epsilon_0}} = \frac{c}{\sqrt{\kappa}}$$

$$\begin{aligned} \frac{\partial^2 B}{\partial x^2} &= (-) \frac{\partial}{\partial x} \left(-\frac{\partial B}{\partial x} \right) = -\kappa \mu_0 \epsilon_0 \frac{\partial}{\partial x} \left(\frac{\partial E}{\partial t} \right) = -\kappa \mu_0 \epsilon_0 \frac{\partial}{\partial t} \left(\frac{\partial E}{\partial x} \right) \\ &= \kappa \mu_0 \epsilon_0 \frac{\partial^2 B}{\partial t^2} \end{aligned}$$

$$\therefore \boxed{\frac{\partial^2 B}{\partial x^2} = \kappa \mu_0 \epsilon_0 \frac{\partial^2 B}{\partial t^2}}$$

$$v = \frac{c}{\sqrt{\kappa}}, \quad c^2 = \frac{1}{\mu_0 \epsilon_0}$$

- Energy density of an electromagnetic wave and energy flow vector (Poynting vector)

$$u = \frac{\kappa \epsilon_0}{2} E^2 + \frac{B^2}{2\mu_0}$$

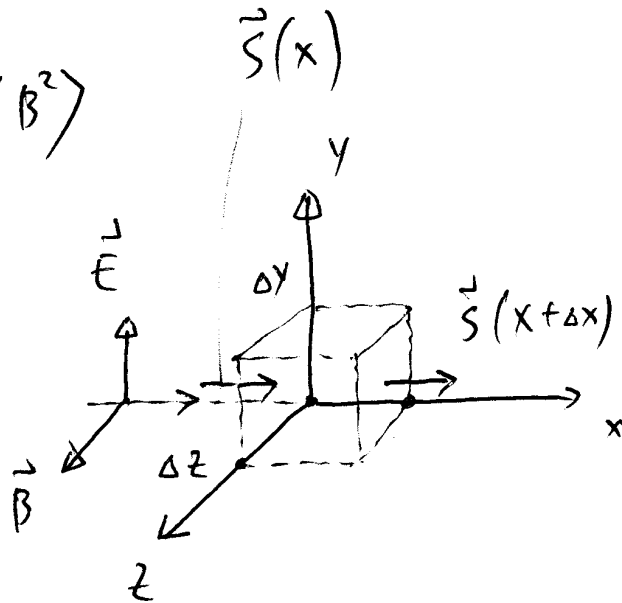
$$\langle u \rangle = \frac{\kappa \epsilon_0}{2} \langle E^2 \rangle + \frac{1}{2\mu_0} \langle B^2 \rangle$$

An electromagnetic wave with

$$\vec{E} = \hat{j} E(x,t)$$

$$\vec{B} = \hat{k} B(x,t)$$

propagates along x direction, carrying electromagnetic energy that enters on the left and exits on the right, causing the energy inside to change.



$$\frac{du}{dt} = \kappa \epsilon_0 E \frac{\partial E}{\partial t} + \frac{1}{\mu_0} B \frac{\partial B}{\partial t}$$

$$= -\frac{1}{\mu_0} E \frac{\partial B}{\partial x} - \frac{1}{\mu_0} B \frac{\partial E}{\partial x}$$

$$= -\frac{\partial}{\partial x} \left(\frac{1}{\mu_0} EB \right)$$

$$\frac{d}{dt} (\Delta x \Delta y \Delta z \cdot u) = (\Delta y \Delta z) \left(\frac{EB}{\mu_0} \Big|_x - \frac{EB}{\mu_0} \Big|_{x+\Delta x} \right)$$

or

$$\frac{d}{dt} (\Delta x \Delta y \Delta z) = (\Delta y \Delta z \hat{i}) \cdot \left(\frac{1}{\mu_0} \vec{E} \times \vec{B} \Big|_x - \frac{1}{\mu_0} \vec{E} \times \vec{B} \Big|_{x+\Delta x} \right)$$

Energy flow vector (Poynting vector)

$$\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B} = |\vec{S}| \cdot \hat{s}$$

$$\langle \vec{S} \rangle = \frac{1}{\mu_0} \langle \vec{E} \times \vec{B} \rangle = \langle |\vec{S}| \rangle \cdot \hat{s} = I \cdot \hat{s}$$

Magnitude of Poynting vector: intensity of an e.m. wave, i.e., energy flowing across a unit surface area per unit time

Direction of Poynting vector: direction of the energy flow.

• Harmonic, plane-wave electromagnetic waves

$$\vec{E} = \hat{j} E_0 \sin(\omega t - kx)$$

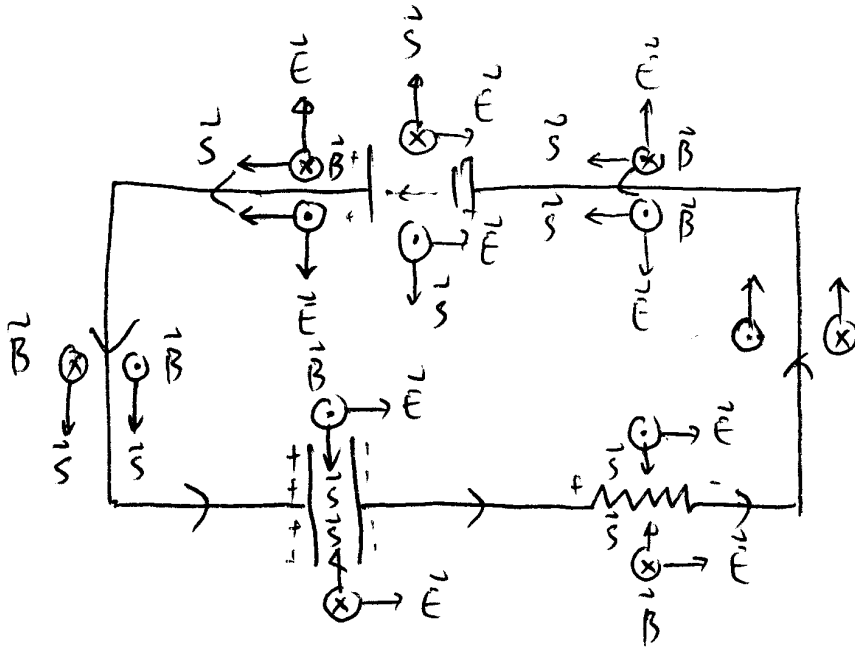
$$\vec{B} = \hat{k} B_0 \sin(\omega t - kx)$$

$k = \frac{2\pi}{\lambda}$ is the wavevector

λ is the wavelength

$\omega = \frac{2\pi}{T}$ is the angular freq.

- Energy flow in an electric circuit



Battery (emf) emits energy

R, C (devices charging) "absorb" energy

— End of the story —